

BS ISO 16844-1:2013



BSI Standards Publication

Road vehicles — Tachograph systems

Part 1: Electrical connectors

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National foreword

This British Standard is the UK implementation of ISO 16844-1:2013.

The UK participation in its preparation was entrusted to Technical Committee AUE/16, Electrical and electronic equipment.

A list of organizations represented on this committee can be obtained on request to its secretary.

This publication does not purport to include all the necessary provisions of a contract. Users are responsible for its correct application.

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Partie 1: Connecteurs électriques*



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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

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Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 16844-1 was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 3, *Electrical and electronic equipment*.

This second edition cancels and replaces the first edition (ISO 16844-1:2001), which has been technically revised. It also incorporates the Technical Corrigendum ISO 16844-1:2001/Cor.1:2005.

ISO 16844 consists of the following parts, under the general title *Road vehicles — Tachograph systems*:

- *Part 1: Electrical connectors*
- *Part 2: Electrical interface with recording unit*
- *Part 3: Motion sensor interface*
- *Part 4: CAN interface*
- *Part 5: Secured CAN interface*
- *Part 6: Diagnostics*
- *Part 7: Parameters*