

INTERNATIONAL STANDARD

NORME INTERNATIONALE

Helical-scan compressed digital video cassette system using 6,35 mm magnetic tape – Format D-7 –

Part 1: VTR specifications

Système de magnétoscope numérique à cassette à balayage hélicoïdal à signal compressé utilisant une bande magnétique de 6,35 mm – Format D-7 –

Partie 1: Spécifications VTR



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**Helical-scan compressed digital video cassette system using 6,35 mm magnetic tape – Format D-7 –
Part 1: VTR specifications**

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Partie 1: Spécifications VTR**

INTERNATIONAL
ELECTROTECHNICAL
COMMISSION

COMMISSION
ELECTROTECHNIQUE
INTERNATIONALE

PRICE CODE
CODE PRIX

XD

ICS 33.160.40

ISBN 978-2-83220-317-0

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

HELICAL-SCAN COMPRESSED DIGITAL VIDEO CASSETTE SYSTEM USING 6,35 mm MAGNETIC TAPE – FORMAT D-7 –

Part 1: VTR specifications

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International Standard IEC 62071-1 has been prepared by technical area 6: Higher data rate storage media, data structures and equipment of IEC technical committee 100: Audio, video and multimedia systems and equipment.

This bilingual version (2012-11) corresponds to the monolingual English version, published in 2005-10.

The text of this standard is based on the following documents:

CDV	Report on voting
100/900/CDV	100/984/RVC

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

The French version of this standard has not been voted upon.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

IEC 62071 consists of the following parts, under the general title *Helical-scan compressed digital video cassette system using 6,35 mm magnetic tape – Format D-7*:

Part 1: VTR specifications

Part 2: Compression format

Part 3: Data stream format

This part 1 describes the VTR specifications which are tape, magnetization, helical recording, modulation method and basic system data for video compressed data.

Part 2 describes the specifications for encoding process and data format for 525i and 625i systems.

Part 3 describes the specifications for transmission of DV-based compressed video and audio data stream over 270 Mb/s and 360 Mb/s serial digital interface.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to the specific publication. At this date, the publication will be

- reconfirmed;
- withdrawn;
- replaced by a revised edition, or
- amended.

HELICAL-SCAN COMPRESSED DIGITAL VIDEO CASSETTE SYSTEM USING 6,35 mm MAGNETIC TAPE – FORMAT D-7 –

Part 1: VTR specifications

1 Scope

This part of IEC 62071 specifies the content, format and recording method of the data blocks containing video, audio, and associated data which form the helical records on 6,35 mm tape contained in cassettes as specified in SMPTE 307M.

In addition, this standard specifies the content, format, and recording method for longitudinal cue and control tracks.

One video channel and two independent audio channels are recorded in the digital format for 25 Mb/s VTRs and one video channel and four independent audio channels for 50 Mb/s VTRs. Each of these channels is designed to be capable of independent editing.

The video channel records and reproduces a component television signal in the 525-line system with a frame frequency of 29,97 Hz (hereinafter referred to as the 525/60 system) and the 625-line system with a frame frequency of 25,00 Hz (hereinafter referred to as the 625/50 system).

Prior to recording, the digital signal is be compressed to a DV-based 25 Mb/s bit stream with 4:1:1 sampling or a DV-based 50 Mb/s bit stream with 4:2:2 sampling.

The standard includes the process required to decode the DV-based 25 Mb/s bit stream and 50 Mb/s bit stream into output video, audio, and data.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

AES3:2003, *AES Recommended Practice for Digital Audio Engineering – Serial transmission format for two-channel linearly represented digital audio data*

SMPTE 12M: 1999, *Television, Audio and Film – Time and Control Code*

SMPTE 259M: 1997, *Television – 10-Bit 4:2:2 Component and 4fsc NTSC Composite Digital Signals – Serial Digital Interface*

3 Abbreviations and acronyms

AAUX	Audio auxiliary data
AP1	Audio application ID
AP2	Video application ID
AP3	Subcode application ID
APT	Track application ID

Arb	Arbitrary
AS	AAUX source pack
ASC	AAUX source control pack
B/W	Black and white flag
CGMS	Copy generation management system
DBN	DIF block number
DCT	Discrete cosine transform
DIF	Digital interface
DSF	DIF sequence flag
ECC	Error correction code
EFC	Emphasis channel flag
EOB	End of block
ID	Identification
IDP	ID parity
ITI	Insert and track information
LF	Locked mode flag
PF	Pilot frame
QNO	Quantization number
QU	Quantization
Res	Reserved for future use
SMP	Sampling frequency
SSA	Start sync area
SSYB	Subcode sync block number
STA	Status of the compressed macro block
Syb	Sync block number
TF	Transmitting flag
TIA	Track information area
Trp	Track pair number
VAUX	Video auxiliary data
VLC	Variable length coding
VS	VAUX source pack
VSC	VAUX source control pack
VSM	Vibrating sample magnetometer

4 Environment and test conditions

4.1 Environment

Tests and measurements made on the system to check the requirements of this standard shall be carried out under the following conditions:

- Temperature: $20\text{ °C} \pm 1\text{ °C}$
- Relative humidity: $(50 \pm 2)\%$
- Barometric pressure: from 86 kPa to 106 kPa
- Tape conditioning: not less than 24 h

- Centre tape tension: 0,09 N $\pm$ 0,02 N (see Annex A)

4.2 Reference tape

A blank tape for reference recordings shall be available from the format holder or approved source.

4.3 Calibration tapes

The calibration tapes meeting the requirements of 4.3.1, 4.3.2, and Clause 5 shall be made available from manufacturers who produce digital television tape recorders and players in accordance with this standard.

4.3.1 Record locations and dimensions

Calibration tape shall be manufactured to tolerances shown in Table 1 or Table 2 for 25 Mb/s format or Table 3 or Table 4 for 50 Mb/s format but with these tolerances reduced by 50 %.

4.3.2 Calibration signals

Two sets of signals shall be recorded on the calibration tape:

- a) – Video: 100 / 0 / 100 / 0 colour bars
 - Audio: 1 kHz tone at 20 dB below full scale on each audio channel
 - Cue: 1 kHz and 6 kHz tone at the analogue recording reference level;
- b) A signal of constant recorded frequency (i.e. the Nyquist frequency) for the purpose of mechanical alignment. The recording level shall conform to 7.1.4.3

5 Tape

5.1 Base

The base material shall be polyester or equivalent.

5.2 Width

The tape width shall be 6,350 mm $\pm$ 0,005 mm.

The tape, covered with glass, is measured without tension at a minimum of five different positions along the tape using a calibrated comparator having an accuracy of 0,001 mm (1 μ m). The tape width shall be within the aforementioned specification at any measuring position.

5.3 Width fluctuation

Tape width fluctuation shall not exceed 5 μ m peak-to-peak. Measurement of tape width fluctuation shall be taken over a tape length of 900 mm. The tape width fluctuation shall be within the aforementioned specification at each of ten equally spaced points in the 900 mm span.

5.4 Reference edge straightness

The reference edge straightness maximum deviation is 6 μ m peak-to-peak. Edge straightness fluctuation is measured at the edge of a moving tape guided by three guides having contact on the same edge and having a distance of 85 mm from the first to second guide and 85 mm from the second to third guide. Edge measurements are averaged over a 10 m length and are made 5 mm from the midpoint between the first and second guide towards the first guide.

5.5 Tape thickness

The total tape thickness shall be $8,8 \begin{smallmatrix} 0 \\ -0,8 \end{smallmatrix} \mu\text{m}$ and $6,7 \begin{smallmatrix} 0 \\ -0,4 \end{smallmatrix} \mu\text{m}$.

NOTE Tape of either thickness may be used for 25 Mb/s or 50 Mb/s formats.

5.6 Transmissivity

Transmissivity shall be less than 5 %, measured over the range of wavelengths 800 nm to 1 000 nm.

5.7 Offset yield strength

The offset yield strength shall be greater than 3 N. The force to produce 0,2 % elongation of a 1 000 mm test sample with a pull rate of 10 mm per minute shall be used to confirm the offset yield strength. The line beginning at 0,2 % elongation parallel to the initial tangential slope is drawn and then read at the point of intersection of the line and the stress-strain curve.

5.8 Magnetic coating

The magnetic layer of the tape shall consist of a coating of metal particles or equivalent.

5.9 Coating coercivity

The magnetic coating coercivity shall be a class 2300 (approximately 2300 Oe / 184000 A/m), with an applied field of 10000 Oe / 800000 A/m measured by a VSM.

6 Helical recordings

6.1 Tape speed

The tape speed for the 25 Mb/s format shall be 33,8201 mm/s for the 525/60 system and 33,8539 mm/s for the 625/50 system. The tape speed for the 50 Mb/s format shall be 67,6401 mm/s for the 525/60 system and 67,7077 mm/s for the 625/50 system. The tolerance shall be $\pm 0,2$ % respectively.

6.2 Sectors

Each recorded track contains an ITI sector, an audio sector, a video sector and a subcode sector.

6.3 Record locations and dimensions

Record locations and dimensions for continuous recording of 25 Mb/s format shall be as specified in Figures 1 and 3, and Table 1 (525/60 system) or in Figures 1 and 3, and Table 2 (625/50 system). In recording, sector locations on each helical track shall be contained within the tolerance specified in Figure 1 and Table 1 (525/60 system) or in Figure 1 and Table 2 (625/50 system).

Record location and dimensions for continuous recording of 50 Mb/s format shall be as specified in Figures 2 and 3, and Table 3 (525/60 system) or in Figures 2 and 3, and Table 4 (625/50 system). In recording, sector locations on each helical track shall be contained within the tolerance specified in Figure 2 and Table 3 (525/60 system) or in Figure 2 and Table 4 (625/50 system).

The reference edge of the tape for dimensions specified in this standard shall be the lower edge as shown in Figures 1 and 2. The magnetic coating, with the direction of tape travel as shown in Figures 1 and 2, are on the side facing the observer.

As indicated in Figures 1 and 2, this standard anticipates a zero guard band between recorded tracks, and the nominal record head width shall be equal to the track pitch of 18 μm . The scanner head configuration should be chosen so that the recorded track widths are contained within the limits of 16 μm to 20 μm .

The format requires flying erasure for recording. In insert editing, this standard provides a guard band of $3 \mu\text{m} \pm 1,5 \mu\text{m}$ between the previously recorded track and the inserted track at editing points only. A typical track pattern for insert editing is shown in Figures B.1 and B.2 of Annex B.

6.4 Helical track record tolerance zones

In the case of 25 Mb/s format, the centre of two consecutive tracks starting at the first track in each video frame shall be contained within the pattern of the two tolerance zones established in Figure 4. Each zone is defined by two parallel lines which are inclined at an angle of $9,1784^\circ$ basic with respect to the tape reference edge. The centrelines of each zone shall be spaced apart 18,0 μm basic. The width of zone 1 shall be 3 μm and the width of zone 2 shall be 5 μm . These zones are established to contain track angle errors, track straightness errors, and vertical head offset tolerances (the measuring technique is shown in Annex C).

In the case of 50 Mb/s format, the lower edge of four consecutive tracks starting at the first track in each video frame shall be contained within the pattern of the four tolerance zones established in Figure 5. Each zone is defined by two parallel lines which are inclined at an angle of $9,1784^\circ$ basic with respect to the tape reference edge. The centrelines of each zone shall be spaced apart 18,0 μm basic. The width of zone 2 shall be 3 μm and the width of zone 1, 3 and 4 shall be 5 μm . These zones are established to contain track angle errors, track straightness errors, and vertical head offset tolerance.

6.5 Relative positions of recorded information

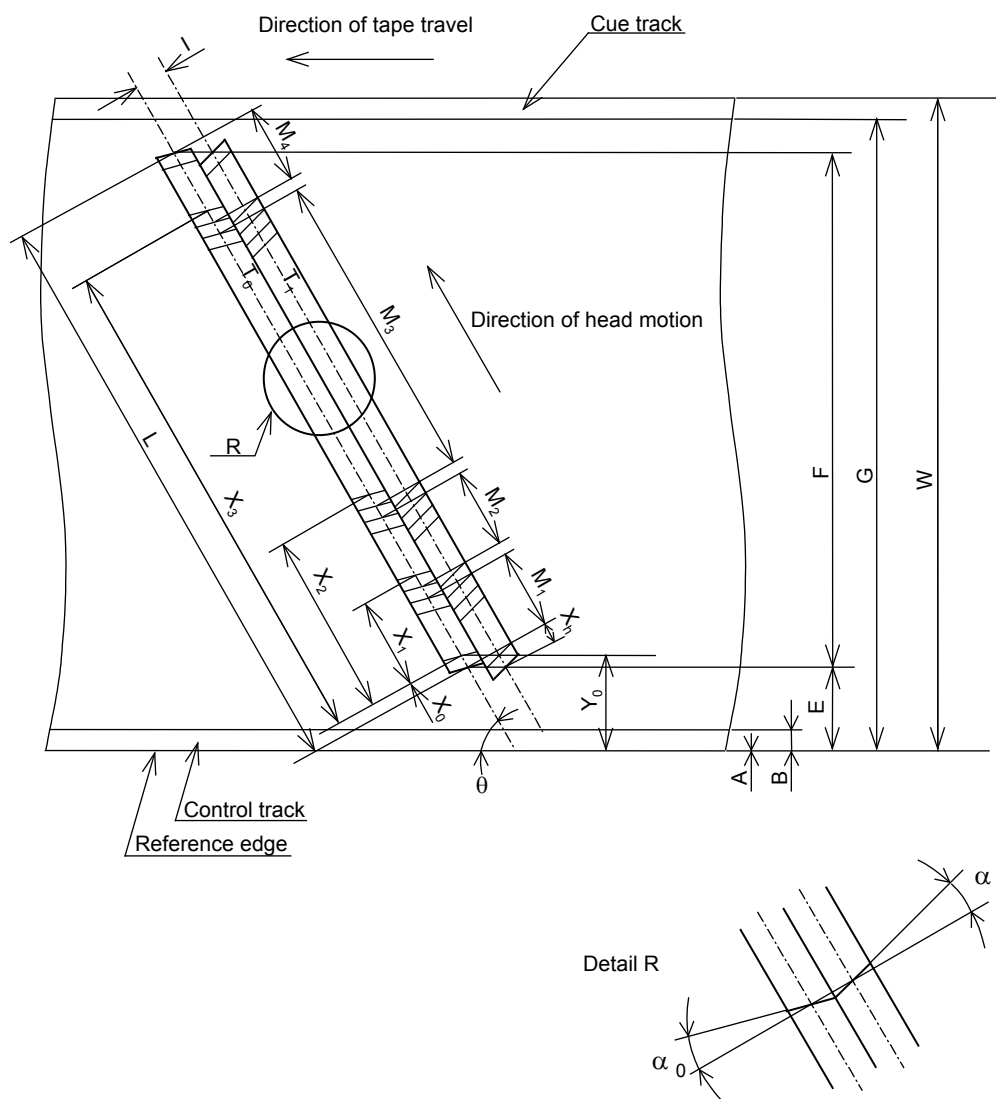
6.5.1 Relative positions of longitudinal tracks

Audio, video, control track and cue track with information intended to be time coincident shall be positioned as shown in Figures 1 to 3.

6.5.2 Programme area reference point

The programme area reference point is determined by the intersection of a line parallel to the reference edge of the tape at a distance Y_0 from the reference edge and the centreline of track 0 in each ITI sector (see Figures 1 to 3).

The end of the preamble and beginning of SSA in the ITI sector shall be recorded at the programme area reference point, and the tolerance of dimension X_0 . The locations are shown in Figures 1 to 3; dimensions X_0 and Y_0 are specified in Tables 1 to 4. The relationship between sectors and contents of each sector is specified in Clause 7.

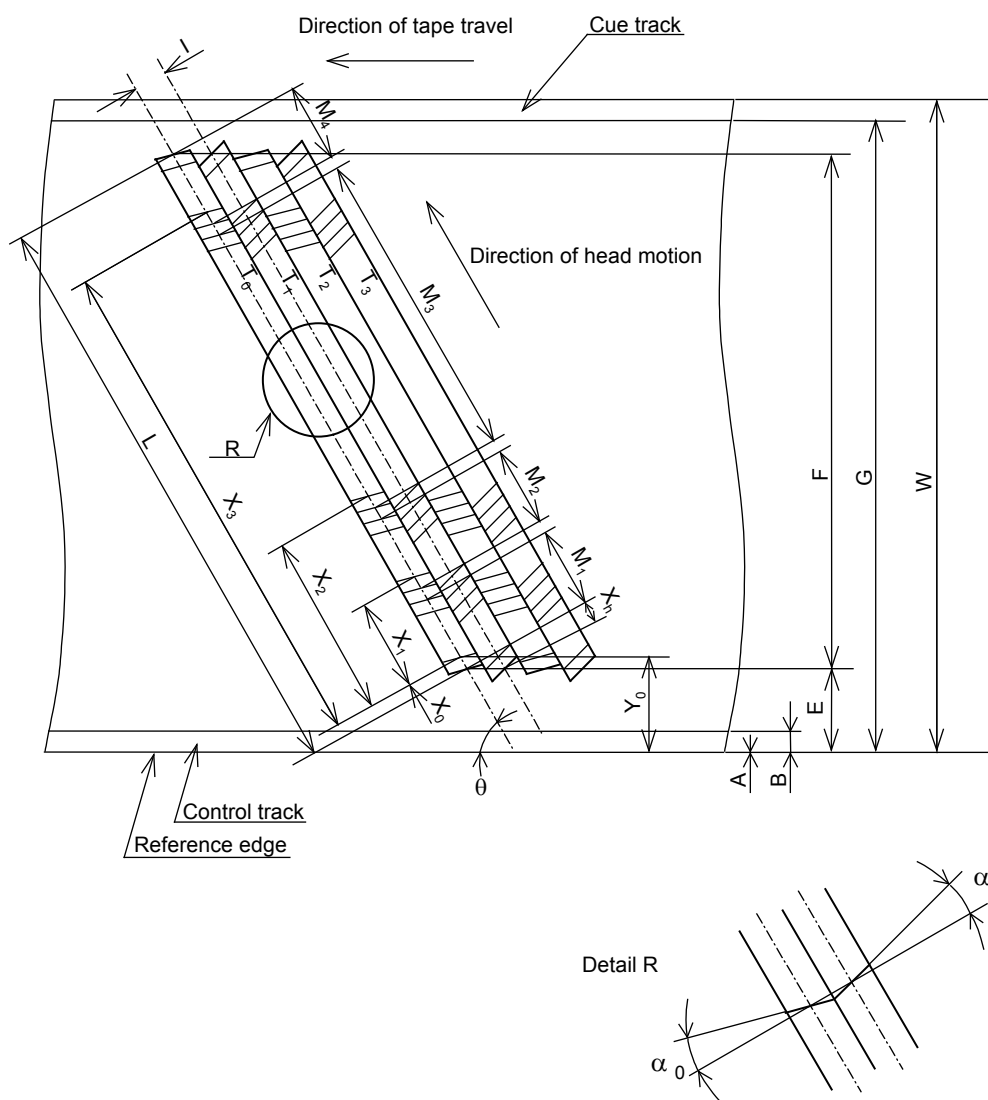


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NOTE 1 M_1 is an ITI sector.NOTE 2 M_2 is an audio sector.NOTE 3 M_3 is a video sector.NOTE 4 M_4 is a subcode sector.

NOTE 5 Tracks viewed from magnetic coating side.

NOTE 6 Dimension X_1 to X_3 are determined by the programme reference point as defined in Figure 3.**Figure 1 – Locations and dimensions of recorded tracks of 25 Mb/s format**



IEC 1859/05

NOTE 1 M_1 is an ITI sector.

NOTE 2 M_2 is an audio sector.

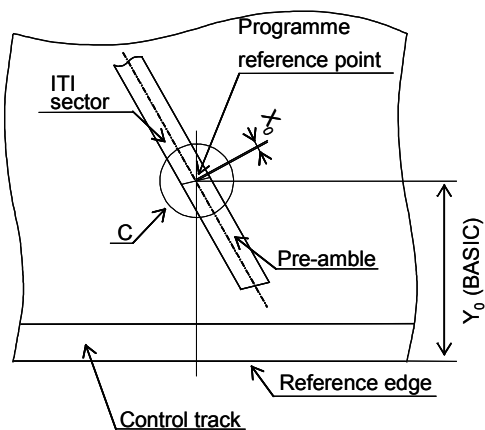
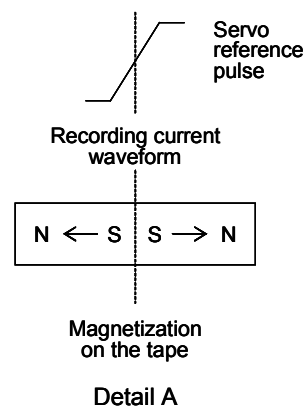
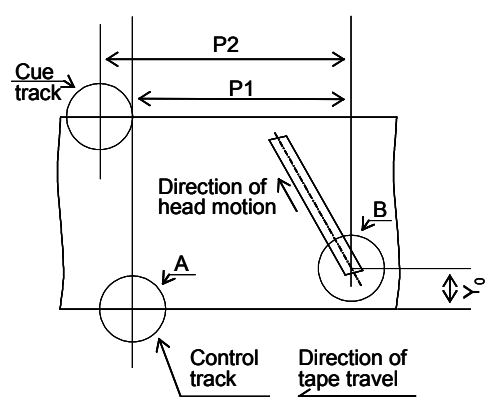
NOTE 3 M_3 is a video sector.

NOTE 4 M_4 is a subcode sector.

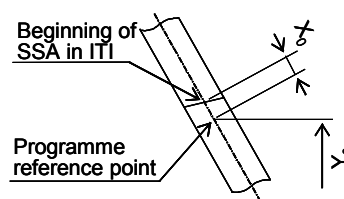
NOTE 5 Tracks viewed from magnetic coating side.

NOTE 6 Dimension X_1 to X_3 are determined by the programme reference point as defined in Figure 3.

Figure 2 – Locations and dimensions of recorded tracks of 50 Mb/s format



Detail B



Detail C

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Figure 3 – Location of cue and control track record

Table 1 – Record locations and dimensions (525/60 system of 25 Mb/s format)

Dimensions in millimetres

Dimensions		Nominal	Tolerance
A	Control track lower edge	0	Basic
B	Control track upper edge	0,400	$\pm 0,050$
E	Programme area lower edge	0,56	Derived
F	Programme area width	5,24	Derived
G	Cue track lower edge	6,000	$\pm 0,050$
I	Helical track pitch	0,018	Ref.
L	Total length of helical track	32,842	Derived
M_1	Length of ITI sector with preamble and post-amble	0,876	Derived
M_2	Length of audio sector with preamble and post-amble	2,810	Derived
M_3	Length of video sector with preamble and post-amble	27,548	Derived
M_4	Length of subcode sector with preamble and post-amble	0,906	Derived
P_1	Control track reference pulse to programme reference point (see Figure 3)	67,500	$\pm 0,030$
P_2	Cue signal, start of code word of cue to programme reference point (see Figure 3)	69,900	$\pm 0,300$
W	Tape width	6,350	$\pm 0,005$
X_0	Location of beginning of SSA in ITI sector	0	$\pm 0,050$
X_1	Location of start of audio data sync blocks	0,809	$\pm 0,050$
X_2	Location of start of video data sync blocks	3,790	$\pm 0,050$
X_3	Location of start of subcode data sync blocks	31,885	$\pm 0,050$
X_h	Head stagger and inline tolerance	0,111	$\pm 0,021$
Y_0	Programme track reference point	0,615	Basic
θ	Track angle	9,178 4	Basic
α_0	Azimuth angle (track 0)	19,97	$\pm 0,150^\circ$
α_1	Azimuth angle (track 1)	20,03	$\pm 0,150^\circ$

NOTE Measurements should be made under the conditions specified in 4.1. The measurements should be corrected to account for actual tape speed (see Figures C.1 and C.2).

Table 2 – Record locations and dimensions (625/50 system of 25 Mb/s format)*Dimensions in millimetres*

Dimensions		Nominal	Tolerance
A	Control track lower edge	0	Basic
B	Control track upper edge	0,400	$\pm 0,050$
E	Programme area lower edge	0,56	Derived
F	Programme area width	5,24	Derived
G	Cue track lower edge	6,000	$\pm 0,050$
I	Helical track pitch	0,018	Ref.
L	Total length of helical track	32,842	Derived
M_1	Length of ITI sector with preamble and post-amble	0,877	Derived
M_2	Length of audio sector with preamble and post-amble	2,813	Derived
M_3	Length of video sector with preamble and post-amble	27,576	Derived
M_4	Length of subcode sector with preamble and post-amble	0,877	Derived
P_1	Control track reference pulse to programme reference point (see Figure 3)	67,500	$\pm 0,030$
P_2	Cue signal, start of code word of cue to programme reference point (see Figure 3)	70,380	$\pm 0,300$
W	Tape width	6,350	$\pm 0,005$
X_0	Location of beginning of SSA in ITI sector	0	$\pm 0,050$
X_1	Location of start of audio data sync blocks	0,810	$\pm 0,050$
X_2	Location of start of video data sync blocks	3,793	$\pm 0,050$
X_3	Location of start of subcode data sync blocks	31,917	$\pm 0,050$
X_h	Head stagger and inline tolerance	0,111	$\pm 0,021$
Y_0	Programme track reference point	0,615	Basic
θ	Track angle	9,178 4°	Basic
α_0	Azimuth angle (track 0)	19,97°	$\pm 0,150^\circ$
α_1	Azimuth angle (track 1)	20,03°	$\pm 0,150^\circ$

NOTE Measurements should be made under the conditions specified in 4.1. The measurements should be corrected to account for actual tape speed (see Figures C.1 and C.2).

Table 3 – Record locations and dimensions (525/60 system of 50 Mb/s format)

Dimensions in millimetres

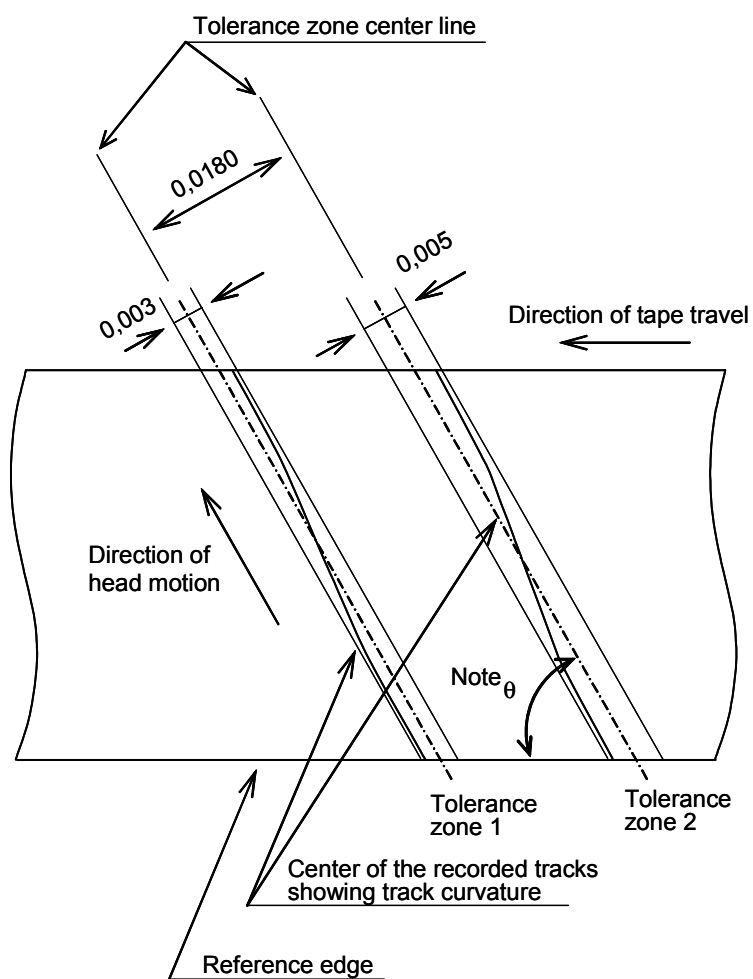
Dimensions		Nominal	Tolerance
A	Control track lower edge	0	Basic
B	Control track upper edge	0,400	$\pm 0,050$
E	Programme area lower edge	0,56	Derived
F	Programme area width	5,24	Derived
G	Cue track lower edge	6,000	$\pm 0,050$
I	Helical track pitch	0,018	Ref.
L	Total length of helical track	32,842	Derived
M_1	Length of ITI sector with preamble and post-amble	0,876	Derived
M_2	Length of audio sector with preamble and post-amble	2,810	Derived
M_3	Length of video sector with preamble and post-amble	27,548	Derived
M_4	Length of subcode sector with preamble and post-amble	0,906	Derived
P_1	Control track reference pulse to programme reference point (see Figure 3)	67,500	$\pm 0,030$
P_2	Cue signal, start of code word of cue to programme reference point (see Figure 3)	67,500	$\pm 0,300$
W	Tape width	6,350	$\pm 0,005$
X_0	Location of beginning of SSA in ITI sector	0	$\pm 0,050$
X_1	Location of start of audio data sync blocks	0,809	$\pm 0,050$
X_2	Location of start of video data sync blocks	3,790	$\pm 0,050$
X_3	Location of start of subcode data sync blocks	31,885	$\pm 0,050$
X_h	Head stagger and inline tolerance	0,111	$\pm 0,021$
Y_0	Programme track reference point	0,615	Basic
θ	Track angle	9,178 4	Basic
α_0	Azimuth angle (track 0, 2)	19,97	$\pm 0,150^\circ$
α_1	Azimuth angle (track 1, 3)	20,03	$\pm 0,150^\circ$

NOTE Measurements should be made under the conditions specified in 4.1. The measurements should be corrected to account for actual tape speed (see Figures C.1 and C.3).

Table 4 – Record locations and dimensions (625/50 system of 50 Mb/s format)*Dimensions in millimetres*

Dimensions		Nominal	Tolerance
A	Control track lower edge	0	Basic
B	Control track upper edge	0,400	$\pm 0,050$
E	Programme area lower edge	0,56	Derived
F	Programme area width	5,24	Derived
G	Cue track lower edge	6,000	$\pm 0,050$
I	Helical track pitch	0,018	Ref.
L	Total length of helical track	32,842	Derived
M_1	Length of ITI sector with preamble and post-amble	0,877	Derived
M_2	Length of audio sector with preamble and post-amble	2,813	Derived
M_3	Length of video sector with preamble and post-amble	27,576	Derived
M_4	Length of subcode sector with preamble and post-amble	0,877	Derived
P_z	Control track reference pulse to programme reference point (see Figure 3)	67,500	$\pm 0,030$
P_2	Cue signal, start of code word of cue to programme reference point (see Figure 3)	67,500	$\pm 0,300$
W	Tape width	6,350	$\pm 0,005$
X_0	Location of beginning of SSA in ITI sector	0	$\pm 0,050$
X_1	Location of start of audio data sync blocks	0,810	$\pm 0,050$
X_2	Location of start of video data sync blocks	3,793	$\pm 0,050$
X_3	Location of start of subcode data sync blocks	31,917	$\pm 0,050$
X_h	Head stagger and inline tolerance	0,111	$\pm 0,021$
Y_0	Programme track reference point	0,615	Basic
θ	Track angle	9,178 4	Basic
α_0	Azimuth angle (track 0, 2)	19,97	$\pm 0,150^\circ$
α_1	Azimuth angle (track 1, 3)	20,03	$\pm 0,150^\circ$

NOTE Measurements should be made under the conditions specified in 4.1. The measurements should be corrected to account for actual tape speed (see Figures C.1 and C.3).



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Dimensions in millimetres

NOTE $\theta = 9,178\ 4^\circ$.

Figure 4 – Locations and dimensions of tolerance zones of helical track record of 25 Mb/s format

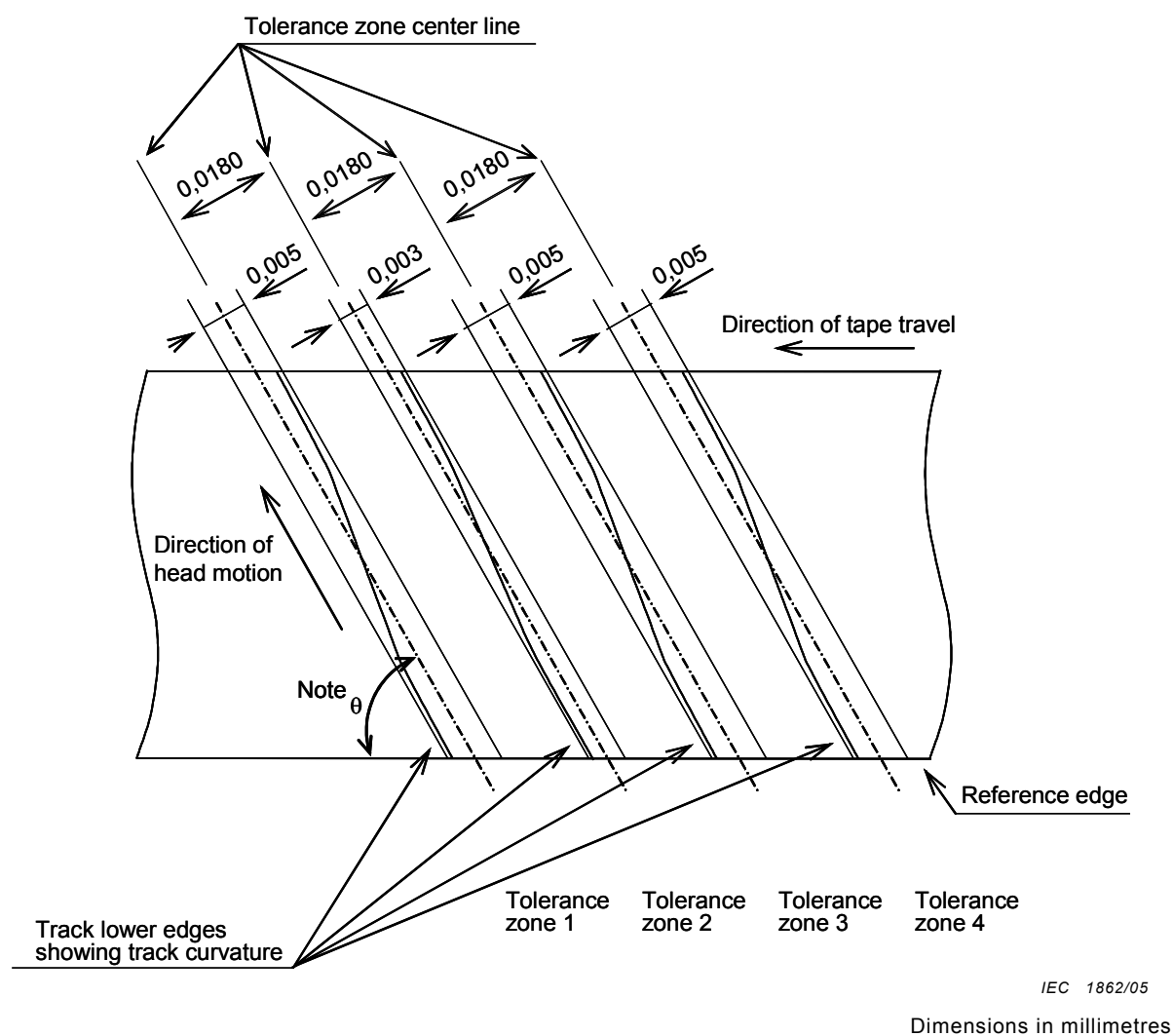


Figure 5 – Locations and dimensions of tolerance zones of helical track record of 50 Mb/s format

6.6 Gap azimuth

6.6.1 Cue and control track

The azimuth angle of the cue and control track head gaps used to produce longitudinal track records shall be perpendicular to these recorded tracks.

6.6.2 Helical track

The azimuth of the head gaps used for the helical track shall be inclined at angles α_0 and α_1 as specified in Tables 1 to 4 with respect to a line perpendicular to the helical track. For 25 Mb/s format, the azimuth of track No.0 for every field shall be oriented in a clockwise direction with respect to a line perpendicular to the helical track direction when viewed from the side of the tape containing the magnetic record. For 50 Mb/s format, the azimuth of tracks No. 0 and No. 2 for every field shall be oriented in a clockwise direction in the same manner.

6.6.3 Transport and scanner

The effective drum diameter, tape tension, helix angle, and tape speed taken together determine the track angle. Different methods of design and/or variations in drum diameter and tape tension can produce equivalent recordings for interchange purposes.

A possible configuration of the transport uses a scanner with an effective diameter of 21,700 mm. Scanner rotation is in the same direction as tape motion during record mode. In 25 Mb/s format, data are recorded by two heads each mounted 180° apart. Figure 6 shows a possible mechanical configuration of the scanner and the relationship between the longitudinal heads and the scanner. Table 5 shows the corresponding mechanical parameters.

In 50 Mb/s format, data are recorded by two pairs of heads each mounted 180° apart. Figure 7 shows a possible mechanical configuration of the scanner and the relationship between the longitudinal heads and the scanner. Table 6 shows the corresponding mechanical parameters.

Other mechanical configurations are allowed provided the same footprint of recorded information is produced on tape.

Table 5 – Parameters for a possible scanner design of 25 Mb/s format

Parameters	525/60 system	625/50 system
Scanner rotation speed (rpm)	9 000/1,001	9 000
Number of tracks per rotation	2	
Drum diameter (mm)	21,700	
Centre span tension (N)	0,09	
Helix angle (degrees)	9,150 0	
Effective wrap angle (degrees)	174	
Scanner circumferential speed (m/s)	10,182	10,192
Bit frequency f_b (Hz)	41 850 000	
H_1, H_2 overwrap head entrance (degrees)	5,0	
H_1, H_2 overwrap head exit (degrees)	6,0	
Maximum tip projection (μm)	20	
Record head track width (μm)	18	

Table 6 – Parameters for a possible scanner design of 50 Mb/s format

Parameters	525/60 system	625/50 system
Scanner rotation speed (rpm)	9 000/1,001	9 000
Number of tracks per rotation	4	
Drum diameter (mm)	21,700	
Centre span tension (N)	0,09	
Helix angle (degrees)	9,119 7	
Effective wrap angle (degrees)	174,6	
Scanner circumferential speed (m/s)	10,149	10,159
Bit frequency f_b (Hz)	41 715 000	
H_1, H_3 overwrap head entrance (degrees)	4,7	
H_1, H_3 overwrap head exit (degrees)	5,7	
Maximum tip projection (μm)	20	
Record head track width (μm)	18	

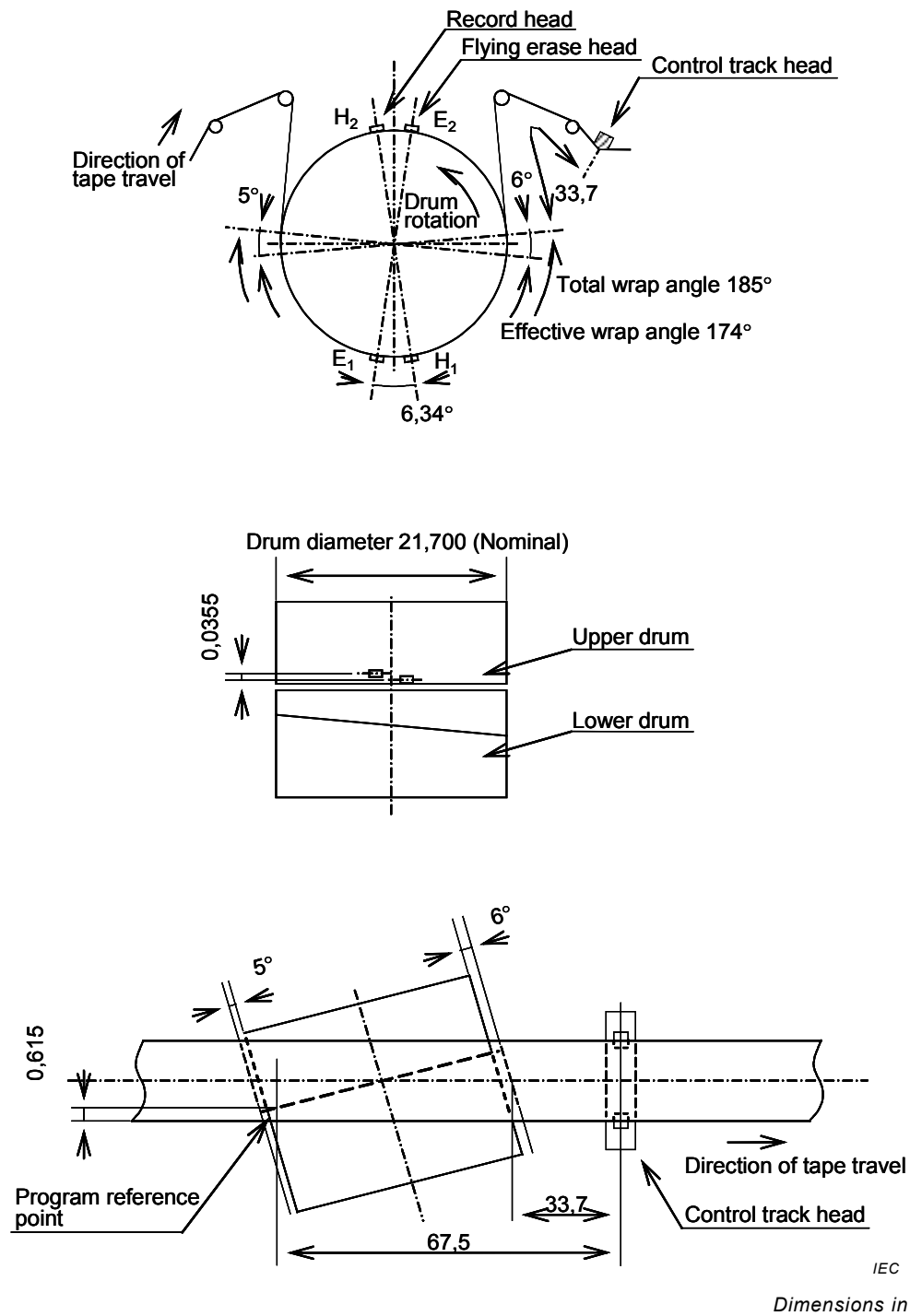


Figure 6 – A possible scanner configuration and tape wrap of 25 Mb/s format

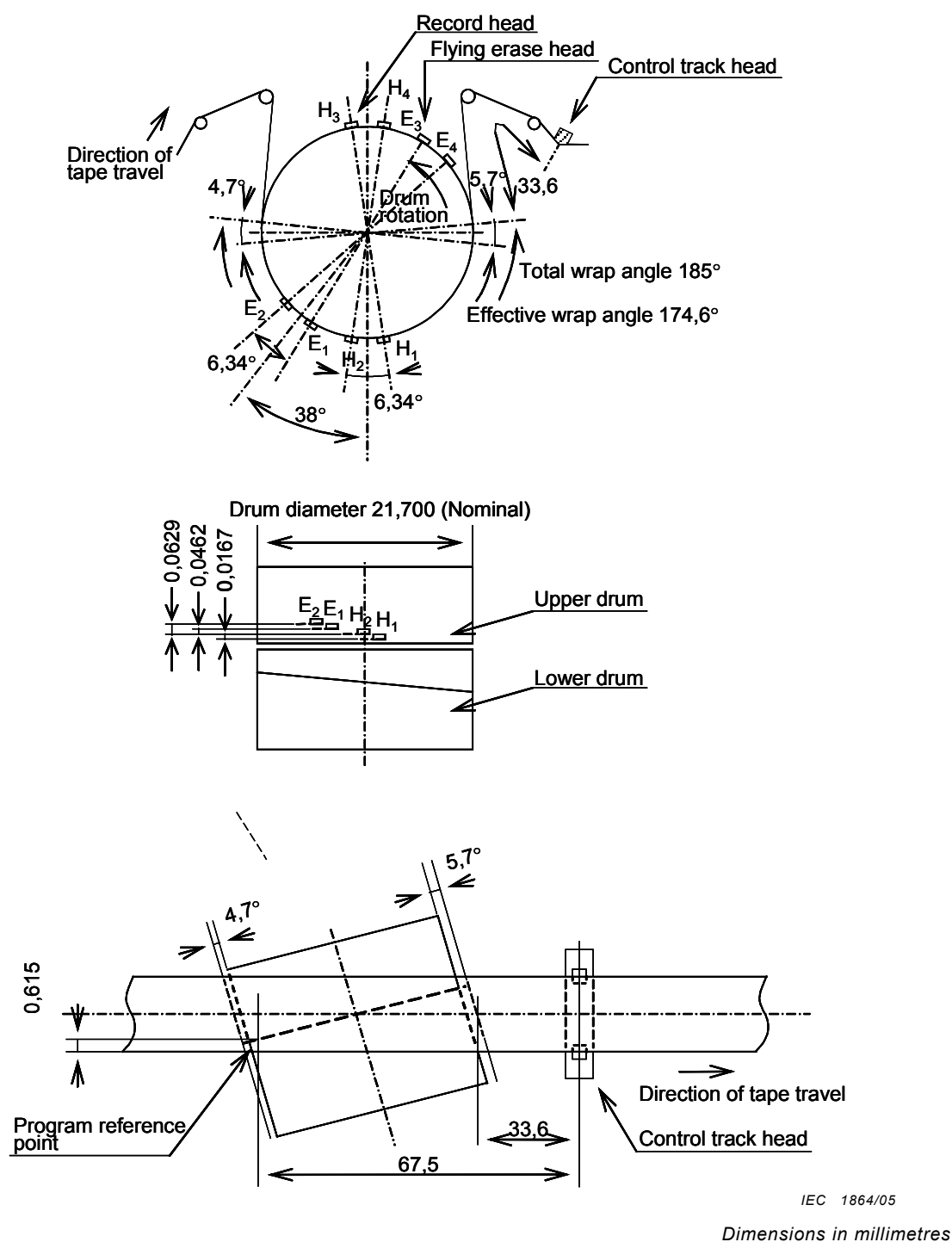


Figure 7 – A possible scanner configuration and tape wrap of 50 Mb/s format

7 Programme track data

7.1 General

7.1.1 Overview

For the 25 Mb/s format, each television frame is recorded on 10 tracks for the 525/60 system or 12 tracks for the 625/50 system. For the 50 Mb/s format, each television frame is recorded on 20 tracks for the 525/60 system or 24 tracks for the 625/50 system. The helical tracks contain digital data from the ITI sector, video sector, audio sector, and subcode sector.

The ITI sector contains the start sync and track information. The subcode sector contains the time and control code data and it may also include other optional data.

Figure 8 shows a typical block diagram of the recording circuit. All edit gaps between sectors accommodate timing errors during editing. Figure 9 shows the arrangement of the ITI sector, video and audio sectors, and the subcode sector on the tape.

For the generation of low frequency tracking information, the helical data stream is converted by 24/25 modulation to obtain the following conditions:

- Track F_0 : Attenuation of f_1 and f_2 frequency components by at least 9 dB;
- Track F_1 : Generation of f_1 component of at least 16 dB, but not more than 19 dB;
- Track F_2 : Generation of f_2 component of at least 16 dB, but not more than 19 dB

where

$$f_1 = f_b / 90 \text{ (Hz)}$$

$$f_2 = f_b / 60 \text{ (Hz)}$$

f_b = bit frequency: the frequency whose period is a time interval of one channel bit (Hz).

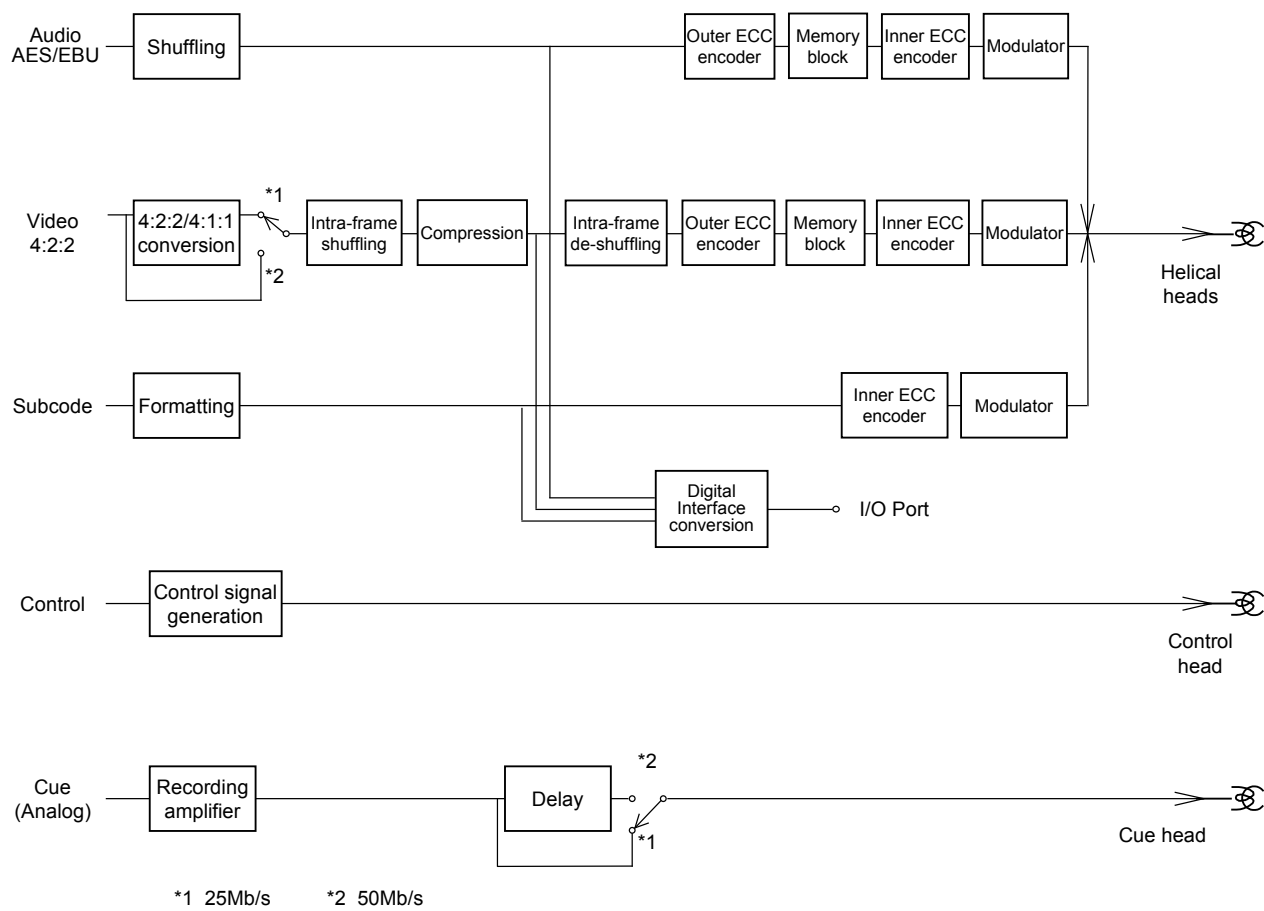
Tracks are recorded in the repeated cycle of $F_0 - F_1 - F_0 - F_2$ sequence.

In the 525/60 system for the 25 Mb/s format, PF shows the frame information for the second track of each frame. Figures 10 and 11 and Tables 7 and 8 show the arrangement of the pilot signals of the 25 Mb/s format. Figures 12 and 13 and Tables 9 and 10 show the arrangement of the pilot signals of the 50 Mb/s format. The frequency characteristics and the recorded level of the low frequency pilot signals shall be chosen in accordance with Figure 14.

The recommended frequency characteristic of the F_0 track is specified in Annex D.

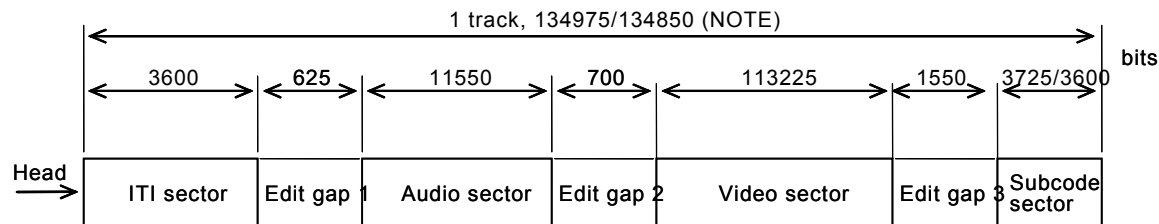
7.1.2 Labelling convention

The most significant bit is written on the left and first recorded to tape. The lowest numbered byte is shown at the left/top and is the first encountered in the input data stream. Byte values are expressed in hexadecimal notation unless otherwise noted. An h subscript indicates a hexadecimal value.



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Figure 8 – Possible recording system configuration with digital interface port (informative)



NOTE 525/60 system / 625/50 system

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Figure 9 – Sector arrangement on helical track

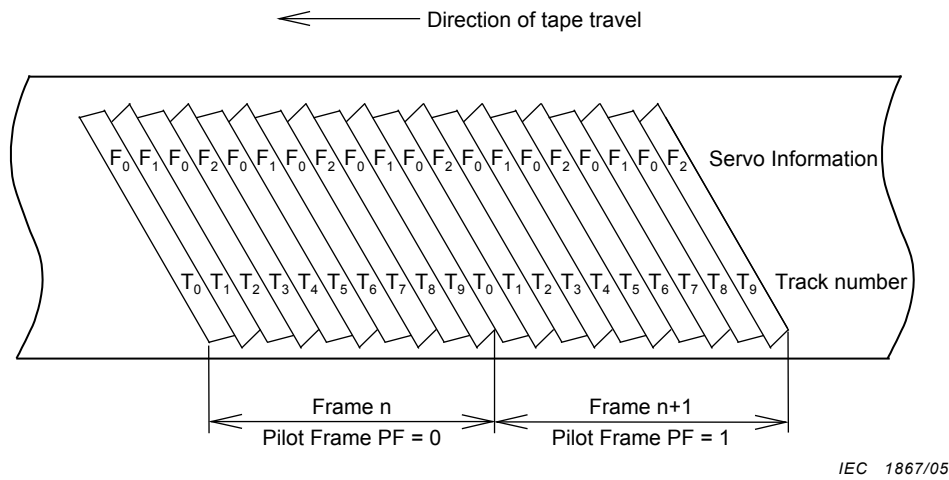


Figure 10 – Frames and tracks (525/60 system of 25 Mb/s format)

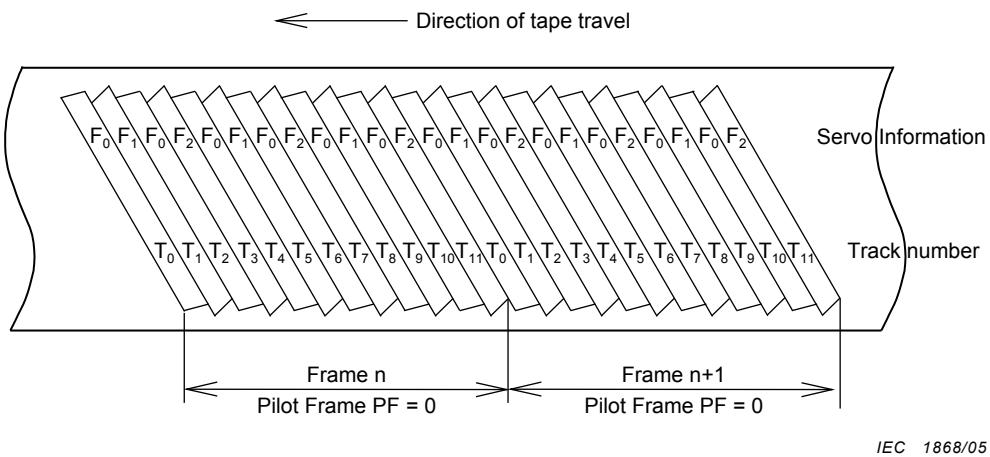


Figure 11 – Frames and tracks (625/50 system of 25 Mb/s format)

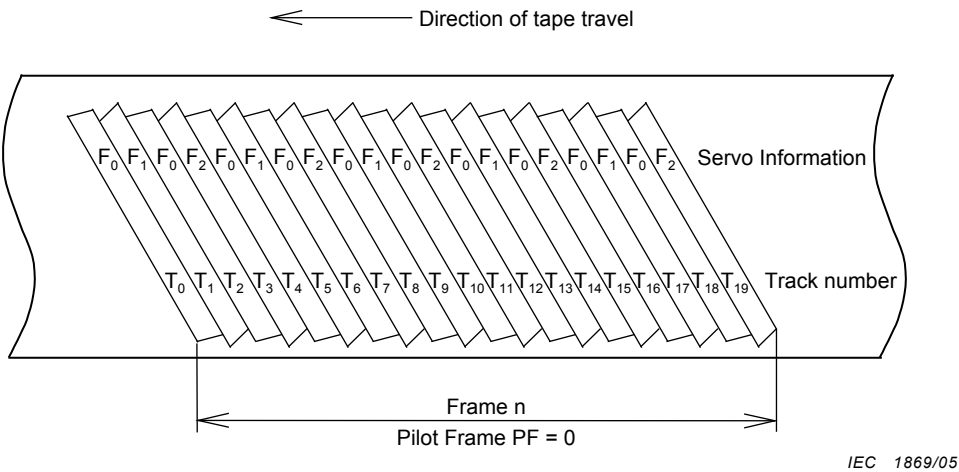


Figure 12 – A frame and tracks (525/60 system of 50 Mb/s format)

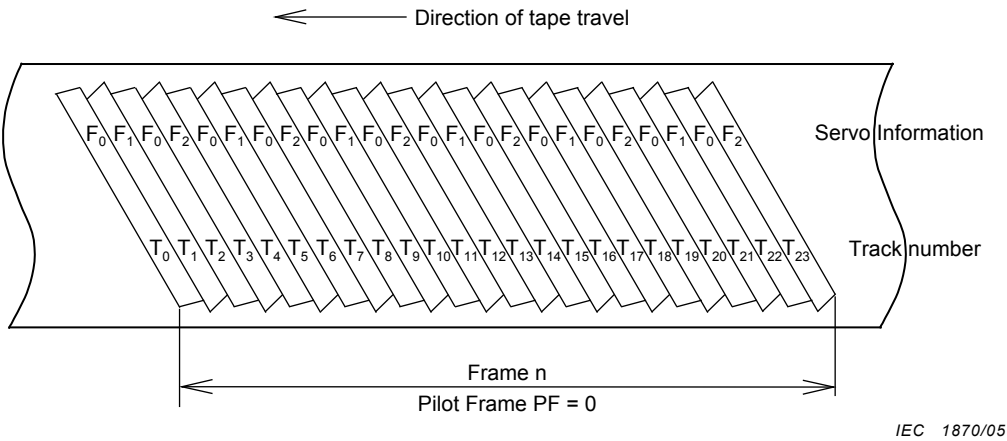


Figure 13 – A frame and tracks (625/50 system of 50 Mb/s format)

Table 7 – Frames and servo information (525/60 system of 25 Mb/s format)

Frame	Track number	Servo information	Pilot frame PF
Frame n	T_0	F_0	0
	T_1	F_1	0
	T_2	F_0	0
	T_3	F_2	0
	T_4	F_0	0
	T_5	F_1	0
	T_6	F_0	0
	T_7	F_2	0
	T_8	F_0	0
	T_9	F_1	0
Frame $n+1$	T_0	F_0	1
	T_1	F_2	1
	T_2	F_0	1
	T_3	F_1	1
	T_4	F_0	1
	T_5	F_2	1
	T_6	F_0	1
	T_7	F_1	1
	T_8	F_0	1
	T_9	F_2	1

Table 8 – Frames and servo information (625/50 system of 25 Mb/s format)

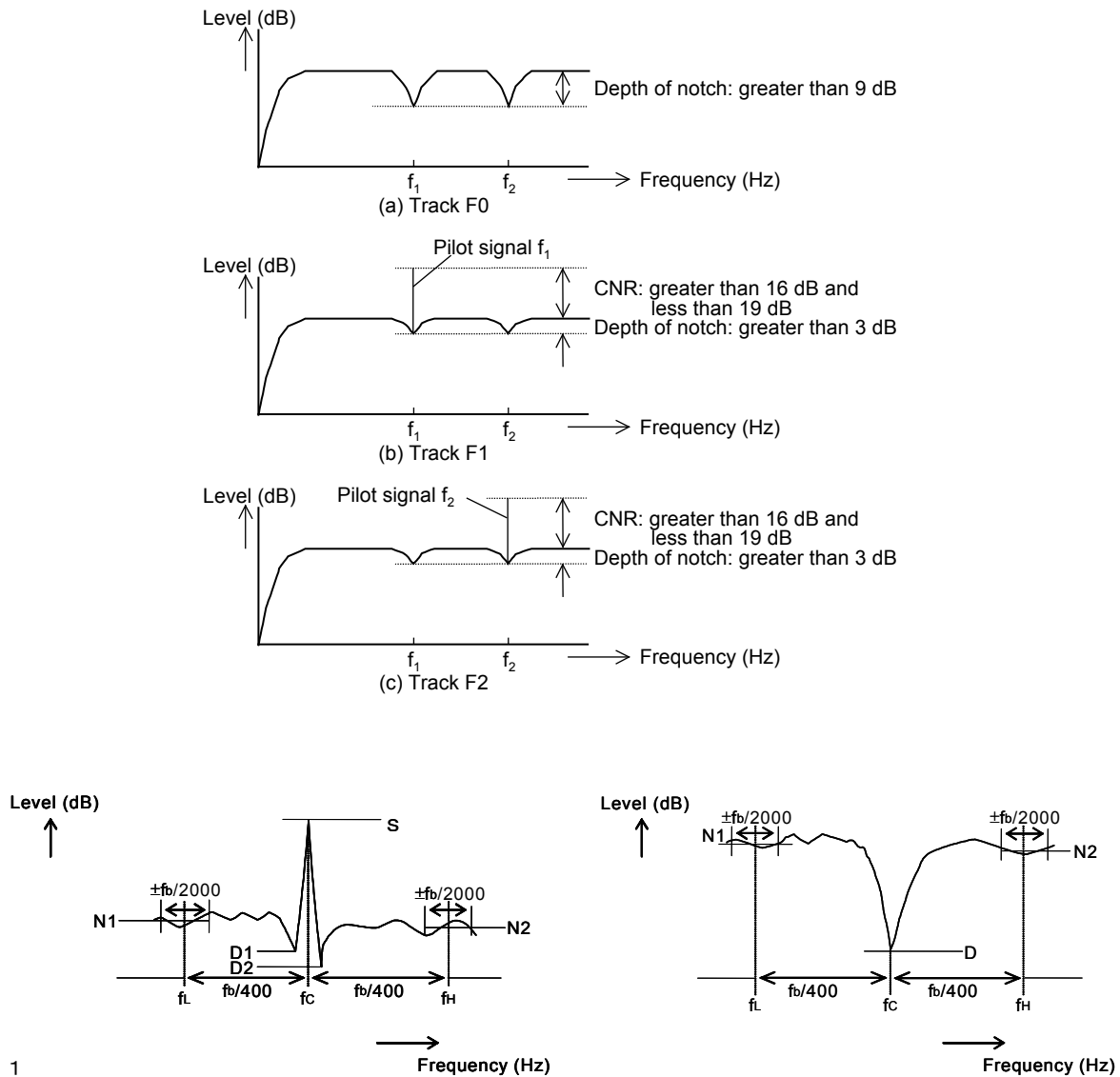
Frame	Track number	Servo information	Pilot frame PF
Frame n	T_0	F_0	0
	T_1	F_1	0
	T_2	F_0	0
	T_3	F_2	0
	T_4	F_0	0
	T_5	F_1	0
	T_6	F_0	0
	T_7	F_2	0
	T_8	F_0	0
	T_9	F_1	0
	T_{10}	F_0	0
	T_{11}	F_2	0
Frame $n+1$	T_0	F_0	0
	T_1	F_1	0
	T_2	F_0	0
	T_3	F_2	0
	T_4	F_0	0
	T_5	F_1	0
	T_6	F_0	0
	T_7	F_2	0
	T_8	F_0	0
	T_9	F_1	0
	T_{10}	F_0	0
	T_{11}	F_2	0

Table 9 – A frame and servo information (525/60 system of 50 Mb/s format)

Frame	Track number	Servo information	Pilot frame PF
Frame <i>n</i>	T ₀	F ₀	0
	T ₁	F ₁	0
	T ₂	F ₀	0
	T ₃	F ₂	0
	T ₄	F ₀	0
	T ₅	F ₁	0
	T ₆	F ₀	0
	T ₇	F ₂	0
	T ₈	F ₀	0
	T ₉	F ₁	0
	T ₁₀	F ₀	0
	T ₁₁	F ₂	0
	T ₁₂	F ₀	0
	T ₁₃	F ₁	0
	T ₁₄	F ₀	0
	T ₁₅	F ₂	0
	T ₁₆	F ₀	0
	T ₁₇	F ₁	0
	T ₁₈	F ₀	0
	T ₁₉	F ₂	0

Table 10 – A frame and servo information (625/50 system of 50 Mb/s format)

Frame	Track number	Servo information	Pilot frame PF
Frame <i>n</i>	T ₀	F ₀	0
	T ₁	F ₁	0
	T ₂	F ₀	0
	T ₃	F ₂	0
	T ₄	F ₀	0
	T ₅	F ₁	0
	T ₆	F ₀	0
	T ₇	F ₂	0
	T ₈	F ₀	0
	T ₉	F ₁	0
	T ₁₀	F ₀	0
	T ₁₁	F ₂	0
	T ₁₂	F ₀	0
	T ₁₃	F ₁	0
	T ₁₄	F ₀	0
	T ₁₅	F ₂	0
	T ₁₆	F ₀	0
	T ₁₇	F ₁	0
	T ₁₈	F ₀	0
	T ₁₉	F ₂	0
	T ₂₀	F ₀	0
	T ₂₁	F ₁	0
	T ₂₂	F ₀	0
	T ₂₃	F ₂	0



NOTE 1 $f_1 = f_b / 90$ (Hz)

$f_2 = f_b / 60$ (Hz)

f_b is the frequency whose period is a time interval of one channel bit(Hz)

Resolution bandwidth $= f_b / 20925$ (Hz)

Data is obtained by integration over 30 repeated cycles

NOTE 2 $CNR = [S - (N_1 + N_2) / 2]$ (dB)

Depth of notch with peak $= [(N_1 + N_2) / 2 - (D_1 + D_2) / 2]$ (dB)

Depth of notch without peak $= [(N_1 + N_2) / 2 - D]$ (dB)

N_1 is defined as an average value over $f_L \pm f_b / 2000$ (dB)

N_2 is defined as an average value over $f_H \pm f_b / 2000$ (dB)

f_L is defined as $f_c - f_b / 400$ (Hz)

f_H is defined as $f_c + f_b / 400$ (Hz)

f_c means a peak or notch frequency (Hz)

Figure 14 – Frequency characteristics of tracks

7.1.3 Signal processing

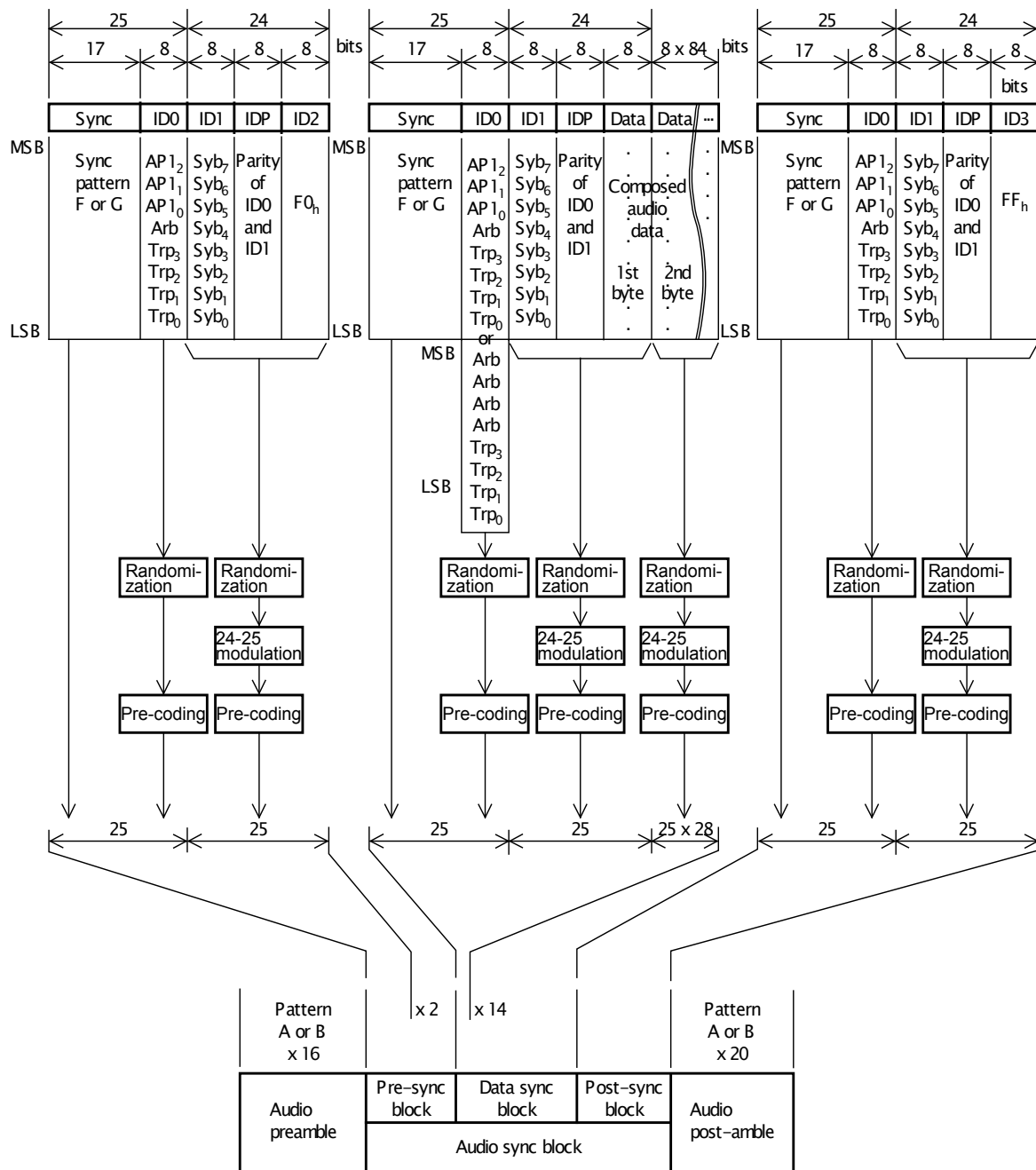
Figures 15 to 17 show the processing of modulation related to the recorded signals. The programme track data with the exception of ID0 shall be processed through three operations as shown below:

- randomization;
- 24-25 modulation;
- pre-coding.

The programme track data of ID0 shall be processed through two operations as shown below:

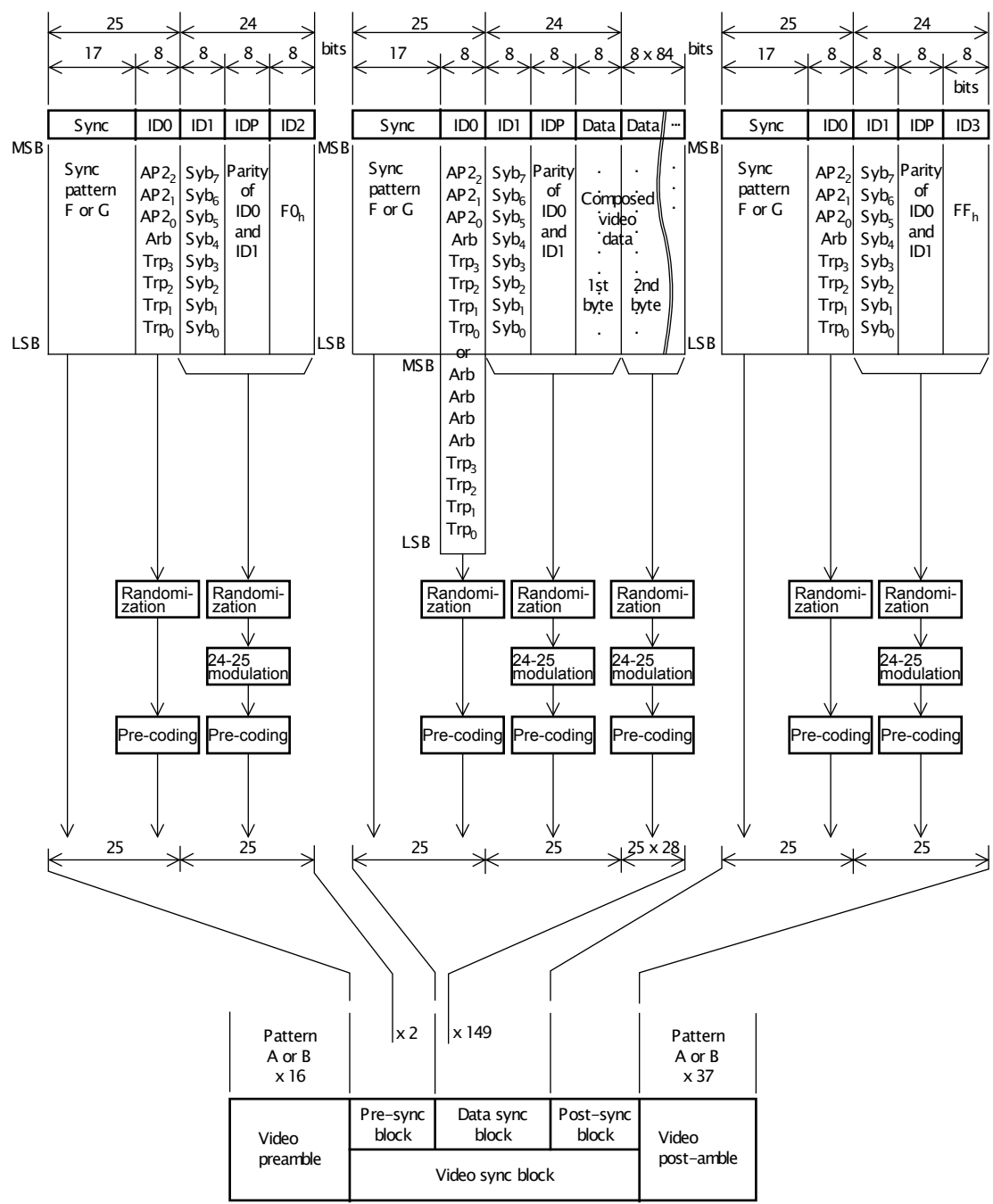
- randomization;
- pre-coding.

Figure 18 shows a possible block diagram of the process.



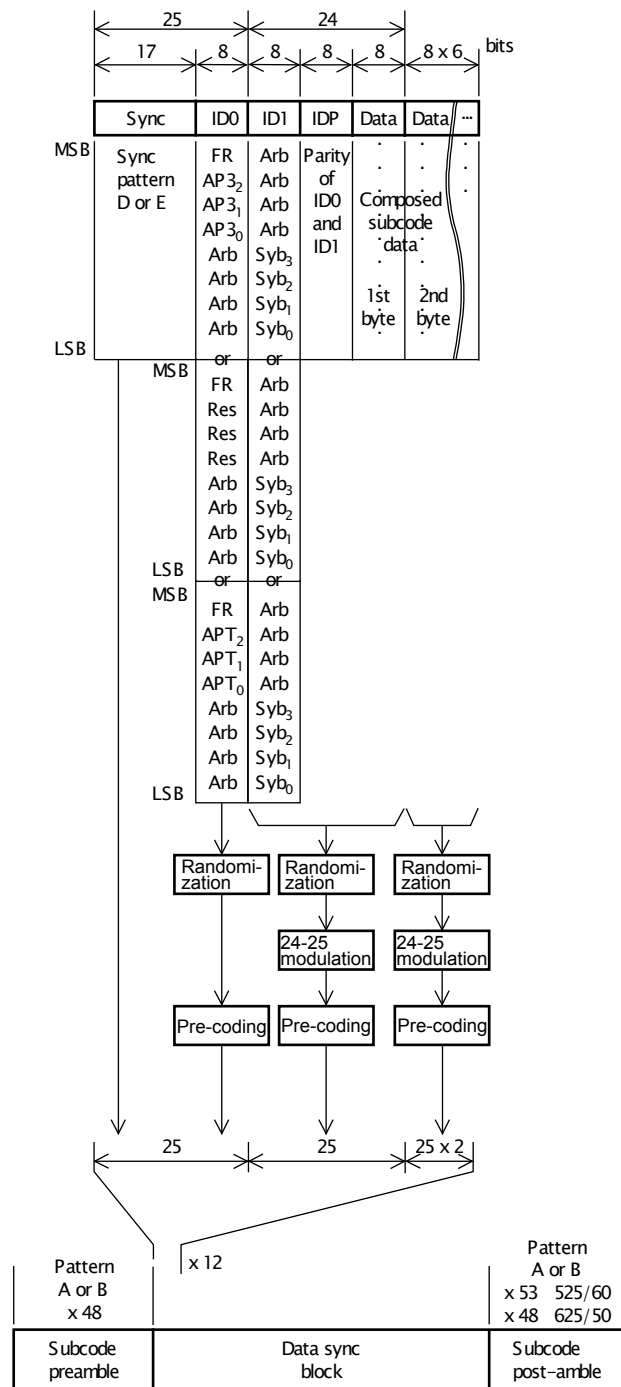
IEC 1872/05

Figure 15 – Modulation for audio sector



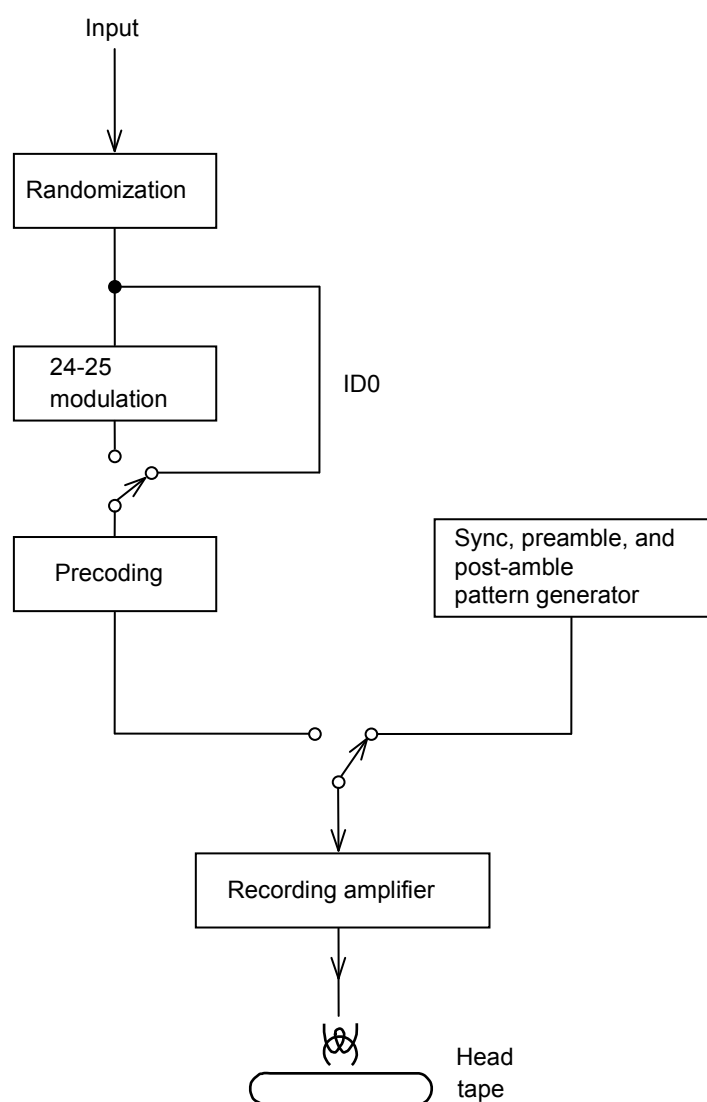
IEC 1873/05

Figure 16 – Modulation for video sector



IEC 1874/05

Figure 17 – Modulation for subcode sector



IEC 1875/05

Figure 18 – Possible block diagram for signal processing

7.1.3.1 Randomization

Bit streams of data except sync patterns shall be randomized. The randomizing is equivalent to performing the exclusive-or operation between the serial data stream and the serial stream generated by the polynomial function below:

$$X^7 + X^3 + 1$$

where X^i are place-keeping variables in GF(2), the binary field. The first term is the most significant and the first to enter the division computation. The randomizing is reset at ID0.

The randomization limits the run length of the same binary value.

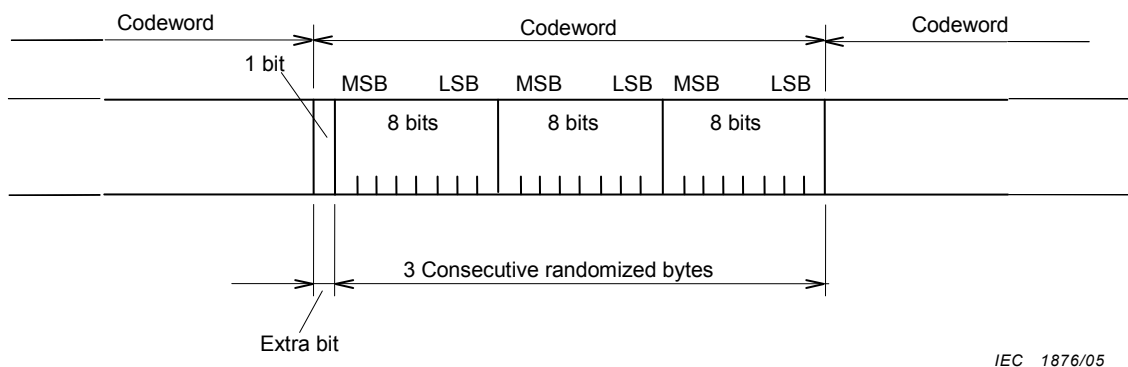
7.1.3.2 24-25 modulation

The 24-25 modulation is applied to the randomized data bit stream. An extra bit is inserted into the bit stream at the beginning of three consecutive randomized bytes, as shown in Figure 19. The modulation output, 25 bits data, is referred to as a code word. The following criteria are used to insert a bit 1 or 0 at the beginning of each three consecutive bytes:

- if the run length of 1s or 0s, including the extra bit to be inserted at the junction, is shorter than 9, a bit generating the required pilot frequency is inserted;
- if the run length of 1s or 0s, including the extra bit to be inserted at the junction, exceeds 10, a bit which breaks the run continuation is inserted;
- including the extra bit to be inserted at the junction, and the run length of both 1s and 0s exceeds 10, a bit generating the required pilot frequency is inserted.

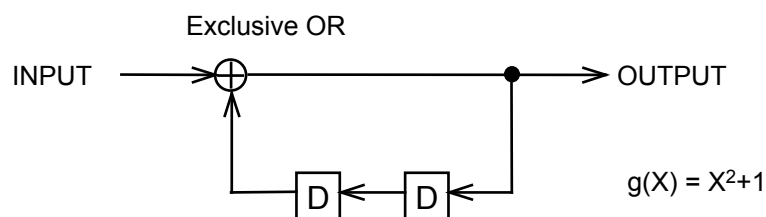
7.1.3.3 Pre-coding

The modulated bit stream shall be converted to interleaved NRZI as shown in Figures 15 to 17 and Figure 20.



IEC 1876/05

Figure 19 – Bit stream before interleaved NRZI modulation



IEC 1877/05

Figure 20 – Pre-coding

7.1.4 Magnetization

7.1.4.1 Polarity

The recorder shall operate in reproduction without regard to the polarity of the recorded flux on the helical tracks.

7.1.4.2 Record equalization

The record current shall generate a record head gap flux level that is constant within ± 1 dB between f_1 and $f_b/2$.

7.1.4.3 Record current level

The optimum record current is 6 dB higher than the lower side of the current value producing 1 dB below the maximum playback output at $f_b/2$.

7.2 Insert and track information (ITI) sector

7.2.1 Structure

The ITI sector is located at the entrance side of each track for accurate placement of the reproducing

head. The ITI sector, after initial recording, is not replaced in an editing operation.

The ITI sector contains the following elements:

- ITI preamble;
- Start sync area (SSA);
- Track information area (TIA);
- ITI post-amble.

Figure 21 shows the structure of the ITI sector.

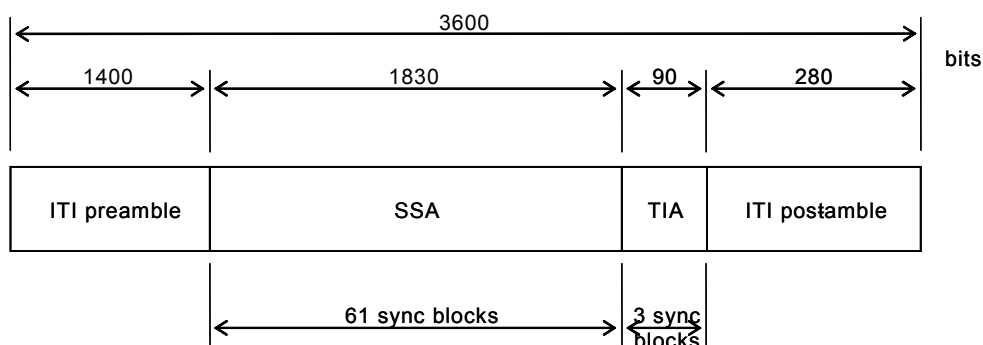
7.2.2 ITI preamble

The bit stream of the ITI preamble before the recording shall be defined as in Tables 11 to 13 in accordance with the low frequency appropriate pilot tone signal for each track. The length of the ITI preamble shall be 1400 bits as recorded on tape.

7.2.3 Start sync area (SSA)

SSA consists of 61 sync blocks and each sync block consists of 30 bits. Every start-sync block has a number which indicates the position of the sync block from the beginning of the SSA from zero.

The bit stream of the SSA after the modulation shall be as defined in Tables 14 to 16 in accordance with the low frequency pilot signals. The length of the SSA shall be 1830 bits as recorded on tape.



NOTE Each sync block has 30 bits.

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Figure 21 – Structure of ITI sector

Table 11 – Bit stream of ITI preamble for servo information F_0

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	1000101110	40	1000101110	80	1000101110	120	1000101110
1	1000101110	41	1000101110	81	1000101110	121	1000101110
2	1000101110	42	1000101110	82	1000101110	122	1000101110
3	1000101110	43	1000101110	83	1000101110	123	1000101110
4	1000101110	44	1000101110	84	1000101110	124	1000101110
5	1000101110	45	1000101110	85	1000101110	125	1000101110
6	1000101110	46	1000101110	86	1000101110	126	1000101110
7	1000101110	47	1000101110	87	1000101110	127	1000101110
8	1000101110	48	1000101110	88	1000101110	128	1000101110
9	1000101110	49	1000101110	89	1000101110	129	1000101110
10	1000101110	50	1000101110	90	1000101110	130	1000101110
11	1000101110	51	1000101110	91	1000101110	131	1000101110
12	1000101110	52	1000101110	92	1000101110	132	1000101110
13	1000101110	53	1000101110	93	1000101110	133	1000101110
14	1000101110	54	1000101110	94	1000101110	134	1000101110
15	1000101110	55	1000101110	95	1000101110	135	1000101110
16	1000101110	56	1000101110	96	1000101110	136	1000101110
17	1000101110	57	1000101110	97	1000101110	137	1000101110
18	1000101110	58	1000101110	98	1000101110	138	1000101110
19	1000101110	59	1000101110	99	1000101110	139	1000101110
20	1000101110	60	1000101110	100	1000101110		
21	1000101110	61	1000101110	101	1000101110		
22	1000101110	62	1000101110	102	1000101110		
23	1000101110	63	1000101110	103	1000101110		
24	1000101110	64	1000101110	104	1000101110		
25	1000101110	65	1000101110	105	1000101110		
26	1000101110	66	1000101110	106	1000101110		
27	1000101110	67	1000101110	107	1000101110		
28	1000101110	68	1000101110	108	1000101110		
29	1000101110	69	1000101110	109	1000101110		
30	1000101110	70	1000101110	110	1000101110		
31	1000101110	71	1000101110	111	1000101110		
32	1000101110	72	1000101110	112	1000101110		
33	1000101110	73	1000101110	113	1000101110		
34	1000101110	74	1000101110	114	1000101110		
35	1000101110	75	1000101110	115	1000101110		
36	1000101110	76	1000101110	116	1000101110		
37	1000101110	77	1000101110	117	1000101110		
38	1000101110	78	1000101110	118	1000101110		
39	1000101110	79	1000101110	119	1000101110		

Table 12 – Bit stream of ITI preamble for servo information F_1

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	1101110001	40	1000101110	80	0010001110	120	1101110001
1	1101110001	41	0010001110	81	1101110001	121	1000101110
2	1101110001	42	0010001110	82	1101110001	122	0010001110
3	1101110001	43	0010001110	83	1101110001	123	0010001110
4	1000101110	44	0010001110	84	1101110001	124	0010001110
5	0010001110	45	1101110001	85	1000101110	125	0010001110
6	0010001110	46	1101110001	86	0010001110	126	1101110001
7	0010001110	47	1101110001	87	0010001110	127	1101110001
8	0010001110	48	1101110001	88	0010001110	128	1101110001
9	1101110001	49	1000101110	89	0010001110	129	1101110001
10	1101110001	50	0010001110	90	1101110001	130	1000101110
11	1101110001	51	0010001110	91	1101110001	131	0010001110
12	1101110001	52	0010001110	92	1101110001	132	0010001110
13	1000101110	53	0010001110	93	1101110001	133	0010001110
14	0010001110	54	1101110001	94	1000101110	134	0010001110
15	0010001110	55	1101110001	95	0010001110	135	1101110001
16	0010001110	56	1101110001	96	0010001110	136	1101110001
17	0010001110	57	1101110001	97	0010001110	137	1101110001
18	1101110001	58	1000101110	98	0010001110	138	1101110001
19	1101110001	59	0010001110	99	1101110001	139	1000101110
20	1101110001	60	0010001110	100	1101110001		
21	1101110001	61	0010001110	101	1101110001		
22	1000101110	62	0010001110	102	1101110001		
23	0010001110	63	1101110001	103	1000101110		
24	0010001110	64	1101110001	104	0010001110		
25	0010001110	65	1101110001	105	0010001110		
26	0010001110	66	1101110001	106	0010001110		
27	1101110001	67	1000101110	107	0010001110		
28	1101110001	68	0010001110	108	1101110001		
29	1101110001	69	0010001110	109	1101110001		
30	1101110001	70	0010001110	110	1101110001		
31	1000101110	71	0010001110	111	1101110001		
32	0010001110	72	1101110001	112	1000101110		
33	0010001110	73	1101110001	113	0010001110		
34	0010001110	74	1101110001	114	0010001110		
35	0010001110	75	1101110001	115	0010001110		
36	1101110001	76	1000101110	116	0010001110		
37	1101110001	77	0010001110	117	1101110001		
38	1101110001	78	0010001110	118	1101110001		
39	1101110001	79	0010001110	119	1101110001		

Table 13 – Bit stream of ITI preamble for servo information F₂

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	1101110001	40	0010001110	80	1101110001	120	1101110001
1	1101110001	41	0010001110	81	0010001110	121	1101110001
2	1101110001	42	1101110001	82	0010001110	122	1101110001
3	0010001110	43	1101110001	83	0010001110	123	0010001110
4	0010001110	44	1101110001	84	1101110001	124	0010001110
5	0010001110	45	0010001110	85	1101110001	125	0010001110
6	1101110001	46	0010001110	86	1101110001	126	1101110001
7	1101110001	47	0010001110	87	0010001110	127	1101110001
8	1101110001	48	1101110001	88	0010001110	128	1101110001
9	0010001110	49	1101110001	89	0010001110	129	0010001110
10	0010001110	50	1101110001	90	1101110001	130	0010001110
11	0010001110	51	0010001110	91	1101110001	131	0010001110
12	1101110001	52	0010001110	92	1101110001	132	1101110001
13	1101110001	53	0010001110	93	0010001110	133	1101110001
14	1101110001	54	1101110001	94	0010001110	134	1101110001
15	0010001110	55	1101110001	95	0010001110	135	0010001110
16	0010001110	56	1101110001	96	1101110001	136	0010001110
17	0010001110	57	0010001110	97	1101110001	137	0010001110
18	1101110001	58	0010001110	98	1101110001	138	1101110001
19	1101110001	59	0010001110	99	0010001110	139	1101110001
20	1101110001	60	1101110001	100	0010001110		
21	0010001110	61	1101110001	101	0010001110		
22	0010001110	62	1101110001	102	1101110001		
23	0010001110	63	0010001110	103	1101110001		
24	1101110001	64	0010001110	104	1101110001		
25	1101110001	65	0010001110	105	0010001110		
26	1101110001	66	1101110001	106	0010001110		
27	0010001110	67	1101110001	107	0010001110		
28	0010001110	68	1101110001	108	1101110001		
29	0010001110	69	0010001110	109	1101110001		
30	1101110001	70	0010001110	110	1101110001		
31	1101110001	71	0010001110	111	0010001110		
32	1101110001	72	1101110001	112	0010001110		
33	0010001110	73	1101110001	113	0010001110		
34	0010001110	74	1101110001	114	1101110001		
35	0010001110	75	0010001110	115	1101110001		
36	1101110001	76	0010001110	116	1101110001		
37	1101110001	77	0010001110	117	0010001110		
38	1101110001	78	1101110001	118	0010001110		
39	0010001110	79	1101110001	119	0010001110		

Table 14 – Bit stream of SSA for servo information F₀

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	0010011101	50	0101010101	100	0110101001	150	0010011101
1	0101010101	51	0010011101	101	0101011001	151	0110010101
2	0101010101	52	0101101001	102	0010011101	152	0101101001
3	0010011101	53	0101011001	103	0110101001	153	0010011101
4	0101010101	54	0010011101	104	0101101001	154	0110010101
5	0101011001	55	0101101001	105	0010011101	155	0101100101
6	0010011101	56	0101101001	106	0110101001	156	0010011101
7	0101010101	57	0010011101	107	0101100101	157	0110010101
8	0101101001	58	0101101001	108	0010011101	158	0110101001
9	0010011101	59	0101100101	109	0110101001	159	0010011101
10	0101010101	60	0010011101	110	0110101001	160	0110010101
11	0101100101	61	0101101001	111	0010011101	161	0110100101
12	0010011101	62	0110101001	112	0110101001	162	0010011101
13	0101010101	63	0010011101	113	0110100101	163	0110010101
14	0110101001	64	0101101001	114	0010011101	164	0110010101
15	0010011101	65	0110100101	115	0110101001	165	0010011101
16	0101010101	66	0010011101	116	0110010101	166	0110010101
17	0110100101	67	0101101001	117	0010011101	167	0110011001
18	0010011101	68	0110010101	118	0110101001	168	0010011101
19	0101010101	69	0010011101	119	0110011001	169	0110011001
20	0110010101	70	0101101001	120	0010011101	170	0101010101
21	0010011101	71	0110011001	121	0110100101	171	0010011101
22	0101010101	72	0010011101	122	0101010101	172	0110011001
23	0110011001	73	0101100101	123	0010011101	173	0101011001
24	0010011101	74	0101010101	124	0110100101	174	0010011101
25	0101011001	75	0010011101	125	0101011001	175	0110011001
26	0101010101	76	0101100101	126	0010011101	176	0101101001
27	0010011101	77	0101011001	127	0110100101	177	0010011101
28	0101011001	78	0010011101	128	0101101001	178	0110011001
29	0101011001	79	0101100101	129	0010011101	179	0101100101
30	0010011101	80	0101101001	130	0110100101	180	0010011101
31	0101011001	81	0010011101	131	0101100101	181	0110011001
32	0101101001	82	0101100101	132	0010011101	182	0110101001
33	0010011101	83	0101100101	133	0110100101		
34	0101011001	84	0010011101	134	0110101001		
35	0101100101	85	0101100101	135	0010011101		
36	0010011101	86	0110101001	136	0110100101		
37	0101011001	87	0010011101	137	0110100101		
38	0110101001	88	0101100101	138	0010011101		
39	0010011101	89	0110100101	139	0110100101		
40	0101011001	90	0010011101	140	0110010101		
41	0110100101	91	0101100101	141	0010011101		
42	0010011101	92	0110010101	142	0110100101		
43	0101011001	93	0010011101	143	0110011001		
44	0110010101	94	0101100101	144	0010011101		
45	0010011101	95	0110011001	145	0110010101		
46	0101011001	96	0010011101	146	0101010101		
47	0110011001	97	0110101001	147	0010011101		
48	0010011101	98	0101010101	148	0110010101		
49	0101101001	99	0010011101	149	0101011001		

Table 15 – Bit stream of SSA for servo information F_1

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	0111001000	50	0101010111	100	1001010100	150	1000110111
1	1010101000	51	1000110111	101	1010100100	151	0110010111
2	1010101000	52	0101101011	102	0111001000	152	0101101001
3	0111001000	53	0101011001	103	0110101011	153	0111001000
4	0101010111	54	0111001000	104	0101101011	154	1001101000
5	0101011011	55	1010010100	105	1000110111	155	1010011000
6	1000110111	56	1010010100	106	0110101011	156	0111001000
7	0101010111	57	0111001000	107	0101100101	157	0110010111
8	0101101001	58	0101101011	108	0111001000	158	0110101011
9	0111001000	59	0101100111	109	1001010100	159	1000110111
10	1010101000	60	1000110111	110	1001010100	160	0110010111
11	1010011000	61	0101101011	111	0111001000	161	0110100101
12	0111001000	62	0110101001	112	0110101011	162	0111001000
13	0101010111	63	0111001000	113	0110100111	163	1001101000
14	0110101011	64	1010010100	114	1000110111	164	1001101000
15	1000110111	65	1001011000	115	0110101011	165	0111001000
16	0101010111	66	0111001000	116	0110010101	166	0110010111
17	0110100101	67	0101101011	117	0111001000	167	0110011011
18	0111001000	68	0110010111	118	1001010100	168	1000110111
19	1010101000	69	1000110111	119	1001100100	169	0110011011
20	1001101000	70	0101101011	120	0111001000	170	0101010101
21	0111001000	71	0110011001	121	0110100111	171	0111001000
22	0101010111	72	0111001000	122	0101010111	172	1001100100
23	0110011011	73	1010011000	123	1000110111	173	1010100100
24	1000110111	74	1010101000	124	0110100111	174	0111001000
25	0101011011	75	0111001000	125	0101011001	175	0110011011
26	0101010101	76	0101100111	126	0111001000	176	0101101011
27	0111001000	77	0101011011	127	1001011000	177	1000110111
28	1010100100	78	1000110111	128	1010010100	178	0110011011
29	1010100100	79	0101100111	129	0111001000	179	0101100101
30	0111001000	80	0101101001	130	0110100111	180	0111001000
31	0101011011	81	0111001000	131	0101100111	181	1001100100
32	0101101011	82	1010011000	132	1000110111	182	1001010100
33	1000110111	83	1010011000	133	0110100111		
34	0101011011	84	0111001000	134	0110101001		
35	0101100101	85	0101100111	135	0111001000		
36	0111001000	86	0110101011	136	1001011000		
37	1010100100	87	1000110111	137	1001011000		
38	1001010100	88	0101100111	138	0111001000		
39	0111001000	89	0110100101	139	0110100111		
40	0101011011	90	0111001000	140	0110010111		
41	0110100111	91	1010011000	141	1000110111		
42	1000110111	92	1001101000	142	0110100111		
43	0101011011	93	0111001000	143	0110011001		
44	0110010101	94	0101100111	144	0111001000		
45	0111001000	95	0110011011	145	1001101000		
46	1010100100	96	1000110111	146	1010101000		
47	1001100100	97	0110101011	147	0111001000		
48	0111001000	98	0101010101	148	0110010111		
49	0101101011	99	0111001000	149	0101011011		

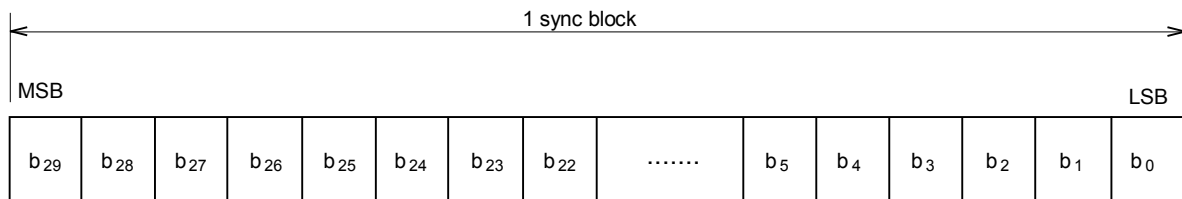
Table 16 – Bit stream of SSA for servo information F₂

Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB	Order of recording	Codeword MSB LSB
0	1000110111	50	1010101000	100	0110101011	150	1000110111
1	1010101000	51	0111001000	101	0101011011	151	1001101000
2	1010101000	52	0101101011	102	1000110111	152	1010010100
3	0111001000	53	0101011011	103	1001010100	153	0111001000
4	0101010111	54	1000110111	104	1010010100	154	0110010111
5	0101011011	55	1010010100	105	0111001000	155	0101100111
6	1000110111	56	1010010100	106	0110101011	156	1000110111
7	1010101000	57	0111001000	107	0101100111	157	1001101000
8	1010010100	58	0101101011	108	1000110111	158	1001010100
9	0111001000	59	0101100111	109	1001010100	159	0111001000
10	0101010111	60	1000110111	110	1001010100	160	0110010111
11	0101100111	61	1010010100	111	0111001000	161	0110100111
12	1000110111	62	1001010100	112	0110101011	162	1000110111
13	1010101000	63	0111001000	113	0110100111	163	1001101000
14	1001010100	64	0101101011	114	1000110111	164	1001101000
15	0111001000	65	0110100111	115	1001010100	165	0111001000
16	0101010111	66	1000110111	116	1001101000	166	0110010111
17	0110100111	67	1010010100	117	0111001000	167	0110011011
18	1000110111	68	1001101000	118	0110101011	168	1000110111
19	1010101000	69	0111001000	119	0110011011	169	1001100100
20	1001101000	70	0101101011	120	1000110111	170	1010101000
21	0111001000	71	0110011011	121	1001011000	171	0111001000
22	0101010111	72	1000110111	122	1010101000	172	0110011011
23	0110011011	73	1010011000	123	0111001000	173	0101011011
24	1000110111	74	1010101000	124	0110100111	174	1000110111
25	1010100100	75	0111001000	125	0101011011	175	1001100100
26	1010101000	76	0101100111	126	1000110111	176	1010010100
27	0111001000	77	0101011011	127	1001011000	177	0111001000
28	0101011011	78	1000110111	128	1010010100	178	0110011011
29	0101011011	79	1010011000	129	0111001000	179	0101100111
30	1000110111	80	1010010100	130	0110100111	180	1000110111
31	1010100100	81	0111001000	131	0101100111	181	1001100100
32	1010010100	82	0101100111	132	1000110111	182	1001010100
33	0111001000	83	0101100111	133	1001011000		
34	0101011011	84	1000110111	134	1001010100		
35	0101100111	85	1010011000	135	0111001000		
36	1000110111	86	1001010100	136	0110100111		
37	1010100100	87	0111001000	137	0110100111		
38	1001010100	88	0101100111	138	1000110111		
39	0111001000	89	0110100111	139	1001011000		
40	0101011011	90	1000110111	140	1001101000		
41	0110100111	91	1010011000	141	0111001000		
42	1000110111	92	1001101000	142	0110100111		
43	1010100100	93	0111001000	143	0110011011		
44	1001101000	94	0101100111	144	1000110111		
45	0111001000	95	0110011011	145	1001101000		
46	0101011011	96	1000110111	146	1010101000		
47	0110011011	97	1001010100	147	0111001000		
48	1000110111	98	1010101000	148	0110010111		
49	1010010100	99	0111001000	149	0101011011		

7.2.4 Track information area (TIA)

Track information area (TIA) consists of three sync blocks. Each sync block consists of 30 bits as shown in Figure 22. Every sync block has the same track information. Before the randomization, application ID of the track information shall be defined as in Table 17. The pilot frame shall be assigned as in Table 18.

Before the recording, the bit stream of the TIA shall be as defined in Tables 19 to 21 in accordance with the low frequency pilot signals. The length of the TIA shall be 90 bits as recorded on tape.



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Figure 22 – Structure of sync block of TIA

Table 17 – Application ID of track information

b ₁₇	b ₁₆	b ₁₅	b ₁₄	b ₁₃	b ₁₂	b ₇	b ₆	b ₅	b ₄	ID
APT ₂	APT ₂	APT ₁	APT ₁	APT ₀	APT ₀	TP ₁	TP ₁	TP ₀	TP ₀	
0	0	0	0	1	1	0	0	1	1	D-7 standard format
Others										Reserved

Table 18 – Pilot frame

	b ₃	b ₂
PF = 0	0	0
PF = 1	1	1