

Tomographic Particle Image Velocimetry for Flow Analysis in a Single Cylinder Optical Engine

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ABSTRACT

Better understanding of flow phenomena inside the combustion chamber of a diesel engine and accurate measurement of flow parameters is necessary for engine optimization i.e. enhancing power output, fuel economy improvement and emissions control. Airflow structures developed inside the engine combustion chamber significantly influence the air-fuel mixing. In this study, in-cylinder air flow characteristics of a motored, four-valve diesel engine were investigated using time-resolved high-speed Tomographic Particle Imaging Velocimetry (PIV). Single cylinder optical engine provides full optical access of combustion chamber through a transparent cylinder and flat transparent piston top. Experiments were performed in different vertical planes at different engine speeds during the intake and compression stroke under motoring condition. For visualization of air flow pattern, graphite particles were used for flow seeding. In the experiments, highly swirling air flow pattern was found, which was dominant in the vicinity of valves. Swirling patterns significantly affected by engine speed and increased at higher engine speed. The average structure of the flow field was analyzed, which showed a clear orientation of the average velocity, which changed during different phases of the cycle. Vorticity analysis showed higher vorticity beneath the intake valve that affects turbulence in air flow. Different components of velocity as V_x , V_y and V_z showed that engine speed and z-location affected all velocity components in which maximum variation takes place in Z-direction.

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INTRODUCTION

Airflow structures generated inside the cylinder of an internal combustion engines influence the fuel-air mixing significantly during compression stroke. Hence accurate measurement of these structures becomes very important to optimize the engine power output, fuel economy and emissions control. Several research groups carried out endoscopic optical diagnostics in IC engines however results obtained by these experiments were unable to explain air flow characteristics due to limited access [1, 2, 3]. Dierksheide et al. [1] performed PIV measurements using endoscope, CCD camera for image capturing and laser sheet for illumination.

Particle Image Velocimetry is a technique which is non-intrusive in nature and has been in practice for many years now and is being widely used for doing flow visualization of fluids. In this technique, the fluid flow is seeded with tracer particles and a laser sheet illuminates the tracer particles in the fluid flow. High speed cameras in double exposure mode are used to capture images of the seeded flow and instantaneous velocity fields are generated from the images captured using auto-correlation or cross-correlation techniques which provide data about the velocity and direction of flow in the area of interest [4, 5, 6, 7]. A lot of work has been performed for IC engine in-cylinder flow analysis more prominently in SI engines as compared to diesel engines. Basic objectives of these studies were to characterize velocity profile of air, turbulent characteristics of airflow

that affects air-fuel mixing. Several researchers have performed PIV experiments for characterization of turbulence properties, spatial flow structures and influences of cycle-to cycle variations [8, 9, 10, 11, 12, 13]. Bucker et al. [5] performed stereoscopic PIV for in-cylinder flow visualization. Reuss et al. [10] studied large scale turbulent structures in directed and undirected IC engine flows and their cyclic variability. Funk et al. [9] studied turbulence properties in high and low swirl in cylinder flows. But these findings were only able to resolve 2D planar Velocity. Muler et al. [13] studied flow field in a direct injection spray guided optical engine at 500, 1000 and 2000 rpm and analyzed the cycle to cycle variation. Researchers have varied several parameters and tried to optimize the PIV systems to get good and accurate results. They studied the effects of particle image diameter, interrogation region area, seeding density, in plane and out of plane particle movement, interrogation region pixel resolution [14, 15, 16, 17, 18, 19]. Reeves et al. [20] performed 2-D flow measurements in an optical SI engine for real time flow visualizations in horizontal and vertical planes. Voisine et al. [12] investigated air flow characteristics using two component PIV and analyzed spatial structure of flow and its temporal evolution. Stansfield et al. [21] carried out in cylinder 2-D PIV measurements at different engine speeds and also calculated tumble ratios from the obtained vector fields. They used two engine speeds and found significant change in air velocity flow structures. Calendini et al. [22] was the first to perform stereoscopic PIV to resolve three components of velocity in an IC engine. Dannemann et

al. [23] performed planar PIV experiments at different crank angle positions using motored condition. They measured flow field in eight axial planes and presented 3D velocity structures.

Although stereoscopic PIV was found capable for third velocity component in an engine but spatial derivatives and three dimensional flow structures have not much studied. Hence in-cylinder measurements of the instantaneous 3D flow field are the next level for better understanding of turbulent mixing of air and fuel inside the combustion chamber. There are several techniques have been developed for 3D imaging in which 3D particle tracking velocimetry (PTV), 3D light sheet scanning PIV, holographic PIV and Tomographic PIV (TPIV) are significantly adopted by researchers [24, 25, 26, 27]. 3D PTV technique is based on low seeding densities that results sparse vector fields and holographic PIV technique works on chemical processing of the photographic holographic plates.

Elsinga et al. [28] introduced TPIV method in which Tomographic reconstruction of the 3D particle distribution was performed by volumetric correlation of the reconstructed particle distribution. Baum et al. [29] used Tomographic particle image velocimetry (TPIV) within a motored direct-injection spark-ignition (DISI) optical engine to investigate the instantaneous volumetric flow field during intake and compression stroke. Tomographic PIV is a flow visualization technique which enables us to resolve all three components of velocity in a 3D measurement volume. The volume can be varied from very thin to thick volumes. MART Algorithm (Multiplicative Algebraic Reconstruction Technique) is used to do the construction and 3D cross correlation is done to return 3D velocity data in the measurement volume. Tomographic PIV technique is very relevant in IC Engines for instantaneous flow visualization where the air flow inside the cylinder is highly varying inside in volume.

Limitation in optical access, physical space surrounding the engine, thick curved glass cylinder and engine vibration causes major problems in 3D PIV. In the present investigation, single cylinder optical engine with quartz window was used for Tomographic PIV investigation. Two different engine speeds (1200 rpm and 2100 rpm), two piston positions (270°bTDC and 90°bTDC) in intake and compression stroke and five different Z locations were investigated for velocity, vorticity and different component of velocity as V_x , V_y and V_z .

EXPERIMENTAL SETUP AND METHODOLOGY

Schematic of single cylinder optical research engine equipped with PIV system is shown in [figure 1](#).

Experiments were conducted on a single cylinder optical research engine (AVL 5402) coupled with an AC dynamometer. Test engine is equipped with fuel conditioning, lubricating oil conditioning and coolant condition systems for conducting investigations at various engine operating conditions. For the current investigations, lubricating oil temperature and coolant temperature were kept constant (80°C and 60°C respectively) for the entire duration of experiments. Engine load and speed were controlled by AC

dynamometer (Wittur Electric Drives, 2SB 3). This dynamometer can motor the engine upto 3000 rpm. State-of-the-art intake air measurement system (ABB Automation, Sensy-flow P), gravimetric fuel flow meter (AVL, 733S.18) were used for performing engine tests. In-cylinder pressure was measured using a piezoelectric pressure transducer (AVL, QC34C) and charge amplifier along with a high speed combustion data acquisition and analysis system (AVL, Indismart) on a crank angle basis using a high precision shaft encoder (AVL, 365CC/ 365X). Maximum motoring pressure for optical head assembly is 34 bar. Technical specifications of the test engine are given in [table 1](#).

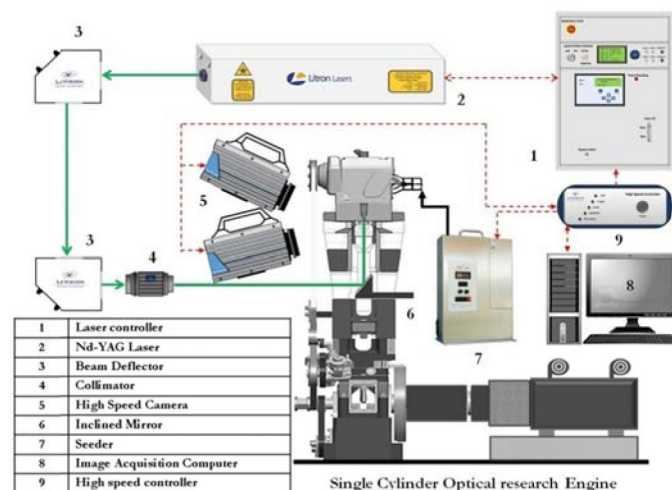


Figure 1. Schematic of SCORE with PIV

Table 1. Technical specifications of SCORE

Engine Type	AVL 5402
Number of cylinders	1
Bore/ stroke	85/ 90 mm
Swept volume	510.7 cc
Compression Ratio	17.5
Inlet port type	Tangential and Swirl Inlet Port
Maximum power	6 kW
Maximum Engine speed	2500 rpm
Fuel Injection Pressure	200-1400 bar
Fuel system	Common Rail Direct Injection
High Pressure System	Common Rail CP4.1 BOSCH
Engine Management System	AVL-RPEMS+ ETK7 (Bosch)
Valves per cylinder	4 (2 inlet, 2 exhaust)
Valve train type	DOHC cam follower
Liner type / base	Wet

For PIV experiments, optical head assembly of test engine was used. In this system, engine has a full length quartz liner and a sapphire window in the piston crown to provide full optical access of the combustion chamber. A high pressure air jet was supplied below extended piston for piston cooling. Constant 60°C coolant temperature was used to avoid thermal concentration in quartz window. PIV setup consisted of a double pulse Nd:YLF laser (Litron, LDY series Laser) with maximum output 150W was used as the light source for illumination for seeding particles. Two beam deflectors were used to direct the laser beam in the desired direction to a collimator. The collimator converts the laser beam into a light sheet which was deflected by a 45° inclined mirror which is fixed inside the extended piston. This piston has a sapphire window in the piston crown from where laser sheet enters inside the optical head assembly of engine. The quartz optical window provided optical

access to the combustion chamber. The laser sheet was aligned with the central axis of the cylinder in line with the fuel injector. Two high speed CCD cameras (LaVision, 1024×1024 pixels, 12 bits) having schiempflug adapters were used in double frame mode (Frame rate 2500 Hz) to capture the images. For the visualization of flow pattern, intake air was seeded with graphite particles at 2.5 bar pressure using solid particle disperser (Palas, RBG 1000). For the experiments, calibration was performed in the centre plane along the central axis of combustion chamber where the laser sheet was aligned just beneath the injector. A rectangular two level 3-D calibration plate and polynomial calibration model was used to perform the calibration.

Davis 8.2 software (LaVision) was used to perform the Tomographic processing of the images. As a part of pre-processing of the images, 5×5 sliding minimum was subtracted from the images to get a constant background across the images. For smoothening of vector field, Gaussian smoothing of 3×3 pixels was applied during analysis. Geometric mask was used to select the desired area in the captured images. The volume reconstruction of the images was done using Fast MART (Multiplicative Algebraic Reconstruction Technique). Direct correlation was done for volume correlation with four window sizes, first being 128 voxel with 75% overlap and other 3 being 64 voxels with 75% overlap with decreasing volume binning for each step. This was followed by vector post-processing in which universal outlier detection was done to remove spurious vectors. A Gaussian smoothing of 3×3×3 and a second order polynomial filter was applied during post processing to the vector fields. Practical experimental setup used for PIV experiments is shown in [figure 2](#).

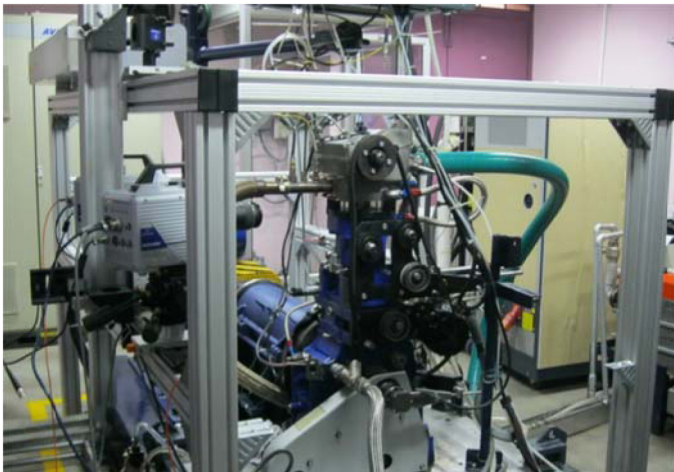


Figure 2. Practical setup of SCORE with PIV

RESULT AND DISCUSSIONS

In this research, Tomographic PIV was performed for $Z = 9$ mm and results are represented for $Z = 1$ mm, 3 mm, 5 mm, 7 mm and 9 mm (5 different z positions). $Z = 5$ mm being the centre plane along the central axis beneath the fuel injector. $Z = 1$ mm and $Z = 3$ mm being near the intake valve and $Z = 7$ mm and $Z = 9$ mm being near the exhaust valve. To investigate the air flow characteristics, engine was

motored at two different engine speeds as 1200 and 2100 rpm. For analysis, two different piston positions as 270° bTDC and 90° bTDC were selected during intake and compression stroke respectively. For the experiments a volume of 48×28×9 mm³ was chosen for image analysis as shown in [figure 3](#).

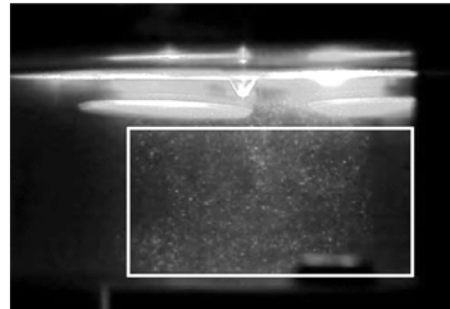


Figure 3. Area of interest for image analysis

For PIV experiments, calibration was performed through the optical window in order to take into account the optical distortions due to window curvature during the PIV imaging. Piston crown window diameter was 48mm, compared to 85mm bore diameter and the light sheet passing through the window was not sufficient to illuminate entire width of the combustion chamber. Enlargement of the piston crown window is required for the investigation of flows near the combustion chamber wall. Image noise due to flares caused by film fogging also prevented measurements close to the combustion chamber walls. Appropriate camera focusing and optical corrections help reduce laser pulse energy, which illuminates the seed particles. For pulse energies below 75 mJ, scattered light level in the camera image plane was found to vary directly proportional to the illuminating laser pulse energy however for higher laser pulse energies, flare increased at a greater rate.

Velocity Analysis

Velocity profiles at two engine speeds as 1200 and 2100 rpm were analysed at different Z locations and compared. Significant changes in flow pattern was observed in velocity profile along with variations in velocity for both engine speeds. For better understanding of the the velocity profile, streamlines were also drawn during image analysis. During the intake stroke (270° bTDC), velocity profile is shown in [figure 4](#) for 1200 and 2100 rpm at $Z = 3$ mm and 7mm. Tumble motion can be seen in [Figure 4\(a\)](#) due to circulation of air due to reverse motion of air from the piston after it strikes the piston. In [figure 4\(b\)](#), a stagnation point is observed at $x = 23$ mm, $y = -1$ mm. At this point air from the inlet valves and piston meet and a point of convergence arises. At 1200 rpm, the velocity range in the considered area of interest ranges from 0-14.5 m/s. Similarly, at 2100 rpm, stagnation points were observed in both cases (Z locations). Tumble motion is also observed in case of 2100 rpm which is relatively stronger near the piston. Sudden change in the direction of air motion is the main reason for this finding. The velocity range at 2100 rpm is found 0-19 m/s which is comparatively higher compared to 1200 rpm due to higher engine speed.