

A Study into Compression Ring Dynamics using Response Surface Methodology

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ABSTRACT

For decades the operational dynamics of the compression ring during operation, have been subject to debate [1, 2, 3, 4, 5, 6, 7]. A complex computer simulation, using Design Of Experiments (DOE) methodology, was developed to study the effect of the compression ring rotation during running-in stages. Response Surface (RS) has been used to optimize ring displacement, as function of ring mass, width and radius. The optimised surface response has been compared to used compression rings and has shown a 2% variation between calculated and measured values.

CITATION: Dickinson, M., Renevier, N., and Calderbank, J., "A Study into Compression Ring Dynamics using Response Surface Methodology," *SAE Int. J. Passeng. Cars - Mech. Syst.* 8(1):2015, doi:10.4271/2015-01-1335.

INTRODUCTION

For almost two century's since the introduction of the split ring, there has been a considerable interest in the mechanics and dynamics of the piston rings in the combustion conditions [8, 9, 10, 11, 12]. The four stroke engine that has been used for this study is a KTM 520. As this engine is a motorcycle engine this means, a high level of RPM can be obtained, this makes this an ideal selection for race condition research. To simulate the environment of running-in conditions the recommended running-in operational speed has been selected of 7,000 rpm [13]. This paper presents simulation results from MatLab to display how the compression ring behaviours. In this work the ideal gas was used, a thermal and dynamic analysis was performed to enable an accurate behaviour representation. 3 sample sets of KTM BS-grade compression rings with MoS2 coatings were analysed after 60mins of operation. Each ring was checked using a Quanta FEI Scanning Electron Microscope (SEM). Each image was cross analysed using open source software Gwyddion.

SYSTEM

The KTM 520 engine dimensions and material features have been reported in Table 1.

Table 1. showing component details

Dimension [mm]	Component	Material
95	Compression ring	BS-Grade 400 grey
94.95	Piston	4032-T6 alloy
95	Cylinder	Nikasil
115	Connecting Rod	UNS C67400
31	Crank	EN-30B Alloy Steel

To calculate pressure and displacement of the piston during operation, equations noted by Stone were used [11]. Further modelling methods were used from work noted by Dickinson [4].

To reduce the number of simulations, a centre composite, 3 factorial RS has been used to optimise the compression ring displacement. Factors such as radius, cross sectional width and the ring overall mass were studied.

Table 2. Factors for RS

Ring Width mm	Ring Rad mm	Ring Mass g
1 - 5	30 - 50	0.2 - 1.2

Table 2 shows the factors used in the RS. This produced a surface based on 20 runs, generating the RS graph.

Surface Plot of RunOrder vs Ring Rad, Ring Width

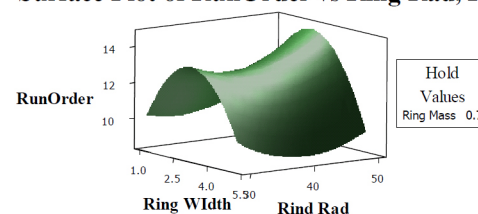


Figure 1. RS plot

Figure 1 shows the RS plot defined through the factorial set-up.

The defined variables are introduced into a Matlab/SimMechanics model. Each engine component is reengineered and defined within the SimMechanics system. The system is a G-Graphical interface to keep the system organised, where each major components are created with their own sub program (Figure 2).

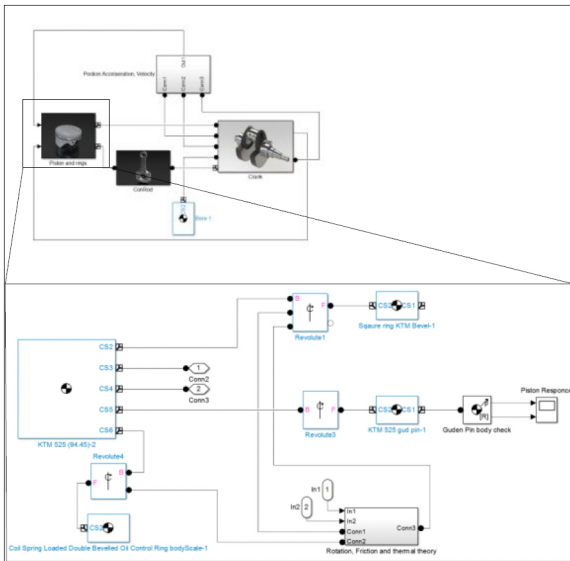


Figure 2. MatLab/SimMechanics model

Figure 2 shows the SimMechanics model used. The methodology used has been previously described [2, 3, 4].

To validate the simulation results, SEM images were taken of the top face of the compression ring to examine for scratches on the surface that would indicate ring rotation.

The displacement angle indicating ring displacement has been calculated using:

$$x = \tan^{-1} \left(\frac{L}{R_{rad}} \right) \quad (1)$$

$$R_{rad} = R - D \quad (2)$$

Where L is the length of the measured scratch, R is the piston ring radius, D is the SEM observed image position from the outer radius of the ring.

RESULTS

Post processing of the data generated by the RS DOE shows a good correlation in the running order, as seen in Figure 3.

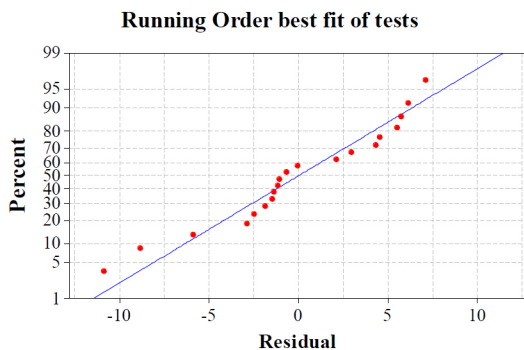


Figure 3. running order results best fit

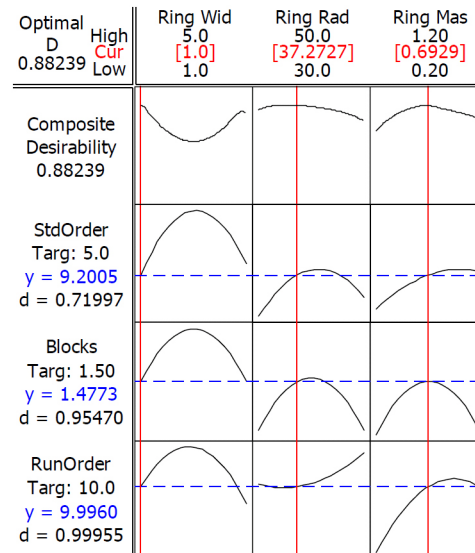


Figure 4. Running order of the optimised solution

The running order of the optimised solution (Table 3) is presented in Figure 4.

Table 3. Optimised solution

Ring Width (RW) mm	Ring Rad (RR) mm	Ring Mass (RM) g
1	37.27	0.69239

Each goal for the StdOrder = 5, Blocks = 1.5 and Runorder = 10. The composite desirability is 0.88239.

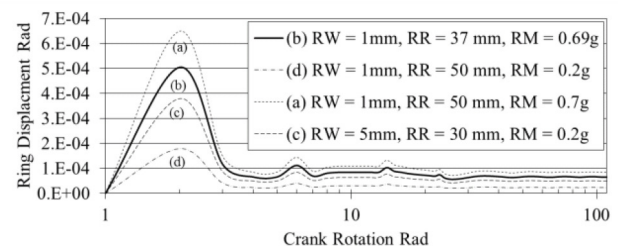


Figure 5. Ring displacement radius (b)

Figure 5 shows four representatives RS ring displacement radius outputs. Large oscillations are found below 10 radians of the crank rotation, with the factors defined, a second order system behaviour is seen. For the optimised solution (Table 3), the ring will rotate by a maximum of 0.005 rads. The result also indicates a resting time reached after 50 rads.

Figure 6 shows one of three samples images taken with SEM of the run-in KTM piston rings. Each image was measured for the maximum arc size relative to the ring radius.