DEUTSCHE NORM September 2015

DIN EN 61158-4-19

ICS 35.100.20; 35.160

Ersatz für
DIN EN 61158-4-19:2013-01
Siehe Anwendungsbeginn

Industrielle Kommunikationsnetze – Feldbusse – Teil 4-19: Protokollspezifikation des Data Link Layer (Sicherungsschicht) – Typ 19-Elemente (IEC 61158-4-19:2014); Englische Fassung EN 61158-4-19:2014, nur auf CD-ROM

Industrial communication networks –
Fieldbus specifications –
Part 4-19: Data-link layer protocol specification – Type 19 elements
(IEC 61158-4-19:2014);
English version EN 61158-4-19:2014, only on CD-ROM

Réseaux de communication industriels –
Spécifications des bus de terrain –
Partie 4-19: Spécification du protocole de la couche liaison de données –
Éléments de type 19
(CEI 61158-4-19:2014);
Version anglaise EN 61158-4-19:2014, seulement en CD-ROM

Gesamtumfang 457 Seiten

DKE Deutsche Kommission Elektrotechnik Elektronik Informationstechnik in DIN und VDE

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Anwendungsbeginn

Anwendungsbeginn für die von CENELEC am 2014-09-19 angenommene Europäische Norm als DIN-Norm ist 2015-09-01.

Für DIN EN 61158-4-19:2013-01 besteht eine Übergangsfrist bis 2017-09-19.

Nationales Vorwort

Vorausgegangener Norm-Entwurf: E DIN EN 61158-400:2013-08.

Für dieses Dokument ist das nationale Arbeitsgremium K 956 „Feldbus“ der DKE Deutsche Kommission Elektrotechnik Elektronik Informationstechnik in DIN und VDE (www.dke.de) zuständig.

Die enthaltene IEC-Publikation wurde vom SC 65C „Industrial networks“ erarbeitet.

Das IEC-Komitee hat entschieden, dass der Inhalt dieser Publikation bis zu dem Datum (stability date) unverändert bleiben soll, das auf der IEC-Website unter „http://webstore.iec.ch“ zu dieser Publikation angegeben ist. Zu diesem Zeitpunkt wird entsprechend der Entscheidung des Komitees die Publikation
– bestätigt,
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– durch eine Folgeausgabe ersetzt oder
– geändert.

Für den Fall einer undatierten Verweisung im normativen Text (Verweisung auf eine Norm ohne Angabe des Ausgabedatums und ohne Hinweis auf eine Abschnittsnummer, eine Tabelle, ein Bild usw.) bezieht sich die Verweisung auf die jeweils neueste gültige Ausgabe der in Bezug genommenen Norm.

Für den Fall einer datierten Verweisung im normativen Text bezieht sich die Verweisung immer auf die in Bezug genommene Ausgabe der Norm.

Der Zusammenhang der zitierten Normen mit den entsprechenden Deutschen Normen ergibt sich, soweit ein Zusammenhang besteht, grundsätzlich über die Nummer der entsprechenden IEC-Publikation. Beispiel: IEC 60068 ist als EN 60068 als Europäische Norm durch CENELEC übernommen und als DIN EN 60068 ins Deutsche Normenwerk aufgenommen.

Das Präsidium des DIN hat mit Präsidialbeschluss 1/2004 festgelegt, dass DIN-Normen, deren Inhalt sich auf internationale Arbeitsergebnisse der Informationsverarbeitung gründet, unter bestimmten Bedingungen allein in englischer Sprache veröffentlicht werden dürfen. Diese Bedingungen sind für die vorliegende Norm erfüllt.

Da sich die Benutzer der vorliegenden Norm der englischen Sprache als Fachsprache bedienen, wird die Englische Fassung der EN 61158-4-19 veröffentlicht. Zu deren Abschnitt 1, der den Anwendungsbereich festlegt, und Abschnitt 3, der die Begriffe festlegt, wurde eine Übersetzung angefertigt und als Nationaler Anhang NA der vorliegenden Norm hinzugefügt. Für viele der verwendeten Begriffe existieren keine gebräuchlichen deutschen Benennungen, da sich die deutschen Anwender in der Regel ebenfalls der englischen Benennungen bedienen. Diese Norm steht nicht in unmittelbarem Zusammenhang mit Rechtsvorschriften und ist nicht als Sicherheitsnorm anzusehen.

Einführung

Ein Feldbus ist ein digitaler serieller Datenbus für die Kommunikation zwischen Geräten der industriellen Automatisierungstechnik wie beispielsweise Messeinrichtungen, Stellgliedern, Reglern und speicherprogrammierbaren Steuerungen. Die Normen der Reihe DIN EN 61158 legen eine Anzahl von Feldbus-Protokolltypen fest. Die Reihe DIN EN 61158-4 legt das Protokoll des Data Link Layer für die einzelnen Typen fest.

Änderungen

Gegenüber DIN EN 61158-4-19:2013-01 wurden folgende Änderungen vorgenommen:

a) Verbindungen nach dem Procedure-Consumer-Modell hinzugefügt;

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b) Zeitstempelung von Nachrichten hinzugefügt;

c) neue Fähigkeiten zum Umschalten während des Betriebs zur Aufnahme von Redundanz und zur Fehlerbehandlung hinzugefügt;

d) redaktionelle Überarbeitung.

Frühere Ausgaben

DIN V 19245-1: 1988-01
DIN 19245-1: 1991-04
DIN 19245-2: 1991-04
DIN EN 50170/1: 1997-07
DIN EN 50170/2: 1997-07
DIN EN 50170/3: 1997-07
DIN EN 50254: 1999-07
DIN EN 50170/A2: 2000-08
DIN EN 50170/A1: 2002-11
DIN EN 50170/A3: 2002-11
DIN EN 61158-4: 2005-05
DIN EN 61158-4-19: 2008-09, 2013-01

Nationaler Anhang NA
(informativ)

1 Anwendungsbereich[N1)]

1.1 Allgemeines

Der Data Link-Layer stellt grundlegende zeitkritische Kommunikation für den Datentransfer zwischen Geräten in einer Automatisierungsumgebung bereit.

Dieses Protokoll stellt Kommunikationsmöglichkeiten für alle teilnehmenden Data Link-Einheiten bereit

a) in einem synchron gestarteten, zyklischen Ablauf gemäß eines vordefinierten Ablaufplans, und

b) in einer zyklischen oder azyklischen asynchronen Weise, wie für jede derartige Data Link-Einheit im jeweiligen Zyklus gefordert.

Demnach kann dieses Protokoll als eines charakterisiert werden, welches zyklischen und azyklischen asynchronen Zugriff bereitstellt, aber mit einem synchronen Neustart jedes Zyklus.

1.2 Spezifikationen

Diese Norm legt Folgendes fest:

a) Prozeduren für zeitgerechten Datentransfer und Informationssteuerung von einer Data Link-Benutzereinheit zu einer gleichartigen Benutzereinheit sowie zwischen der Data Link-Einheit, welche den verteilten Data Link-Dienst-Anbieter bildet;

b) die Struktur der Feldbus-DLPDUs, welche verwendet werden für den Transfer von Daten und Informationssteuerung durch das Protokoll dieser Norm und ihre Darstellung als Physical Layer.

N1) Die Nummerierung aus IEC 61158-4-19 wurde beibehalten.

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1.3 Prozeduren

Die Prozeduren sind definiert in Form von

a) den Interaktionen zwischen gleichartigen DL-Einheiten (DLEs) durch den Austausch der Feldbus-DLPDUs;

b) den Interaktionen zwischen einem DL-Dienst-(DLS-)Anbieter und einem DLS-Benutzer im selben System durch den Austausch von DLS-Primitiven;

c) den Interaktionen zwischen einem DLS-Anbieter und einem Ph-Dienst-Anbieter im selben System durch den Austausch von Ph-Dienstprimitiven.

1.4 Anwendbarkeit

Diese Prozeduren sind auf Instanzen der Kommunikation zwischen Systemen anwendbar, welche die zeitkritischen Kommunikationsdienste innerhalb des Data Link Layer des OSI oder des Feldbusreferenzmodells unterstützen und die Fähigkeit erfordern, in einer offenen Systemverbundumgebung zu verbinden.

Profile stellen ein einfaches Multiattribut-Hilfsmittel zur Zusammenfassung der Implementierungsfähigkeiten bereit und unterstützen dadurch die Anwendbarkeit für unterschiedliche zeitkritische Kommunikationsanforderungen.

1.5 Konformität

Diese Norm legt auch Konformitätsanforderungen für Systeme fest, die diese Prozeduren implementieren. Sie enthält jedoch keine Prüfungen, um die Konformität mit diesen Anforderungen nachzuweisen.

3.2 Zusätzliche Begriffe für Typ 19

Für die Anwendung dieses Dokuments gelten die folgenden Begriffe.

3.2.1
Rundsendung
(en: broadcast)
Übertragung an alle Geräte in einem Netzwerk ohne Bestätigung durch die Empfänger

3.2.2
Kommunikationszyklus
(en: communication cycle)
festgelegte Zeitdauer zwischen zwei Master-Synchronisationstelegrammen, in der Echtzeit-Telegramme über den RT-Kanal und Nicht-Echtzeit-Telegramme über den IP-Kanal übertragen werden

3.2.3
Steuereinheit
(en: control unit)
Steuergerät (z. B. eine SPS nach der Spezifikation in der Normenreihe IEC 61131)

3.2.4
Steuerwort
(en: control word)
zwei aufeinanderfolgende Oktette im Master-Datentelegramm, die Befehle für das adressierte Gerät enthalten

3.2.5
Querkommunikation
(en: cross communication)
direkter Multicast-Datentransfer zwischen Geräten

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3.2.6
Zykluszeit
(en: cycle time)
Dauer eines Kommunikationszyklus

3.2.7
zyklische Kommunikation
(en: cyclic communication)
periodischer Austausch von Telegrammen

3.2.8
zyklische Daten
(en: cyclic data)
Teil eines Telegramms, dessen Bedeutung sich während einer zyklischen Operation des Netzwerks nicht ändert

3.2.9
zyklischer Betrieb
(en: cyclic operation)
Betrieb, bei dem die Geräte im Kommunikationsnetzwerk in feststehenden, konstanten Zeitintervallen nacheinander adressiert und abgefragt werden

3.2.10
Gerät
(en: device)
Slave im Kommunikationsnetzwerk (z. B. ein Antriebssystem nach der Definition in der Normenreihe IEC 61800, E/A-Stationen nach der Definition in der Normenreihe IEC 61131)

3.2.11
Feld für Geräteadresse
(en: device address field)
Adressfeld (acht Bits), das die Adresse des Gerätes enthält

3.2.12
Gerätesteuerung
(en: device control)
vier aufeinanderfolgende Oktette im Master-Datentelegramm, die Befehle für jedes Gerät enthalten

3.2.13
Gerätestatus
(en: device status)
vier aufeinanderfolgende Oktette im Bestätigungstelegramm, die Statusinformationen für jedes Gerät enthalten

3.2.14
DLE-Stationskennung
(en: DLE station identifier)
einer DLE zugewiesene Netzwerkadresse

3.2.15
Slot der DLE-Station
(en: DLE station slot)
Einheit (Granularität von eins) positionsabhängiger Zuordnung (für ein zyklisches Datenfeld), von der eine DLE eine oder mehrere belegen kann, beschrieben durch den Bereich beginnend bei der DLE-Stationskennung mit einer Länge, die der konfigurierten Anzahl von belegten Slots entspricht

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3.2.16
Element
(en: element)
Teil von IDNs – jede IDN weist 7 Elemente auf, wobei jedes Element eine spezifische Bedeutung hat (z. B. Nummer, Name, Daten)

3.2.17
EtherTyp
(en: EtherType)
Teil des Typ 19-spezifischen Telegramm-Headers

3.2.18
Weiterleitung
(en: forwarding)
Modus, in dem ein Gerät ein empfangenes Telegramm entweder verändert oder unverändert an den anderen Port weiterleitet

3.2.19
Identifikationsnummer
IDN
(en: identification number; IDN)
Kennzeichnung von Betriebsdaten, unter der ein Datenblock mit seinem Attribut, seinem Namen, seiner Einheit, seinen minimalen und maximalen Eingabewerten und den Daten aufbewahrt wird

3.2.20
Linie; Linienstruktur
(en: line; line structure)
Netzwerktopologie, bei der das Übertragungsmedium von Station zu Station in Form einer Linie geleitet wird; die Information wird in einer Richtung vom Master zum letzten Slave der Linie übertragen und strömt anschließend in umgekehrter Reihenfolge über alle Slaves zum Master zurück (CP16/3)

3.2.21
Schleifenschaltung
(en: loopback)
Modus, in dem ein Gerät ein empfangenes Telegramm entweder verändert oder unverändert an denselben und an den anderen Port weiterleitet

3.2.22
Master
(en: master)
Knoten, der den anderen Knoten (d. h. Slaves) das Recht zur Übertragung zuweist

3.2.23
Master-Datentelegramm
MDT
(en: master data telegram; MDT)
Telegramm, in das der Master seine Daten einfügt

3.2.24
Master-DLE
(en: master DLE)
DLE, welche die Funktionen eines Netzwerk-Masters ausführt

3.2.25
Master-Synchronisationstelegramm
MST
(en: master synchronization telegram; MST)
Telegramm oder Teil eines Telegramms, in das/den der Master ein Zeitsynchronisationssignal einfügt

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3.2.26
MDT0-Telegramm
(en: MDT0 telegram)
Telegramm, mit dem der Master seine Synchronisationsdaten sowie alle seine Echtzeitdaten oder Teile davon an die Slaves überträgt

3.2.27
Teilnehmer
(en: participant)
Knoten

3.2.28
Physical Layer
(en: physical layer)
erste Schicht des ISO-OSI-Referenzmodells

3.2.29
Protokoll
(en: protocol)
Vereinbarung über die Datenformate, Zeitabfolgen und Fehlerkorrektur für den Datenaustausch von Kommunikationssystemen

3.2.30
Echtzeitdaten
(en: real-time data)
Teil des Telegramms, dessen Bedeutung sich während einer zyklischen Operation der Schnittstelle nicht ändert

3.2.31
RT-Kanal
(en: RT channel)
festgelegter Zeitschlitz innerhalb des Kommunikationszyklus, in dem die CPF16-Echtzeittelegramme weitergeleitet werden

3.2.32
Dienstkanal
SVC
(en: service Channel; SVC)
Nicht-Echtzeit-Übertragung von Informationen über den RT-Kanal auf Anforderung des Masters hin

3.2.33
Slave
(en: slave)
Knoten, dem das Recht zur Übertragung durch den Master zugewiesen wird

3.2.34
Slave-DLE
(en: slave DLE)
DLE, welche die Funktionen eines Netzwerk-Slaves ausführt

3.2.35
Station
(en: station)
Knoten

3.2.36
Statuswort
(en: status word)
zwei aufeinanderfolgende Oktette im Bestätigungstelegramm, die Statusinformationen eines Gerätes enthalten

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3.2.37
S-0-nnnn
(en: S-0-nnnn)
Kennzeichnung von IDNs

3.2.38
Telegramm
(en: telegram)
DLPDU

3.2.39
Topologie
(en: topology)
physische Netzwerkarchitektur in Bezug auf die Verbindung zwischen den Stationen des Kommunikationssystems

3.2.40
Topologieindex
(en: topology index)
Position eines Slaves in einem Typ 19-Netz unter Verwendung einer Nummerierung mit aufsteigender Reihenfolge, startend mit dem Wert 1 am ersten Slave nach dem Master

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EUROPEAN STANDARD

NORME EUROPÉENNE

EUROPÄISCHE NORM

EN 61158-4-19

October 2014

ICS 25.040.40; 35.100.20; 35.110

Supersedes EN 61158-4-19:2012

English Version

Industrial communication networks - Fieldbus specifications - Part 4-19: Data-link layer protocol specification - Type 19 elements (IEC 61158-4-19:2014)

Réseaux de communication industriels - Spécifications des bus de terrain - Partie 4-19: Spécification du protocole de la couche liaison de données - Éléments de type 19 (CEI 61158-4-19:2014)

Industrielle Kommunikationsnetze - Feldbusse - Teil 4-19: Protokollspezifikation des Data Link Layer (Sicherungsschicht) - Typ 19-Elemente (IEC 61158-4-19:2014)

This European Standard was approved by CENELEC on 2014-09-19. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

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Ref. No. EN 61158-4-19:2014 E

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Foreword

The text of document 65C/762/FDIS, future edition 3 of IEC 61158-4-19, prepared by SC 65C “Industrial networks” of IEC/TC 65 “Industrial-process measurement, control and automation" was submitted to the IEC-CENELEC parallel vote and approved by CENELEC as EN 61158-4-19:2014.

The following dates are fixed:

• latest date by which the document has to be implemented at national level by publication of an identical national standard or by endorsement	(dop)	2015-06-19
• latest date by which the national standards conflicting with the document have to be withdrawn	(dow)	2017-09-19

This document supersedes EN 61158-4-19:2012.

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Endorsement notice

The text of the International Standard IEC 61158-4-19:2014 was approved by CENELEC as a European Standard without any modification.

In the official version, for bibliography, the following notes have to be added for the standards indicated:

IEC 61131 Series	NOTE	Harmonised as EN 61131 Series
IEC 61158-1:2014	NOTE	Harmonised as EN 61158-1:2014
IEC 61158-3-19:2014	NOTE	Harmonised as EN 61158-3-19:2014
IEC 61158-5-16:2007	NOTE	Harmonised as EN 61158-5-16:2007
IEC 61158-5-19:2014	NOTE	Harmonised as EN 61158-5-19:2014
IEC 61158-6-16:2007	NOTE	Harmonised as EN 61158-6-16:2007
IEC 61158-6-19:2014	NOTE	Harmonised as EN 61158-6-19:2014
IEC 61784-1	NOTE	Harmonised as EN 61784-1
IEC 61784-2	NOTE	Harmonised as EN 61784-2
IEC 61800-7 Series	NOTE	Harmonised as EN 61800-7 Series
IEC 61800-7-201	NOTE	Harmonised as EN 61800-7-201
IEC 61800-7-202	NOTE	Harmonised as EN 61800-7-202
IEC 61800-7-203	NOTE	Harmonised as EN 61800-7-203
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INTRODUCTION

This part of IEC 61158 is one of a series produced to facilitate the interconnection of automation system components. It is related to other standards in the set as defined by the “three-layer” fieldbus reference model described in IEC 61158-1.

The data-link protocol provides the data-link service by making use of the services available from the physical layer. The primary aim of this standard is to provide a set of rules for communication expressed in terms of the procedures to be carried out by peer data-link entities (DLEs) at the time of communication. These rules for communication are intended to provide a sound basis for development in order to serve a variety of purposes:

a) as a guide for implementors and designers;

b) for use in the testing and procurement of equipment;

c) as part of an agreement for the admittance of systems into the open systems environment;

d) as a refinement to the understanding of time-critical communications within OSI.

This standard is concerned, in particular, with the communication and interworking of sensors, effectors and other automation devices. By using this standard together with other standards positioned within the OSI or fieldbus reference models, otherwise incompatible systems may work together in any combination.

NOTE Attention is drawn to the fact that use of the associated protocol type(s) is restricted by its (their) intellectual-property-right holder(s). In all cases, the commitment to limited release of intellectual-property-rights made by the holder(s) of those rights permits a particular data-link layer protocol type to be used with physical layer and application layer protocols in Type combinations as specified explicitly in the profile parts. Use of the various protocol type(s) in other combinations may require permission from their respective intellectual-property-right holders.

The International Electrotechnical Commission (IEC) draws attention to the fact that it is claimed that compliance with this document may involve the use of patents concerning Type 19 elements and possibly other types given in this document as follows:

DE 102 00 502 4759.8-32	[BR]	Verfahren zur Laufzeitkorrektur in einer Kommunikationsstruktur
DE 102 37 097	[RI]	Korrektur von Signallaufzeiten in verteilten Kommunikationssystemen

IEC takes no position concerning the evidence, validity and scope of these patent rights.

The holders of these patent rights have assured IEC that they are willing to negotiate licenses either free of charge or under reasonable and non-discriminatory terms and conditions with applicants throughout the world. In this respect, the statement of the holders of these patent rights is registered with IEC. Information may be obtained from:

[BR] BoschRexrothAG
Zum Eisengiesser 1
D-97816 Lohr
Germany

[RI] Rexroth Indramat GmbH
Bgm.-Dr.-Nebel-Str. 2
D - 97816 Lohr
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INDUSTRIAL COMMUNICATION NETWORKS – FIELDBUS SPECIFICATIONS –

Part 4-19: Data-link layer protocol specification – Type 19 elements

1 Scope

1.1 General

The data-link layer provides basic time-critical messaging communications between devices in an automation environment.

This protocol provides communication opportunities to all participating data-link entities

a) in a synchronously-starting cyclic manner, according to a pre-established schedule, and
b) in a cyclic or acyclic asynchronous manner, as requested each cycle by each of those data-link entities.

Thus this protocol can be characterized as one which provides cyclic and acyclic access asynchronously but with a synchronous restart of each cycle.

1.2 Specifications

This standard specifies

a) procedures for the timely transfer of data and control information from one data-link user entity to a peer user entity, and among the data-link entities forming the distributed data-link service provider;
b) the structure of the fieldbus DLPDUs used for the transfer of data and control information by the protocol of this standard, and their representation as physical interface data units.

1.3 Procedures

The procedures are defined in terms of

a) the interactions between peer DL-entities (DLEs) through the exchange of fieldbus DLPDUs;
b) the interactions between a DL-service (DLS) provider and a DLS-user in the same system through the exchange of DLS primitives;
c) the interactions between a DLS-provider and a Ph-service provider in the same system through the exchange of Ph-service primitives.

1.4 Applicability

These procedures are applicable to instances of communication between systems which support time-critical communications services within the data-link layer of the OSI or fieldbus reference models, and which require the ability to interconnect in an open systems interconnection environment.

Profiles provide a simple multi-attribute means of summarizing an implementation's capabilities, and thus its applicability to various time-critical communications needs.

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1.5 Conformance

This standard also specifies conformance requirements for systems implementing these procedures. This part of this standard does not contain tests to demonstrate compliance with such requirements.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE All parts of the IEC 61158 series, as well as IEC 61784-1 and IEC 61784-2 are maintained simultaneously. Cross-references to these documents within the text therefore refer to the editions as dated in this list of normative references.

IEC 61158-4-16:2007, *Industrial communication networks – Fieldbus specifications – Part 4-16: Data-link layer protocol specification – Type 16 elements*

ISO/IEC 7498-1, *Information technology – Open Systems Interconnection – Part 1: Basic Reference Model: The Basic Model*

ISO/IEC 7498-3, *Information technology – Open Systems Interconnection – Part 3: Basic Reference Model: Naming and addressing*

ISO/IEC 8802-3, *Information technology – Telecommunications and information exchange between systems – Local and metropolitan area networks – Specific requirements – Part 3: Carrier sense multiple access with collision detection (CSMA/CD) access method and physical layer specifications*

ISO 8601, *Data elements and interchange formats – Information interchange – Representation of dates and times*

IEEE 802.3: *IEEE Standard for Information technology – Telecommunications and information exchange between systems – Local and metropolitan area networks – Specific requirements – Part 3: Carrier Sense Multiple Access with Collision Detection (CSMA/CD) Access Method and Physical Layer Specifications*

Internet Engineering Task Force (IETF), *Request for Comments (RFC): RFC 879, The TCP Maximum Segment Size and Related Topics* (available at <http://www.ietf.org/rfc/rfc0879.txt>)

3 Terms, definitions, symbols, acronyms, abbreviations and conventions

For the purposes of this document, the following terms, definitions, symbols, abbreviations and conventions apply.

3.1 Reference model terms and definitions

This standard is based in part on the concepts developed in ISO/IEC 7498-1 and ISO/IEC 7498-3, and makes use of the following terms defined therein.

3.2 Additional Type 19 terms and definitions

For the purposes of this document, the following terms and definitions apply.

3.2.1
broadcast
transmission to all devices in a network without any acknowledgment by the receivers

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3.2.2
communication cycle
fixed time period between two master synchronization telegrams in which real-time telegrams are transmitted in the RT channel and non-real-time telegrams are transmitted in the IP channel

3.2.3
control unit
control device (for example, a PLC as specified in the IEC 61131 standard family)

3.2.4
control word
two adjacent octets inside the master data telegram containing commands for the addressed device

3.2.5
cross communication
direct multicast data transfer between devices

3.2.6
cycle time
duration of a communication cycle

3.2.7
cyclic communication
periodic exchange of telegrams

3.2.8
cyclic data
part of a telegram, which does not change its meaning during cyclic operation of the network

3.2.9
cyclic operation
operation in which devices in the communication network are addressed and queried one after the other at fixed, constant time intervals

3.2.10
device
a slave in the communication network, (for example, a power drive system as defined in the IEC 61800 standard family, I/O stations as defined in the IEC 61131 standard family)

3.2.11
device address field
address field (eight bits) containing the address of the device

3.2.12
device control
four adjacent octets inside the master data telegram containing commands for each device

3.2.13
device status
four adjacent octets inside the acknowledge telegram containing status information for each device

3.2.14
DLE station identifier
network address assigned to a DLE

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3.2.15
DLE station slot
unit (granularity of one) of position dependent mapping (for cyclic data field) of which a DLE may occupy one or more, delineated by the range beginning at the DLE station identifier with a length equal to the configured number of occupied slots

3.2.16
element
part of IDNs – each IDN has 7 elements, whereas each one has a specific meaning (for example: number, name, data)

3.2.17
EtherType
part of the Type 19 specific telegram header

3.2.18
forwarding
mode by which a device passes on a received telegram to the other port, either changed or unchanged

3.2.19
identification number
IDN
designation of operating data under which a data block is preserved with its attribute, name, unit, minimum and maximum input values, and the data

3.2.20
line
line structure
network topology, in which the transmission medium is routed from station to station in the form of a line; the information is transmitted in one direction from the master down to the last slave in the line, and then flows back to the master via all the slaves in the reverse order (CP16/3)

3.2.21
loopback
mode by which a device passes on a received telegram to the same port and to the other port, either changed or unchanged

3.2.22
master
node, which assigns the other nodes (i.e., slaves) the right to transmit

3.2.23
master data telegram
MDT
telegram, in which the master inserts its data

3.2.24
master DLE
DLE that performs the functions of network master

3.2.25
master synchronization telegram
MST
telegram, or part of a telegram, in which the master inserts a time synchronization signal

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3.2.26
MDT0 telegram
telegram, in which the master transmits its synchronization data, as well as parts or all of its real-time data, to the slaves

3.2.27
participant
node which is connected to the network

3.2.28
physical layer
first layer of the ISO-OSI reference model

3.2.29
protocol
convention about the data formats, time sequences, and error correction in the data exchange of communication systems

3.2.30
real-time data
part of the telegram that does not change its meaning during cyclic operation of the interface

3.2.31
RT channel
defined time slot within the communication cycle, which passes the CPF16 real-time telegrams

3.2.32
service channel
SVC
non real-time transmission of information upon master request during RT channel

3.2.33
slave
node, which is assigned the right to transmit by the master

3.2.34
slave DLE
DLE that performs the functions of network slave

3.2.35
station
node which is connected to the network

3.2.36
status word
two adjacent octets inside the acknowledge telegram containing status information of a device

3.2.37
S-0-nnnn
designation of IDNs

3.2.38
telegram
DLPDU

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3.2.39
topology
physical network architecture with respect to the connection between the stations of the communication system

3.2.40
topology index
position of a slave in a Type 19 network using a daisy chain numeration starting with value 1 at the first slave after the master

3.3 Symbols

ADR	device address (1 ≤ ADR ≤ 511) adjusted directly on the device, for example using a selector switch
AT MST	header in AT
AT0...3	acknowledge telegrams
INFO	service channel information
JtScyc	jitter in tScyc
MDT0	master data telegram with synchronization data that the slaves evaluates
MDT1...3	master data telegrams without synchronization data
P1	port 1
P2	port 2
RxD	received data
SLKN	slave identification parameter, slave arrangement
SVC	service channel
t1	AT transmission starting time
t1min	shortest AT transmission starting time
t3	command value valid time
t4	feedback acquisition capture point
t5	minimum feedback processing time
tcable	time, by which the transmitted signal is delayed by the cable, for each unit of length (approx., 5 ns/m)
trep	time, by which the received signal is delayed by a forwarding slave (input-output)
tRing	time, which a master telegram needs, until it has passed through the network and reached the master again
tScyc	communication cycle time

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TxD	transmitted data

3.4 Acronyms and abbreviations

AHS	service transport handshake of the device (acknowledge HS)
AT	acknowledge telegram
C-CON	connection control
C-DEV	device control
C1D	class 1 diagnostic
CP	communication phase
CPS	communication phase switching
CRC	cyclic redundancy check
CSoS	CIP Safety on SERCOS
FCS	DLPDU check sequence
FG	Function Group
FSP	Function-specific Profile
GDP	Generic Device Profile
HP	Hot-Plug
HP0	Hot-Plug phase 0
HP1	Hot-Plug phase 1
HP2	Hot-Plug phase 2
HS	service channel handshake (see AHS and MHS)
IDN	identification number
IP	Internet protocol
MAC	media access control
MDT	master data telegram
MDT MST	header in MDT
MHS	service transport handshake of the master

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MS	communication from slave to master
MST	master synchronization telegram
NRT	non real-time
P-channel	primary channel
P-telegram	primary telegram
PL	parametrization level
RT	real-time
RTC	real-time channel
RTD	real-time data in MDT or AT
S-DEV	device status
S-channel	secondary channel
S-telegram	secondary telegrama
SCH	session control header
SCP	Type 19 Communication Profile
SE	structure element
SERCOS	serial real-time communication system interface
SFD	start DLPDU delimiter
SI	structure instance
SMP	Type 19 Messaging Protocol
SVC	service channel
UCC	unified communication channel

3.5 Additional conventions

All data types are assigned identification numbers (IDNs). They include real-time data (commands and feedback values), parameters, and procedures. Most IDNs are similar to those for Type 16 (see IEC 61158-4-16, 3.6). Several IDNs relate to the application and are defined in their relevant standards (for example, IEC 61800-7-20x for Power Drive Systems).

Refer to Annex A for additional information, as well as to IEC 61158-4-16, Clause A.1 for detailed IDN specification.

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4 DL-protocol overview

4.1 Overview

This protocol type provides a highly optimized means of interchanging fixed-length real-time data and variable-length segmented messages between a single master device and a set of slave devices, interconnected in a ring or a line topology. The ring topology provides for redundant communication paths, and in case of a fault it automatically switches to a set of two lines without disturbing the communication.

This protocol type also provides for direct real-time data transmission between slaves, inside the real-time channel (RTC), within each communication cycle.

The exchange of real-time data is totally synchronous by configuration and is unaffected by the messaging traffic.

The device addresses are set by the user, using a selector for example. Additional devices may be added whenever required, even during operation, without affecting the address selections, which already exist. The determination of the number, identity and characteristics of each device may be configured or may be detected automatically at start-up.

Slave interfaces shall be used to connect the slave devices to the network. At the physical layer, a slave represents the connection of one or more devices to the network. Logically, one slave with several devices shall act the same as several slaves with one device each.

This protocol type also provides a unified communication channel (UC channel), in which any Standard Ethernet DLPDUs can be exchanged between Type 19 devices and any other connected Ethernet network nodes.

There are two classes of Type 19 DLE:

a) master DLE;

b) slave DLE.

Only the master DLE is able to initiate cyclic transmission.

Type 19 telegrams are Ethernet DLPDUs according to ISO/IEC 8802-3. Type 19 real-time telegrams shall be transmitted in the real-time part of the communication cycle time. They mainly transport input and output data, for example command and feedback values. The Type 19 header specifies two types type 19 telegrams:

a) Master data telegram (MDT), in which the master transmits real-time data to the slaves;

b) Acknowledge telegram (AT), in which the slaves transmit real-time data to the master and other slaves.

Other Ethernet DLPDUs can be transmitted in the UC channel.

Type 19 specifies 4 MDTs (MDT0 to MDT3). The MDTs shall be transmitted by the master and received by each slave. The MDTs shall contain all information (for example: synchronization, command values, digital outputs) which is sent from the master to the slaves through the real-time channel.

MDT0 shall always be transmitted. MDT1 through MDT3 shall be transmitted only if required depending on the configuration of the application data to be transmitted. The master shall always send the same number of MDTs during each communication cycle.

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Type 19 specifies 4 ATs (AT0 to AT3). The ATs shall be transmitted by the master with the configured AT length. The AT data fields are set to 0, except the application data of cross communication. Each slave shall insert its data into its allocated data field within the AT. The ATs shall contain all information (for example: feedback values, digital inputs) which is sent from the slaves to the master as well as to other slave devices through the real-time channel.

AT0 shall always be transmitted. AT1 through AT3 shall be transmitted only if required depending on the configuration of the application data to be transmitted. The master shall always send the same number of ATs during each communication cycle.

The allocations of the service channels (SVC), the device control (C-DEV), the device status (S-DEV) and the connections in the MDT as well as in the AT shall be configured with parameters. The lengths of connections in the MDTs and the ATs shall depend on the amount of application data and may be different for each slave depending upon configuration. The number of MDTs and ATs may also be different because of the configuration. This configuration shall meet the following requirements.

a) A SVC of a slave shall be transmitted within one MDT or one AT and shall not be spread into different MDTs or ATs.
b) A connection of a slave shall be transmitted within one MDT or one AT and shall not be spread into two different MDTs or ATs.
c) Each connection and SVC shall start at an even address in the MDT and AT.
d) Each device control and device status shall start at an even address in the MDT and AT.
e) All other combination of configurations of SVCs, connections, device control and device status are possible.

Devices in a Type19 network use the order of little endian for the serial transmission of data. Little endian describes the least significant bit of the least significant octet of the least significant word is sent first, followed by the rest of the bits of this octet, then by the rest of the octets of this word, and so on in the same order.

4.2 General DLPDU identification

4.2.1 Introduction

DLPDUs shall be identified as specified in Table 1.

Table 1 – Ethernet DLPDU identification

DLPDU field	Data type	Value/description
Dest MAC	octet[6]	Destination MAC address
Src MAC	octet[6]	Source MAC address
EtherType	WORD	0x88CD (Type 19)

4.2.2 Destination address (Dest MAC)

The master shall transmit DLPDUs to all slaves using the broadcast address 0xFFFF FFFF FFFF as the destination address.

4.2.3 Source address (Src MAC)

The source address shall always be the MAC address of the master.

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4.2.4 EtherType

The EtherType for real-time DLPDUs shall contain the value 0x88CD, which is the unique type field number that has been allocated by the IEEE EtherType Field Registration Authority for Type 19 telegrams.

NOTE This field number refers to Type 19 communication.

4.3 General DLPDU structure

4.3.1 Introduction

The data structure in a DLPDU shall consist of the following data entries as specified in Table 2.

Table 2 – Data structure in a DLPDU

Data field	Data type	Value/description
Header	octet[6]	Defines the DLPDU type
Payload	octet[40-1494]	Data fields are padded, if less than 40 octets

4.3.2 DLPDU header

The DLPDU header shall specify two types of telegrams, as specified in 4.4:

- **Master data telegram (MDT):** MDTs shall transmit data from the master to the slaves;
- **Acknowledge telegram (AT):** ATs shall transmit data from the slaves to the master, as well as to other slaves within the Type 19 network.

4.3.3 DLPDU payload

All transmitted data are permitted to have arbitrary bit sequences.

Padding octets shall be added if the Type 19 data is less than 40 octets, in order to reach a total data field length of at least 46 octets.

The DLPDU payload shall be as described in 4.5 and 4.6.

4.4 DLPDU header

4.4.1 Introduction

The DLPDU header shall distinguish the various DLPDUs. It shall be coded in the telegram whether the DLPDU is transmitted in the primary or secondary channel, whether it is an MDT or an AT, and which one (MDT0 to MDT3, respectively AT0 to AT3).

In a line topology, the master shall decide whether the telegrams are marked as primary or secondary telegrams, depending upon configuration.

The DLPDU header structure is shown in Table 3:

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Table 3 – DLPDU payload header

Data field	Data type	Value/description
DLPDU type	octet[1]	see 4.4.2
Reserved	octet[1]	—
Reserved	octet[4]	—

4.4.2 DLPDU type

The DLPDU type shall be generated by the master and transmitted in every MDT and AT. Its content shall be as shown in Table 4.

Table 4 – DLPDU type

Bit number	Bit value	Description
7	—	Primary or secondary telegram
	0	Telegram on the primary channel (P-Telegram)
	1	Telegram on the secondary channel (S-Telegram)
6	—	MDT or AT
	0	MDT
	1	AT
5	—	Cycle CNT
	0	Cycle CNT is disabled
	1	Cycle CNT is enabled (Cycle CNT is defined in MDT phase (bit 6-4)
4	—	(reserved)
3-2		(reserved for Telegram number 4 to 15)
1-0	—	Telegram number
	00	Telegram number 0
	01	Telegram number 1
	10	Telegram number 2
	11	Telegram number 3

4.5 MDT DLPDU

4.5.1 MDT MST field summary

The MDT shall be as specified in Table 5. The MDT header of MDT0 is called MST.

Table 5 – MDT header

DLPDU part	Data field	Data type	Value/Description
MDT header	MDT type	octet[1]	see 4.5.3
	MDT phase	octet[1]	see 4.5.4
	MDT CRC	octet[4]	see 4.5.5

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4.5.2 Evaluation of MDT header in the slaves

The MDT header shall be generated by the master and evaluated by the slaves. Each slave shall evaluate the MDT header according to Table 6.

Table 6 – MDT header to be considered by the slave

	MDT type	MDT phase	MDT CRC
MDT0 = MST	Yes	Yes	Yes
MDT1	Yes	No	Yes
MDT2	Yes	No	Yes
MDT3	Yes	No	Yes

NOTE The slave has to evaluate the MDT type and MDT phase only if the MDT CRC is valid.

4.5.3 MDT type

Refer to 4.4.2, whereas bit #6 shall be 0.

4.5.4 MDT phase

The MDT phase shall contain the status of the Type 19 communication during initialization and during CP4. The phase shall be generated by the master and transmitted in every MDT. The structure is shown in Table 7.

Table 7 – MDT phase

Bit number	Bit value	Description
7	—	Communication phase switching (CPS)
	0	Current CP Communication phase (bit 3-0) contains current CP.
	1	New CP Communication phase (bit 3-0) contains the target CP for phase switching.
6-4	—	Cycle CNT (shall be enabled in MDT DLPDU type, bit 5 is set to 1)
	0-7	Value of Cycle CNT (is incremented by 1 in each communication cycle by the master)
3-0	—	Communication phase (CP)
	0000	CP0
	0001	CP1
	0010	CP2
	0011	CP3
	0100	CP4
	0101 to 1111	(reserved)

4.5.5 MDT CRC

The cyclic redundancy check (CRC) shall be used by the transmit and receive algorithms to generate a CRC value for the MDT CRC field. The MDT CRC field shall contain a 4-octet (32-bit) cyclic redundancy check (CRC) value. This value shall be computed as a function of the contents of the destination address (see 4.2.2), source address (see 4.2.3), EtherType (see 4.2.4), Type 19 type

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(see 4.4.2) and phase (see 4.5.4). The encoding shall be as defined by the Standard Ethernet CRC generating polynomial (see ISO/IEC 8802-3).

The MDT CRC shall be generated by the master and transmitted in every MDT (MDT0 to MDT3). This CRC shall be evaluated in every MDT by the slave (see Table 6).

4.5.6 MDT payload during initialization

4.5.6.1 General

The content of the MDT data field depends on the communication phase (CP) and is described in the following subclauses.

4.5.6.2 CP0

The master shall always transmit MDT0 telegrams only, and no MDT1, MDT2, nor MDT3 telegrams. MDT0 shall be structured as stated in Table 8.

Table 8 – MDT0 structure in CP0

DLPDU part	Data field	Data type	Value/Description
MDT	MDT type	octet[1]	MDT0, see 4.5.3
	MDT phase	octet[1]	CP0, see 4.5.4
	MDT CRC	octet[4]	see 4.5.5
MDT payload	Communication version	octet[4]	see Table 9
	MDT Data Field	octet[36]	Shall be padded and not used

Table 9 – Communication version

Bit number	Bit value	Description
31-23	—	(reserved: 0x00 as valid combination shall be checked by slaves)
22	—	SWC
	0	Non-Type 19 (Industrial Ethernet) devices not used by application
	1	Non-Type 19 (Industrial Ethernet) devices used by application: last slave in line shall not forward Type 19 telegrams to the inactive port (loopback without forward shall be activated), only last slave shall set S-0-1032 Communication control.bit 3 = 1
21	—	Fast CP switch
	0	Transmission of MST (MDT0) interrupted during CP switch for CPS delay time (120ms)
	1	CPS delay time reduced to the reconfiguration time of the master (shall be acknowledged by the slave in the topology index field of AT0-CP0)
20	—	Transmission of communication parameters in MDT0 of CP0
	0	No transmission of parameters
	1	Transmission of the following parameters: - AT0 transmission starting time (t1-CP1&CP2) - Beginning of UC channel (t6-CP1&CP2) - End of UC channel (t7-CP1&CP2)

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Bit number	Bit value	Description
19-18	—	(reserved: 0x00 as valid combination shall be checked by slaves)
17-16	—	Structure and number of MDTs and ATs in CP1 and CP2
	00	2 MDTs and 2 ATs in CP1 and CP2 (include SVCs, C-DEV, S-DEV) – up to 255 slaves
	01	4 MDTs and 4 ATs in CP1 and CP2 (include SVCs, C-DEV, S-DEV) – up to 511 slaves
	10	(reserved)
	11	(reserved)
15-8	—	(reserved)
7-1	—	(reserved: 0x00 as valid combination shall be checked by slaves)
0	—	Address allocation
	0	Without address allocation (used for Type 19 Version 1.0 only)
	1	Address allocation (shall be used for Type 19 Version 1.1.1 and greater)

4.5.6.3 CP1 and CP2

The master shall choose between two communication sequences used in CP1 and CP2:

a) If the master supports 255 slaves or less, it may transmit either MDT0 to MDT3 or MDT0 and MDT1 only, for example to save initialization time.

b) If the master supports 256 slaves or more (up to 511 slaves) it shall transmit MDT0 to MDT3.

The slaves shall support both sequence options. It shall select the required one by evaluating bit 17 and bit 16 of the communication version (see Table 9).

The MDT data fields shall contain the service channel (see 6.2) and the device control (see 4.5.7.4.2) of the topology indices as shown in Table 10, Table 11, Table 12 and Table 13 respectively.

In CP1 a slave shall behave as requested if the handshake bit (MHS) is set to 1 in the corresponding SVC control. The MDT SVC INFO is “don’t care”. The content of device control shall be valid.

Telegrams in CP2 shall have the same structure as in CP1, but the contents of SVC INFO shall be valid only in CP2.

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Table 10 – MDT0 in CP1 and CP2 (topology indices 0 to 127)

DLPDU part	Data field	Data type	Value/Description
MDT MST	MDT type	octet[1]	MDT0, see 4.5.3
	MDT phase	octet[1]	CP1 or CP2, see 4.5.4
	MDT CRC	octet[4]	see 4.5.5
MDT data field	MDT SVC for topology index #0	octet[6]	—
	…	…	(And so on for topology indices #1 to #126)
	MDT SVC for topology index #127	octet[6]	—
	Device control for topology address #0	octet[2]	—
	Reserved for topology index #0	octet[2]	—
	…	…	(And so on for topology indices #1 to #126)
	Device control for topology index #127	octet[2]	—
	Reserved for topology index #127	octet[2]	—

Table 11 – MDT1 in CP1 and CP2 (topology indices 128 to 255)

DLPDU part	Data field	Data type	Value/Description
MDT MST	MDT type	octet[1]	MDT1, see 4.5.3
	MDT phase	octet[1]	CP1 or CP2, see 4.5.4
	MDT CRC	octet[4]	see 4.5.5
MDT data field	SVC of topology index #128	octet[6]	—
	…	…	(And so on for topology index #129 to #254)
	SVC of topology index #255	octet[6]	—
	Device control of topology index #128	octet[2]	—
	Reserved for topology index #128	octet[2]	—
	…	…	(And so on for topology index #129 to #254)
	Device control of topology index #255	octet[2]	—
	Reserved for topology index #255	octet[2]	—

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Table 12 – MDT2 in CP1 and CP2 (topology indices 256 to 383)

DLPDU part	Data field	Data type	Value/Description
MDT MST	MDT type	octet[1]	MDT2, see 4.5.3
	MDT phase	octet[1]	CP1 or CP2, see 4.5.4
	MDT CRC	octet[4]	see 4.5.5
MDT data field	SVC of topology index #256	octet[6]	—
	…	…	(And so on for topology index #257 to #382)
	SVC of topology index #383	octet[6]	—
	Device control of topology index #256	octet[2]	—
	Reserved for topology index #256	octet[2]	—
	…	…	(And so on for topology index #257 to #382)
	Device control of topology index #383	octet[2]	—
	Reserved for topology index #383	octet[2]	—

Table 13 – MDT3 in CP1 and CP2 (topology indices 384 to 511)

DLPDU part	Data field	Data type	Value/Description
MDT MST	MDT type	octet[1]	MDT3, see 4.5.3
	MDT phase	octet[1]	CP1 or CP2, see 4.5.4
	MDT CRC	octet[4]	see 4.5.5
MDT data field	SVC of topology index #384	octet[6]	—
	…	…	(And so on for topology index #385 to #510)
	SVC of topology index #511	octet[6]	—
	Device control of topology index #384	octet[2]	—
	Reserved for topology index #384	octet[2]	—
	…	…	(And so on for topology index #385 to #510)
	Device control of topology index #511	octet[2]	—
	Reserved for topology index #511	octet[2]	—

4.5.6.4 CP3 and CP4

In CP3 and CP4, the master shall transmit MDTs with the same structure (see 4.5.7).

In CP3, only the service channel and the device control shall be valid. The configured application data in the connections of the MDTs shall not be evaluated, but they shall have the number of octets required for CP4. The positions of the service channels and the connections in the MDT relevant to the individual slaves shall be as transmitted by the master to the slaves during CP2 with the corresponding communication parameters.

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In CP4, the configured application data shall be valid and filled with command values as determined by the parameters that the master transmitted to the slaves during CP2. The connection control and the resource control which depend on the application profile shall be valid.

4.5.7 MDT payload in normal operation

4.5.7.1 Introduction

The MDT payload of MDT0 (see Table 14) shall always contain

a) one MDT0 hot-plug field (see 4.5.7.2) and depending on the configuration;
b) one MDT0 extended field;
c) several service channels, one per slave only (see 5.5.7.2.4);
d) several device controls, one per slave only;
e) several connections (see 4.5.7.4).

The MDT payload of MDT1 to MDT3 (see Table 14) can contain depending on the configuration

a) several service channels, one per slave only (see 5.5.7.2.4);
b) several device controls, one per slave only;
c) several connections (see 4.5.7.4).

Table 14 – MDT data field

DLPDU part	Data field	Data type	Value/Description
MDT data field	MDT0 hot-plug field	octet[8]	In MDT0 only, see 4.5.7.2
	MDT0 extended field	octet[4]	In MDT0 only, see 4.5.7.2
	MDT service channels	octet[see 4.5.7.3]	Optional. see 4.5.7.3
	MDT real-time data	octet[see 4.5.7.4]	Optional. see 4.5.7.4

For each slave,

- IDN S-0-1013 (SVC offset in MDT) shall set the offset for its service channel;
- IDN S-0-1009 (Device Control offset in MDT) shall set the offset for the device control;
- IDN S-0-1050.x.3 (Telegram assignment) shall set the offset for the connection data;
- IDN S-0-1050.x.5 (Current length of connection) shall contain the length of the connection data;
- IDN S-0-1010 (Lengths of MDTs) shall contain the lengths of all MDTs (in Figure 1 shown for MDT0 only).

These parameters shall be transmitted by the master to the slaves in CP2.

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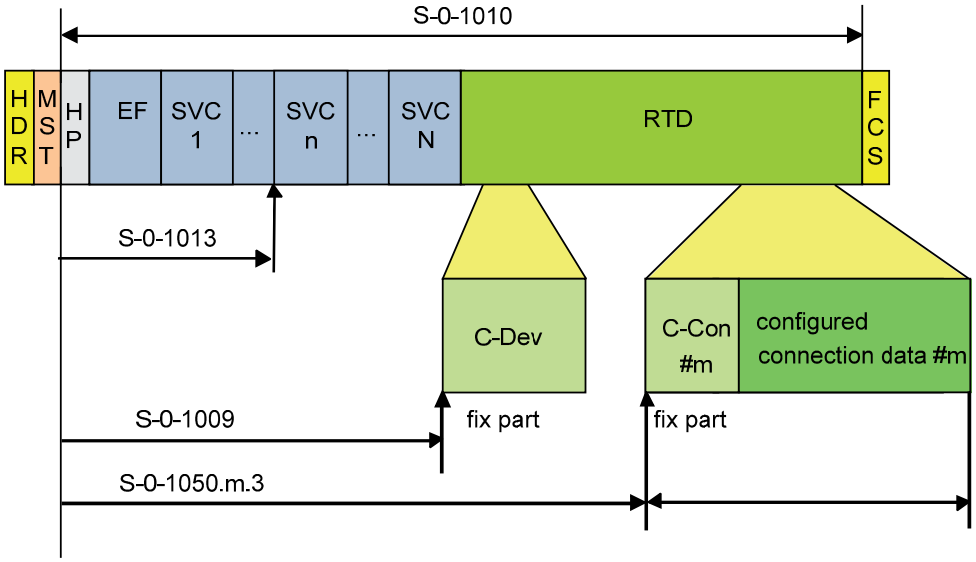

Figure 1 – Example of offsets within MDT payload

4.5.7.2 MDT hot-plug field

4.5.7.2.1 MDT hot-plug field summary

The structure of the MDT hot-plug field shall be as specified in Table 15, depending upon hot-plug phases (see 5.5).

Table 15 – MDT hot-plug field

DLPDU part	Data field	Data type	Value/Description
MDT hot-plug field	MDT-HP address	octet[2]	see 4.5.7.2.2
	HP control	octet[2]	see 4.5.7.2.3
	MDT-HP INFO	octet[4]	see 4.5.7.2.4

4.5.7.2.2 MDT-HP address field

The content of the HP address field in the MDT shall be as specified in Table 16:

Table 16 – HP address in MDT-HP field

Bit number	Value	Description
15-12	—	Slave index specifies the number of slaves within one device (device can contain multiple slaves)
	0-15	Slave index (set by master in HP0)
11-0	—	Device addresses
	0-511	Device addresses for operation (set by master in HP1 and HP2)
	512-4092	(reserved)
	4093	(reserved)
	4094	(reserved)
	4095	Broadcast address (set by master in HP0, each HP slave shall react to this address)

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