

Australian Standard™

Low-voltage switchgear and controlgear

Part 4.2: Contactors and motor-starters—A.C. semiconductor motor controllers and starters



This Australian Standard was prepared by Committee EL-006, Industrial Switchgear and Controlgear. It was approved on behalf of the Council of Standards Australia on 22 July 2004.

This Standard was published on 23 September 2004.

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Australian Chamber of Commerce and Industry
Australian Electrical and Electronic Manufacturers Association
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This Standard was issued in draft form for comment as DR 04163.

Australian Standard™

Low-voltage switchgear and controlgear

Part 4.2: Contactors and motor-starters—A.C. semiconductor motor controllers and starters

Originated as AS 1202.5—1985.
Previous edition AS/NZS 3947.4.2:2000.
Revised and redesignated as AS 60947.4.2—2004.

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Published by Standards Australia International Ltd GPO Box 5420, Sydney, NSW 2001, Australia

ISBN 0 7337 6259 X

PREFACE

This Standard was prepared by the Standards Australia Committee EL-006, Industrial Switchgear and Controlgear to supersede AS 3947.4.2—1997.

The objective of this Standard is to provide characteristics, constructional and performance requirements and tests to verify performance for a.c. semiconductor motor controllers and starters for rated voltage up to 1000 V a.c.

This Standard is Part 4.2 of a series which, when complete, will consist of the following:

AS 60947	Low-voltage switchgear and controlgear
AS 60947.1*	Part 1: General rules
AS 60947.2*	Part 2: Circuit-breakers
AS 60947.3	Part 3: Switches, disconnectors, switch-disconnectors and fuse-combination units
AS 60947.3 Suppl	Part 3: Switches, disconnectors, switch-disconnectors and fuse-combination units, Supplement 1: Fuse-switch-disconnectors and switch-disconnectors for use with low-voltage aerial bundled cables
AS 60947.4.1*	Part 4.1: Contactors and motor-starters—Electromechanical contactors and motor-starters
AS 60947.4.2*	Part 4.2: Contactors and motor-starters—A.C. semiconductor motor controllers and starters (this Standard)
AS 60947.4.3	Part 4.3: Contactors and motor-starters—A.C. semiconductor controllers and contactors for non-motor loads
AS 60947.5.1*	Part 5.1: Control circuit devices and switching elements—Electromechanical control circuit devices
AS 60947.5.2*	Part 5.2: Control circuit devices and switching elements—Proximity switches
AS 60947.5.3	Part 5.3: Control circuit devices and switching elements—Requirements for proximity devices with defined behaviour under fault conditions
AS 60947.5.4*	Part 5.4: Control circuit devices and switching elements—Methods of assessing the performance of low-energy contacts—Special tests
AS 60947.5.5	Part 5.5: Control circuit devices and switching elements—Electrical emergency stop devices with mechanical latching function
AS 60947.5.6	Part 5.6: Control circuit devices and switching elements—D.C. interface for proximity sensors and switching amplifiers (NAMUR)
AS 60947.5.7*	Part 5.7: Control circuit devices and switching elements—Requirements for proximity devices with analogue output
AS 60947.6.1	Part 6.1: Multiple function equipment—Automatic transfer switching equipment
AS 60947.6.2*	Part 6.2: Multiple function equipment—Control and protective switching devices (or equipment) (CPS)
AS 60947.7.1*	Part 7.1: Ancillary equipment—Terminal blocks for copper conductors
AS 60947.7.2*	Part 7.2: Ancillary equipment—Protective conductor terminal blocks for copper conductors

AS 60947.7.3*	Part 7.3:	Ancillary equipment—Safety requirements for terminal blocks for the reception of cartridge fuse-links
AS 60947.8*	Part 8:	Control units for built-in thermal protection for rotating machines

It is the intention of the Committee to align the numbering of this series of Standards with that of the corresponding IEC 60947 series of Standards.

Standards from the list above that are marked with an asterisk (*) are, at the time of publication of this document, available as a part of the AS 60947 series of Standards.

Standards that are not so marked remain as AS/(NZS) 3947 series Standards. Following the next amendment or revision of the corresponding IEC Standard, each of these Standards remaining in the AS/(NZS) 3947 series will be revised and renumbered as a part of the AS 60947 series.

This Standard is identical with and has been reproduced from Consolidated Edition 2.1(2002) of IEC 60947-4-2, *Low-voltage switchgear and controlgear*, Part 4-2: *Contactors and motor-starters—AC semiconductor motor controllers and starters* which includes Edition 2.0 (1999) of IEC 60947-4-2, its Amendment 1 (2001) and its Corrigendum (2002-03).

This Standard covers low-voltage a.c. semiconductor motor controllers and starters, that have many capabilities and features beyond the simple starting and stopping of an induction motor, such as controlled starting and stopping, manoeuvring and controlled running.

The generic term, controller, is used in this Standard wherever the unique features of the power semiconductor switching elements are the most significant points of interest. The generic term, starter, is used wherever the consequences of operating the power semi-conductor switching elements, together with suitable overload protective means are the most significant points of interest. Specific designations (for example form 1, form HxB) are used wherever the unique features of various configurations comprise significant points of interest.

The provisions of the general rules dealt with in AS 60947.1 (hereinafter referred to as Part 1) are applicable to this standard, where specifically called for. Clauses and subclauses, tables, figures and appendices of the general rules thus applicable are identified by reference to Part 1, for example, 1.2.3 of Part 1, table 4 of Part 1, or annex A of Part 1.

This Standard differs from AS/NZS 3947.4.2:2000 in the following:

- (a) Includes requirements and tests for bypassed controllers.
- (b) Utilization categories have been revised.
- (c) Temperature rise requirements and tests have been expanded.
- (d) Ratio of power frequency recovery voltage to rated operational voltage for overload capability tests is now 1.05.
- (e) Requirements for making and breaking capacities for devices in the main circuit have been expanded.
- (f) Tests for performance under short-circuit conditions have been revised
- (g) Normative Annex I giving a modified test circuit for short-circuit testing and informative Annex J giving a flowchart for constructing bypassed semiconductor controllers tests have been added.

A reference to an International Standard identified in the Normative References Clause and the Bibliography by strikethrough (~~example~~) is replaced by a reference to the Australian or Australian/New Zealand Standard(s) listed immediately thereafter and identified by shading (~~example~~). Where the struck-through referenced document and the referenced Australian or Australian/New Zealand Standard are identical, this is indicated in parenthesis after the title of the latter.

As this Standard is reproduced from an International Standard, the following applies:

- (i) Its number does not appear on each page of text and its identity is shown only on the cover and title page.
- (ii) In the source text 'this standard' should read 'this Australian Standard'.
- (iii) A full point should be substituted for a comma when referring to a decimal marker.

The terms 'normative' and 'informative' have been used in this Standard to define the application of the annex to which they apply. A 'normative' annex is an integral part of a Standard, whereas an 'informative' annex is only for information and guidance.

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STANDARDS AUSTRALIA

Australian Standard
Low-voltage switchgear and controlgear
Part 4.2: Contactors and motor-starters—A.C. semiconductor motor
controllers and starters

1 Scope and object

This standard applies to controllers and starters, which may include a series mechanical switching device, intended to be connected to circuits, the rated voltage of which does not exceed 1 000 V a.c.

This standard characterizes controllers and starters for use with and without bypass means.

Controllers and starters dealt with in this standard are not normally designed to interrupt short-circuit currents. Therefore, suitable short-circuit protection (see 8.2.5) should form part of the installation, but not necessarily of the controller or starter.

In this context, this standard gives requirements for controllers and starters associated with separate short-circuit protective devices.

This standard does not apply to:

- continuous operation of a.c. motors at motor speeds other than the normal speed;
- semiconductor equipment, including semiconductor contactors (see 2.2.13 of Part 1) controlling non-motor loads;
- electronic a.c. power controllers covered by IEC 60146.

Contactors and control circuit devices used in controllers and starters should comply with the requirements of their relevant product standard. Where mechanical switching devices are used, they should meet the requirements of their own ~~IEC~~ **AS** product standard, and the additional requirements of this standard.

The object of this standard is to state as follows:

- the characteristics of controllers and starters and associated equipment;
- the conditions with which controllers and starters shall comply with reference to:
 - a) their operation and behaviour;
 - b) their dielectric properties;
 - c) the degrees of protection provided by their enclosures where applicable;
 - d) their construction;
- the tests intended for confirming that these conditions have been met, and the methods to be adopted for these tests;
- the information to be given with the equipment, or in the manufacturer's literature.

2 Normative references

References to International Standards that are struck through in this Clause are replaced by references to equivalent Australian or Australian/New Zealand Standards that are listed immediately thereafter and identified by shading. Any Australian or Australian/New Zealand Standard that is identical to the International Standard it replaces is appropriately identified.

The following normative documents contain provisions which, through reference in this text, constitute provisions of this part of ~~IEC 60947~~ AS 60947. For dated references, subsequent amendments to, or revisions of, any of these publications do not apply. However, parties to agreements based on this part of ~~IEC 60947~~ AS 60947 are encouraged to investigate the possibility of applying the most recent editions of the normative documents indicated below. For undated references, the latest edition of the normative document referred to applies. Members of IEC and ISO maintain registers of currently valid International Standards.

~~IEC 60034-1:1996, Rotating electrical machines — Part 1: Rating and performance¹⁾~~

AS 1359.101, *Rotating electrical machines—General requirements, Part 101: Rating and performance*

IEC 60050(161):1990, *International Electrotechnical Vocabulary (IEV) – Chapter 161: Electromagnetic compatibility*

IEC 60085:1984, *Thermal evaluation and classification of electrical insulation*

~~IEC 60269-1:1998, Low voltage fuses — Part 1: General requirements~~

AS/NZS 60269.1, *Low-voltage fuses, Part 1: General requirements* (identical to IEC 60269-1:1998)

IEC 60410:1973, *Sampling plans and procedures for inspection by attributes*

~~IEC 60439-1:1992, Low voltage switchgear and controlgear assemblies — Part 1: Type-tested and partially type-tested assemblies~~

AS/NZS 3439.1, *Low-voltage switchgear and controlgear assemblies, Part 1: Type-tested and partially type-tested assemblies*

IEC 60664 (all parts), *Insulation coordination for equipment within low-voltage systems*

~~IEC 60947-1:1999, Low voltage switchgear and controlgear — Part 1: General rules~~
Amendment 1 (2000)

AS/NZS 60947.1, *Low-voltage switchgear and controlgear, Part 1: General rules*

IEC/TR3 61000-2-1:1990, *Electromagnetic compatibility (EMC) – Part 2: Environment – Section 1: Description of the environment – Electromagnetic environment for low-frequency conducted disturbances and signalling in public power supply systems*

¹⁾—There exists a consolidated edition 10.2 (1999) that includes IEC 60034-1 (1996), its amendment 1 (1997) and amendment 2 (1999).

~~IEC 61000-3-2:1995, Electromagnetic compatibility (EMC) — Part 3: Limits — Section 2: Limits for harmonic current emissions (equipment input current ≤ 16 A per phase)²⁾~~

AS/NZS 61000.3.2, Electromagnetic compatibility (EMC), Part 3.2: Limits—Limits for harmonic current emissions (equipment input current less than or equal to 16 A per phase)

~~IEC 61000-4-2:1995, Electromagnetic compatibility (EMC) — Part 4: Testing and measurement techniques — Section 2: Electrostatic discharge immunity test — Basic EMC publication³⁾~~

AS/NZS 61000.4.2, Electromagnetic compatibility (EMC), Part 4.2: Testing and measurement techniques—Electrostatic discharge immunity test

~~IEC 61000-4-3:1995, Electromagnetic compatibility (EMC) — Part 4: Testing and measurement techniques — Section 3: Radiated, radio-frequency, electromagnetic field immunity test⁴⁾~~

AS/NZS 61000.4.3, Electromagnetic compatibility (EMC), Part 4.3: Testing and measurement techniques—Radiated, radio-frequency, electromagnetic field immunity test (identical with IEC 61000-4-3 consolidated Edition 1.1 (1998))

IEC 61000-4-4:1995, Electromagnetic compatibility (EMC) — Part 4: Testing and measurement techniques — Section 4: Electrical fast transient/burst immunity test — Basic EMC publication

~~IEC 61000-4-5:1995, Electromagnetic compatibility (EMC) — Part 4: Testing and measurement techniques — Section 5: Surge immunity test~~

AS/NZS 61000.4.5, Electromagnetic compatibility (EMC), Part 4.5: Testing and measurement techniques—Surge immunity test (identical to IEC 61000-4-5:1995)

~~IEC 61000-4-6:1996, Electromagnetic compatibility (EMC) — Part 4: Testing and measurement techniques — Section 6: Immunity to conducted disturbances, induced by radio-frequency fields~~

AS/NZS 61000.4.6, Electromagnetic compatibility (EMC), Part 4.6: Testing and measurement techniques—Immunity to conducted disturbances, induced by radio-frequency fields (identical to IEC 61000-4-6:1996)

IEC 61000-4-11:1994, Electromagnetic compatibility (EMC) — Part 4: Testing and measuring techniques — Section 11: Voltage dips, short interruptions and voltage variations immunity tests

~~CISPR 11:1997, Industrial, scientific and medical (ISM) radio-frequency equipment — Electromagnetic disturbance characteristics — Limits and methods of measurement⁵⁾~~

AS/NZS CISPR 11, Industrial, scientific and medical (ISM) radio-frequency equipment—Electromagnetic disturbance characteristics—Limits and method of measurement

~~CISPR 14-1:1993, Electromagnetic compatibility — Requirements for household appliances, electrical tools and similar apparatus — Part 1: Emission — Product family standard~~

AS/NZS CISPR 14.1, Electromagnetic compatibility—Requirements for household appliances, electric tools and similar apparatus, Part 1: Emission*

²⁾— There exists a consolidated edition 1.2 (1998) that includes IEC 61000-3-2 (1995), its amendment 1 (1997) and amendment 2 (1998).

³⁾— There exists a consolidated edition 1.1 (1999) that includes IEC 61000-4-2 (1995) and its amendment 1 (1998).

⁴⁾— There exists a consolidated edition 1.1 (1998) that includes IEC 61000-4-3 (1995) and its amendment 1 (1998).

⁵⁾— There exists a consolidated edition 3.1 (1999) that includes CISPR 11 (1997) and its amendment 1 (1999).

* Not yet published.

~~CISPR 14-2:1993, Electromagnetic compatibility — Requirements for household appliances, electrical tools and similar apparatus — Part 2: Immunity — Product family standard~~

AS/NZS CISPR 14.2, *Electromagnetic compatibility – Requirements for household appliances, electrical tools and similar apparatus, Part 2: Immunity—Product family standard*

3 Definitions

For the purposes of this standard, relevant definitions of clause 2 of Part 1 and the following additional definitions apply.

3.1 Definitions concerning a.c. semiconductor motor control devices

3.1.1 AC semiconductor motor controllers and starters (see figure 1)

3.1.1.1

a.c. semiconductor motor controller

semiconductor switching device (see 2.2.3 of Part 1) that provides the starting function for an a.c. motor and an OFF-state

NOTE Because dangerous levels of leakage currents (see 3.1.13) can exist in a semiconductor motor controller in the OFF-state, the load terminals should be considered to be live at all times.

3.1.1.1.1

semiconductor motor controller (form 1)

a.c. semiconductor motor controller, in which the starting function may comprise any starting method specified by the manufacturer, and that provides control functions which may include any combination of manoeuvring, controlled acceleration, running or controlled deceleration of an a.c. motor. A FULL-ON state may also be provided

3.1.1.1.2

semiconductor soft-start motor controller (form 2)

special form of a.c. semiconductor motor controller, in which the starting function is limited to a voltage and/or current ramp which may include controlled acceleration, and where the additional control function is limited to providing FULL-ON

3.1.1.1.3

semiconductor direct on line (DOL) motor controller (form 3)

special form of a.c. semiconductor motor controller, in which the starting function is limited to a full-voltage, unramped starting method only, and where the additional control function is limited to providing FULL-ON

3.1.1.2

semiconductor motor starter (form 1, form 2, form 3)

a.c. semiconductor motor controller with suitable overload protection, rated as a unit

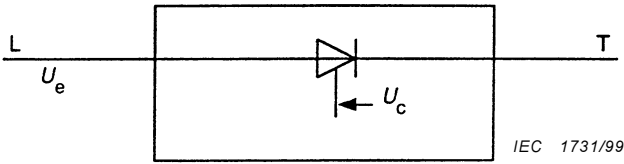
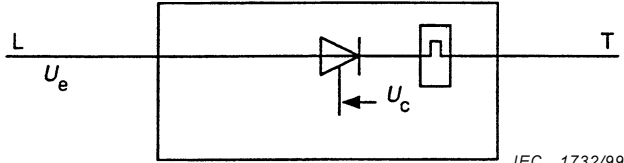
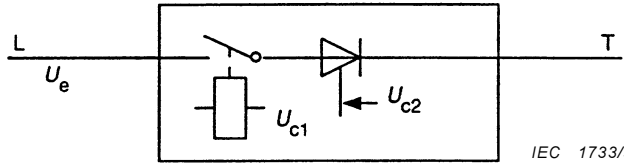
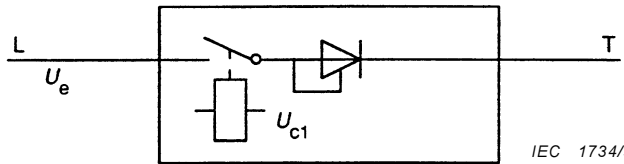
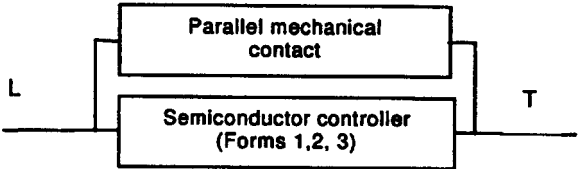
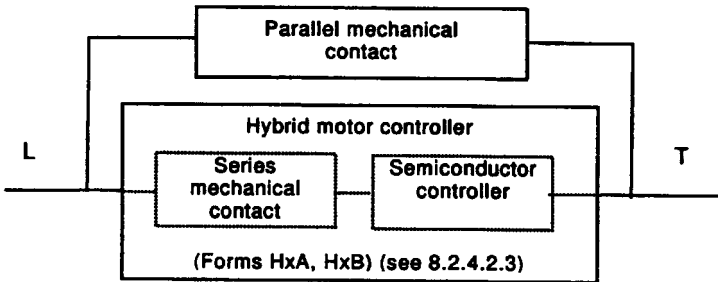
Device			
Semiconductor motor controller (forms 1, 2, 3)			
Semiconductor motor starter (forms 1, 2, 3)			
Hybrid motor controller HxA* where x = 1, 2 or 3			
Hybrid motor controller HxB**			
Bypassed controller			
Bypassed hybrid motor controller			
Hybrid motor starter	Form H1A or H1B with motor overload protection	Form H2A or H2B with motor overload protection	Form H3A or H3B with motor overload protection
* Two separate controls for the controller and the series mechanical switching device. ** One control only for the series mechanical switching device.			

Figure 1 – Semiconductor motor control devices

Table 1 – Functional possibilities of semiconductor motor control devices

Device	Form 1	Form 2	Form 3
Semiconductor motor controller	– OFF – Starting function – Manoeuvring – Controlled acceleration – Running – FULL ON – Controlled deceleration	– OFF state – Starting function – Controlled acceleration – FULL ON	Not available
Semiconductor DOL motor controller	Not available	Not available	– OFF state – Starting function – FULL ON
Semiconductor motor starter	Form 1 controller with motor overload protection	Form 2 controller with motor overload protection	Not available
Semiconductor DOL motor starter	Not available	Not available	Form 3 DOL motor controller with motor overload protection
Hybrid motor controller HxA* where x = 1, 2 or 3	H1A: – Open – OFF state – Starting function – Manoeuvring – Controlled acceleration – Running – Full ON – Controlled deceleration	H2A: – Open – OFF state – Starting function – Controlled acceleration – FULL ON	H3A: – Open – OFF state – Starting function – FULL ON
Hybrid motor controller HxB** where x = 1, 2 or 3	H1B: – Open – Starting function – Manoeuvring – Controlled acceleration – Running – FULL ON – Controlled deceleration	H2B: – Open – Starting function – Controlled acceleration – FULL ON	H3B: – Open – Starting function – FULL ON
Hybrid motor starter	Form H1A or H1B with motor overload protection	Form H2A or H2B with motor overload protection	Form H3A or H3B with motor overload protection
* Two separate controls for the controller and the series mechanical switching device. ** One control only for the series mechanical switching device.			

3.1.2 Hybrid motor controllers and starters (see figure 1)

3.1.2.1

hybrid motor controllers or starters, form HxA (where x = 1, 2 or 3)

form 1, 2 or 3 semiconductor motor controller or starter in series with a mechanical switching device, all rated as a unit. Separate control commands are provided for the series mechanical switching device and the semiconductor motor controller or starter. All the control functions appropriate to the form of motor controller or starter specified are provided, together with an OPEN position

3.1.2.2

hybrid motor controllers or starters, form HxB

form 1, 2 or 3 semiconductor motor controller or starter in series with a mechanical switching device, all rated as a unit. A single control command is provided for both the series mechanical switching device and the semiconductor motor controller or starter. All the control functions appropriate to the form of motor controller specified are provided, with the exception of an OFF state

3.1.2.3**OPEN position**

condition of a hybrid semiconductor motor controller or starter when the series mechanical switching device is in the OPEN position (see 2.4.21 of Part 1)

3.1.3**current-limit function**

ability of the controller to limit the motor current to a specified value. It does not include the ability to limit the instantaneous current under conditions of short circuit

3.1.4**manoeuvre**

any deliberate operation that causes current changes which must be characterized and controlled (for example jogging, braking)

NOTE 1 Starting is a mandatory manoeuvre that is recognized separately.

NOTE 2 Braking operations performed by the a.c. semiconductor motor controller or starter are considered to be a manoeuvre within the scope of this standard.

3.1.5**controlled acceleration**

control of motor performance while increasing motor speed by acting on the motor supply

3.1.6**controlled deceleration**

control of motor performance while decreasing motor speed by acting on the motor supply

3.1.7**controlled running**

control of motor performance by acting on the motor supply while the motor is running at normal speed (for example energy saving)

3.1.8**prospective locked rotor current, (I_{LRP})**

prospective current (see 2.5.5 of Part 1) that would flow when the rated voltage is applied to the motor with a locked rotor

3.1.9**ON-state**

the condition of a controller when the conduction current can flow through its main circuit

3.1.10**FULL-ON (state of controllers)**

the condition of a controller when the controlling functions are set to provide normal full voltage excitation to the load

3.1.11**minimum load current**

minimum operational current in the main circuit which is necessary for correct action of a controller in the ON-state

NOTE The minimum load current should be given as the r.m.s value.

3.1.12**OFF-state**

the condition of a controller when no control signal is applied, and no current exceeding the OFF-state leakage current flows through the main circuit

3.1.13**OFF-state leakage current (I_L)**

the current which flows through the main circuit of a controller in the OFF-state

3.1.14**operation (of a controller)**

transition from the ON-state to the OFF-state, or the reverse

3.1.15**operating cycle (of a controller)**

succession of operations from one state to the other and back to the first state

NOTE A succession of operations not forming an operating cycle is referred to as an operating series.

3.1.16**operating capability**

under prescribed conditions, the ability to perform a series of operating cycles without failure

3.1.17**overload current profile**

current-time coordinate specifying the requirement to accommodate overload currents for a period of time (see 5.3.5.1)

3.1.18**rating index**

rating information organized in a prescribed format, unifying rated operational current and the corresponding utilization category, overload current profile, and the duty cycle or OFF-time (see 6.1e))

3.1.19**tripping operation (of a controller or starter)**

operation to establish and maintain an OFF-state (or open position in the case of a form HxB controller or starter) initiated by a control signal

3.1.20**trip-free controller or starter**

controller or starter which establishes and sustains an OFF-state condition, which cannot be overridden in the presence of a trip condition

NOTE In the case of form HxB, the term "OFF-state condition" is replaced by the term "OPEN position".

3.1.21**phase loss sensitive thermal overload relay or release**

a multipole thermal overload relay or release which operates in case of overload and also in case of loss of phase in accordance with specified requirements

3.1.22**ON-time**

period of time during which the controller is on-load, for example as in figure F.1 of annex F

3.1.23**OFF-time**

the period of time during which the controller is off-load, for example as in figure F.1 of annex F

3.1.24**bypassed controller**

equipment wherein the main circuit contacts of a mechanical switching device are connected in parallel with the main circuit terminals of a semiconductor switching device, and wherein the operating means of the two switching devices are co-ordinated

3.2 EMC definitions

Various EMC definitions are given in IEC 60050, particularly chapter 161. Further explanations are given in IEC 61000-2-1. For convenience and to avoid confusion, some of the key definitions from IEC 60050(161) are reproduced here

3.2.1

electromagnetic compatibility EMC (abbreviation)

ability of an equipment or system to function satisfactorily in its electromagnetic environment without introducing intolerable electromagnetic disturbances to anything in that environment [IEV 161-01-07]

3.2.2

electromagnetic emission

phenomenon by which electromagnetic energy emanates from a source [IEV 161-01-08]

3.2.3

electromagnetic disturbance

any electromagnetic phenomenon which may degrade the performance of a device, equipment or system, or adversely affect living or inert matter [IEV 161-01-05]

NOTE An electromagnetic disturbance may be an electromagnetic noise, an unwanted signal, or a change in the propagation medium itself.

3.2.4

radio (frequency) disturbance

electromagnetic disturbance having components in the radio frequency range [IEV 161-01-13]

3.2.5

radio frequency interference, RFI (abbreviation)

degradation of the reception of a wanted signal caused by radio frequency disturbance [IEV 161-01-14]

NOTE The English words "interference" and "disturbance" are often used indiscriminately. The expression 'radio-frequency interference' is also commonly applied to a radio-frequency disturbance of an unwanted signal.

3.2.6

transient (adjective and noun)

pertaining to or designating a phenomenon or a quantity which varies between two consecutive steady states during a time interval short compared with the time-scale of interest [IEV 161-02-01]

3.2.7

burst (of pulses or oscillations)

sequence of a limited number of distinct pulses or an oscillation of limited duration [IEV 161-02-07]

3.2.8

voltage surge

transient voltage wave propagating along a line or a circuit and characterized by a rapid increase followed by a slower decrease of the voltage [IEV 161-08-11]

4 Classification

Subclause 5.2 gives all data which could be used as criteria for classification.

5 Characteristics of a.c. semiconductor motor controllers and starters

5.1 Summary of characteristics

The characteristics of controllers and starters shall be stated in the following terms, where such terms are applicable:

- type of equipment (5.2);
- rated and limiting values for main circuits (5.3);
- utilization category (5.4);
- control circuits (5.5);
- auxiliary circuits (5.6);
- types and characteristics of relays and releases (5.7);
- coordination with short-circuit protective devices (5.8);
- switching overvoltages (5.9).

5.2 Type of equipment

The following shall be stated:

5.2.1 Form of equipment

Forms of controllers and starters (see 3.1.1 and 3.1.2)

5.2.2 Number of poles

5.2.2.1 Number of main poles

5.2.2.2 Number of main poles where the operation is controlled by a semiconductor switching element

5.2.3 Kind of current

AC only.

5.2.4 Interrupting medium (air, vacuum, etc.)

Applicable only to mechanical switching devices of hybrid controllers and starters.

5.2.5 Operating conditions of the equipment

5.2.5.1 Method of operation

For example:

- symmetrically controlled controller (such as a semiconductor with fully controlled phases);
- non-symmetrically controlled controller (such as thyristors and diodes).

5.2.5.2 Method of control

For example:

- automatic (by pilot switch or sequence control);
- non-automatic (that is push-buttons);
- semi-automatic (that is partly automatic, partly non-automatic).

5.2.5.3 Method of connecting

For example (see figure 2):

- motor in delta, thyristors in series with a winding;
- motor in star, thyristors in delta;
- motor in delta, thyristors connected between winding and supply.

5.3 Rated and limiting values for main circuits

The rated and limiting values established for controllers and starters shall be stated in accordance with 5.3.1 to 5.3.6, but it may not be necessary to establish all applicable values by tests.

5.3.1 Rated voltages

A controller or starter is defined by the following rated voltages.

5.3.1.1 Rated operational voltage (U_e)

Subclause 4.3.1.1 of Part 1 applies.

5.3.1.2 Rated insulation voltage (U_i)

Subclause 4.3.1.2 of Part 1 applies.

5.3.1.3 Rated impulse withstand voltage (U_{imp})

Subclause 4.3.1.3 of Part 1 applies.

5.3.2 Currents

A controller or starter is defined by the following currents:

5.3.2.1 Conventional free air thermal current (I_{th})

Subclause 4.3.2.1 of Part 1 applies.

5.3.2.2 Conventional enclosed thermal current (I_{the})

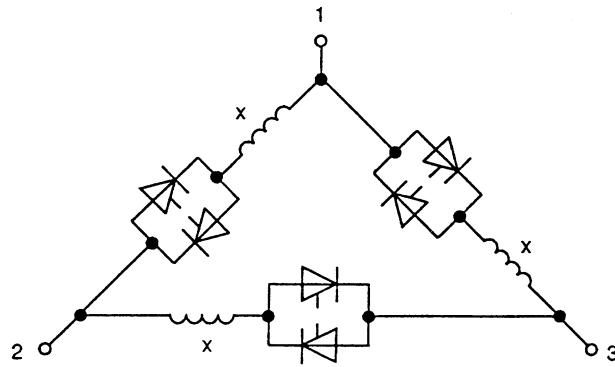
Subclause 4.3.2.2 of Part 1 applies.

5.3.2.3 Rated operational current (I_e)

The rated operational current, I_e , of controllers and starters is the normal operating current when the device is in the FULL-ON state, and takes into account the rated operational voltage (see 5.3.1.1), the rated frequency (see 5.3.3), the rated duty (see 5.3.4), the utilization category (see 5.4), the overload characteristics (see 5.3.5), and the type of protective enclosure, if any.

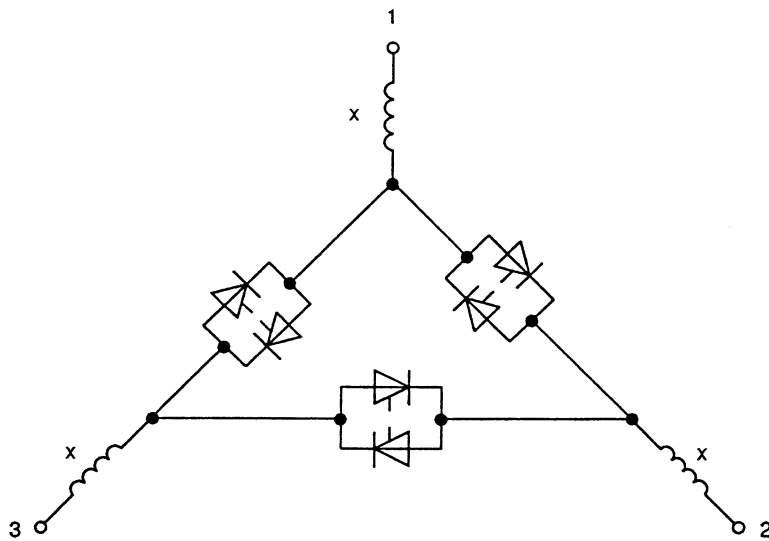
5.3.2.4 Rated uninterrupted current (I_u)

Subclause 4.3.2.4 of Part 1 applies.



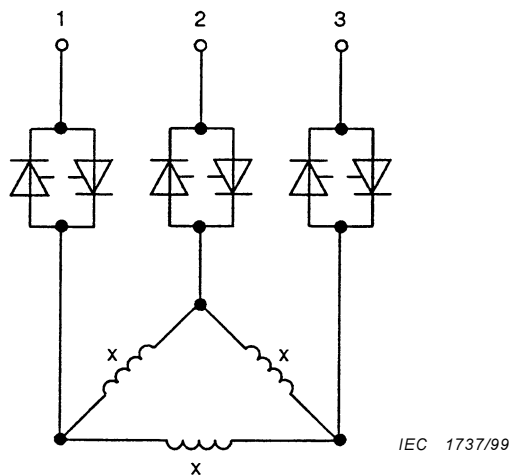
IEC 1735/99

Figure 2a – Motor in delta – Thyristors in series with a winding



IEC 1736/99

Figure 2b – Motor in star – Thyristors in delta



IEC 1737/99

Figure 2c – Motor in delta – Thyristors connected between winding and supply

Figure 2 – Connecting methods

5.3.3 Rated frequency

Subclause 4.3.3 of Part 1 applies.

5.3.4 Rated duty

The rated duties considered as normal are as follows:

5.3.4.1 8 h duty

A duty in which the controller or starter remains in the FULL-ON state while carrying a steady current long enough for the equipment to reach thermal equilibrium, but not for more than 8 h, without interruption.

5.3.4.2 Uninterrupted duty

A duty in which the controller or starter remains in the FULL-ON state while carrying a steady current without interruption for periods of more than 8 h (weeks, months, or even years).

5.3.4.3 Intermittent periodic duty or intermittent duty

Subclause 4.3.4.3 of Part 1 applies, except that the first paragraph is changed to read:

"A duty with on-load periods in which the controller or starter remains in the FULL-ON state, having a definite relation to off-load periods, both periods being too short to allow the equipment to reach thermal equilibrium."

5.3.4.4 Temporary duty

Duty in which the controller or starter remains in the FULL-ON state for periods of time insufficient to allow the equipment to reach thermal equilibrium, the current-carrying periods being separated by off-load periods of sufficient duration to restore equality of temperature with the cooling medium. Standard values of temporary duty are:

30 s, 1 min, 3 min, 10 min, 30 min, 60 min and 90 min.

5.3.4.5 Periodic duty

Subclause 4.3.4.5 of Part 1 applies.

5.3.4.6 Duty cycle values and symbols

For the purpose of this standard, the duty cycle is expressed by two symbols, F and S . These describe the duty, and also set the time that must be allowed for cooling.

F is the ratio of the on-load period to the total period expressed as a percentage.

The preferred values of F are:

$F = 1\%, 5\%, 15\%, 25\%, 40\%, 50\%, 60\%, 70\%, 80\%, 90\%, 99\%$

S is the number of operating cycles per hour. The preferred values of S are:

$S = 1, 2, 3, 4, 5, 6, 10, 20, 30, 40, 50, 60$ operating cycles per hour

NOTE Other values of F and/or S may be declared by the manufacturer.

5.3.5 Normal load and overload characteristics

Subclause 4.3.5 of Part 1 applies, with the following additions.

5.3.5.1 Overload current profile

The overload current profile gives the current-time coordinates for the controlled overload current. It is expressed by two symbols, X and T_x .

X denotes the overload current as a multiple of I_e selected from the array of values in table 4, and represents the maximum value of operating current due to starting, operating, or manoeuvring under overload conditions. $X = I_{LRP}/I_e$ when no current limit function is provided.

Deliberate overcurrents not exceeding 10 cycles (for example boost, kickstart, etc.), which may exceed the stated value of $X \times I_e$, are disregarded for the overload current profile.

T_x denotes the sum of duration times for the controlled overload currents during starting, operating, and manoeuvring. See table 4.

For a starter, T_x is the minimum operating time allowed by the tolerances of the overload relay for the current $X \times I_e$ in the cold state.

5.3.5.2 Operating capability

Operating capability represents the combined capabilities of:

- current commutation and current carrying in the ON-state; and
- establishing and sustaining the OFF-state (blocking),
at full voltage under normal load and overload conditions in accordance with utilization category, overload current profile and specified duty cycles.

Operating capability is characterized by:

- rated operational voltage (see 5.3.1.1);
- rated operational current (see 5.3.2.3);
- rated duty (see 5.3.4);
- overload current profile (see 5.3.5.1);
- utilization category (see 5.4).

Requirements are given in 8.2.4.1.

5.3.5.3 Starting, stopping and manoeuvring characteristics

Typical service conditions for controllers and starters controlling squirrel cage and hermetic refrigeration motors are as follows:

5.3.5.3.1 Starting characteristics of squirrel cage and hermetic refrigeration motors

- a) One direction of rotation with the inclusion of phase-control capability to provide any combination of controlled acceleration to normal speed, controlled deceleration to standstill, or an occasional manoeuvre without de-energizing the controller (AC-53a, AC-58a).
- b) One direction of rotation with the inclusion of phase-control capability to provide controlled acceleration to normal speed. Controllers and starters are rated for intermittent duty only (AC-53b, AC-58b); for example after starting, the motor may be connected into a circuit that bypasses the power semiconductors.

Two directions of rotation may be accomplished by reversing the connections to the controller or motor by means that are beyond the scope of this standard, but are covered by the relevant product standard for the selected means.

Two directions of rotation may also be accomplished by phase reversing within the controller or starter. The requirements for this operation will vary with each application. Therefore, this is subject to agreement between manufacturer and user.

Due to the control capability of controllers and starters, the current during starting, stopping, and any manoeuvre will differ from the conventional values of the prospective locked rotor current listed in table 6.

5.3.5.3.2 Starting characteristics of rheostatic rotor starters with controllers energizing the stator (AC-52a, AC-52b)

Starters can be used to provide reduced voltage excitation to the stator windings of a slip ring motor, and thereby reduce the number of switching steps required in the rotor circuit. For most applications, one or two starting steps are adequate depending upon load torque and inertia, and the severity of start required.

NOTE Starters and controllers covered by this standard are not intended for use in the rotor circuit and therefore, the rotor circuit must be controlled by traditional means. The relevant product standards for the rotor circuits of rheostatic rotor starters should apply.

5.3.6 Rated conditional short-circuit current

Subclause 4.3.6.4 of Part 1 applies.

5.4 Utilization category

Subclause 4.4 of Part 1 applies, with the following addition.

For controllers and starters, the utilization categories as given in table 2 are considered standard. Any other type of utilization shall be based on agreement between manufacturer and user, but information given in the manufacturer's catalogue or tender may constitute such an agreement.

Each utilization category (see table 2) is characterized by the values of the currents, voltages, power-factors and other data of tables 3, 4, 5 and 6, and by the test conditions specified in this standard.

The first digit of the utilization category identification designates a semiconductor motor controller or starter. The second digit designates a typical application. The a-suffix designates the capability of a controller to perform any of the functional possibilities listed in table 1. The b-suffix designates the capability of a controller where it is restricted to performing a transition from an OFF-state to a starting function of duration T_x , and immediately returning to the OFF-state to comprise a duty cycle in accordance with the requirements of 8.2.4.1.

5.4.1 Assignment of ratings based on the results of tests

A designated controller or starter with a rating for one utilization category which has been verified by testing can be assigned other ratings without testing, provided that:

- the rated operational current and voltage that are verified by testing shall not be less than the ratings that are to be assigned without testing;
- the utilization category and duty cycle requirements for the tested rating shall be equal to or more severe than the rating that is to be assigned without testing; the relative levels of severity are given in table 3;
- the overload current profile for the tested rating shall be equal to or more severe than the rating that is to be assigned without testing, in accordance with the relative levels of severity in table 3. Only values of X lower than the tested value of X may be assigned without testing.

Table 2 – Utilization categories

Utilization category	Typical application
AC-52a	Control of slip ring motor stators: 8 h duty with on-load currents for start, acceleration, run
AC-52b	Control of slip ring motor stators: intermittent duty
AC-53a	Control of squirrel cage motors: 8 h duty with on-load currents for start, acceleration, run
AC-53b	Control of squirrel cage motors: intermittent duty
AC-58a	Control of hermetic refrigerant compressor motors with automatic resetting of overload releases: 8 h duty with on-load currents for start, acceleration, run
AC-58b	Control of hermetic refrigerant compressor motors with automatic resetting of overload releases: intermittent duty
NOTE 1 The means of bypassing the semiconductor controller may be integral with the controller/starter or installed separately. NOTE 2 A hermetic refrigerant compressor motor is a combination consisting of a compressor and motor, both of which are enclosed in the same housing, with no external shaft or shaft seals, the motor operating in the refrigerant.	

Table 3 – Relative levels of severity

Severity level	Utilization category	Overload current profile ($X \cdot T_x$)	Time related requirement
Most severe	AC-52a AC-53a AC-58a	Highest value of $(X I_e)^2 \times T_x$ (note 1)	Highest value of $F \times S$ (note 2)
	AC-52b AC-53b AC-58b	Highest value of $(X I_e)^2 \times T_x$ (note 1)	Lowest value of OFF-time (note 3)
NOTE 1 When the highest value of $(X I_e)^2 \times T_x$ occurs at more than one value of $X I_e$, then the highest value of $X I_e$ shall apply. NOTE 2 When the highest value of $F \times S$ occurs at more than one value of S, then the highest value of S shall apply. NOTE 3 When the highest value of $(X I_e)^2 \times T_x$ occurs at more than one value of OFF-time, then the lowest value of OFF-time shall apply.			

5.5 Control circuits

Subclause 4.5.1 of Part 1 applies, with the following additions:

Refer to annex G for examples and illustrations. The characteristics of electronic control circuits are:

- kind of current;
- power consumption;
- rated frequency (or d.c.);
- rated control circuit voltage, U_c (nature: a.c./d.c.);
- rated control supply voltage, U_s (nature: a.c./d.c.);
- nature of control circuit devices (contacts, sensors).

NOTE A distinction is made between control circuit voltage, U_c , which is the controlling input signal, and control supply voltage, U_s , which is the voltage applied to energize the power supply terminals of the control circuit equipment and may be different from U_c , due to built-in transformers, rectifiers, resistors, etc.

5.6 Auxiliary circuits

Subclause 4.6 of Part 1 applies, with the following additions:

Electronic auxiliary circuits perform useful functions (for example monitoring, data acquisition, etc.) that are not necessarily relevant to the direct task of governing the intended performance characteristics.

Under normal conditions, auxiliary circuits are characterized in the same way as control circuits, and are subject to the same kinds of requirements. If the auxiliary functions include unusual performance features, the manufacturer should be consulted to define the critical characteristics.

5.7 Characteristics of relays and releases (overload relays)

Clause B.1 applies to relays and releases provided for motor protection.

5.8 Co-ordination with short-circuit protective devices (SCPD)

Controllers and starters are characterized by the type, ratings, and characteristics of the SCPD to be used to provide overcurrent discrimination between starter and SCPD, and adequate protection of controllers and starters against short-circuit currents.

Requirements are given in 8.2.5 of this standard and in 4.8 of Part 1.

5.9 Switching overvoltages

Under consideration.

6 Product information

6.1 Nature of information

The following information shall be given by the manufacturer:

Identification

- a) the manufacturer's name or trademark;
- b) type designation or serial number;
- c) number of this standard.

Characteristics, basic rated values and utilization

- d) rated operational voltages (see 5.3.1.1);
- e) rated operational currents, corresponding utilization category (5.4), overload current profile (5.3.5.1), and duty cycle (5.3.5.2) or OFF-time, comprising the rating index.

The prescribed format for AC-52a, AC-53a, AC-58a is shown by these examples:

100 A: AC-53a: 6-6: 60-1

This indicates 100 A current rating for general applications with squirrel cage motors. The device can accommodate 600 A for 6 s; 60 % on-load factor; one standard operating cycle per hour.

The prescribed format for AC-52b, AC-53b, AC-58b is shown by the example:

100 A: AC-53b: 3-52: 1 440

This indicates 100 A current rating for starting duty only. The device can accommodate 300 A for 52 s; the OFF-time must not be less than 1 440 s before any subsequent start may be initiated.

- f) value of the rated frequency/frequencies, for example 50 Hz or 50 Hz/60 Hz;
- g) indication of the rated duties as applicable (5.3.4.3);
- h) form designation (for example form 1, or form H1A, see table 1);

Safety and installation

- j) rated insulation voltage (5.3.1.2);
- k) rated impulse withstand voltage (5.3.1.3);
- l) IP code, in case of an enclosed equipment (8.1.11);
- m) pollution degree (7.1.3.2);
- n) rated conditional short-circuit current and type of coordination of the controller or starter, and the type, current rating and characteristics of the associated SCPD (see 5.8);
- p) switching overvoltage (see 5.9);

Control circuits

- q) rated control circuit voltage U_c , nature of current and rated frequency, and, if necessary, rated control supply voltage U_s , nature of current and rated frequency, and any other information (for example impedance matching requirements) necessary to ensure satisfactory operation of the control circuits (see annex G for examples of control circuit configurations);

Auxiliary circuits

- r) nature and ratings of auxiliary circuits (5.6);

Overload relays and releases

- s) characteristics according to 5.7;

EMC emission and immunity levels

- t) the equipment class and the specific requirements necessary to maintain compliance (see 8.3.2);
- u) the immunity levels attained and the specific requirements necessary to maintain compliance (see 8.3.3).

6.2 Marking

Subclause 5.2 of Part 1 applies to controllers and starters, with the following additions:

Data under d) to u) above shall be included on the nameplate, or on the equipment, or in the manufacturer's published literature.

Data under c) and l) above preferably shall be marked on the equipment.

6.3 Instructions for installation, operation, and maintenance

Subclause 5.3 of Part 1 applies, with the following addition:

Information shall be provided by the manufacturer to advise the user on the measures to be taken with regard to the equipment:

- in the event of a short circuit;
- in connection with the requirements for EMC (see 8.3.2).

7 Normal service, mounting and transport conditions

Clause 6 of Part 1 applies, with the following exceptions:

7.1 Normal service conditions

Subclause 6.1 of Part 1 applies, with the following exceptions:

7.1.1 Ambient air temperature

The ambient air temperature does not exceed +40 °C, and its average over a period of 24 h does not exceed +35 °C.

The lower limit of the ambient air temperature is 0 °C.

Ambient air temperature is that existing in the vicinity of the equipment if supplied without enclosure, or in the vicinity of the enclosure if supplied with an enclosure.

NOTE If the equipment is to be used at ambient air temperatures above +40 °C (for example within switchgear and control gear assemblies and in forges, boiler rooms, tropical countries) or below 0 °C (for example –25 °C, as required by IEC 60439-1 AS/NZS 3439.1 for outdoor installed low-voltage switchgear and controlgear assemblies) the manufacturer should be consulted. Information given in the manufacturer's catalogue may satisfy this requirement.

7.1.2 Altitude

The altitude of the site of installation does not exceed 1 000 meters.

NOTE For equipment to be used at higher altitudes, it is necessary to take into account the reduction of the dielectric strength, and the cooling effect of the air. Electrical equipment intended to operate in these conditions shall be designed or used in accordance with an agreement between manufacturer and user.

7.1.3 Atmospheric conditions

7.1.3.1 Humidity

Subclause 6.1.3.1 of Part 1 applies.

7.1.3.2 Degrees of pollution

Unless otherwise stated by the manufacturer, controllers and starters are intended for use in pollution degree 3 environmental conditions, as defined in 6.1.3.2 of Part 1. However, other pollution degrees may be considered to apply, depending upon the micro-environment.

7.1.4 Shock and vibrations

Subclause 6.1.4 of Part 1 applies.

7.2 Conditions during transport and storage

Subclause 6.2 of Part 1 applies.

7.3 Mounting

Subclause 6.3 of Part 1 applies, and for EMC considerations, see 8.3 and 9.3.5 below.

7.4 Electrical system disturbances and influences

For EMC considerations, see 8.3 and 9.3.5.